

## THE NEW $\nu$ -METRIC INDUCES THE CLASSICAL GAP TOPOLOGY

AMOL SASANE

*Abstract.* Let  $\mathcal{A}_+$  denote the set of Laplace transforms of complex Borel measures  $\mu$  on  $[0, +\infty)$  such that  $\mu$  does not have a singular non-atomic part. In [1], an extension of the classical  $\nu$ -metric of Vinnicombe was given, which allowed one to address robust stabilization problems for unstable plants over  $\mathcal{A}_+$ . In this article, we show that this new  $\nu$ -metric gives a topology on unstable plants which coincides with the classical gap topology for unstable plants over  $\mathcal{A}_+$  with a single input and a single output.

*Mathematics subject classification (2010):* Primary 93B36; Secondary 93D15, 46J15.

*Keywords and phrases:*  $\nu$ -metric, robust control, Banach algebras.

### REFERENCES

- [1] J. A. BALL AND A. J. SASANE, *Extension of the  $\nu$ -metric*, Complex Analysis and Operator Theory, to appear.
- [2] A. BRUDNYI AND A. J. SASANE, *Sufficient conditions for the projective freeness of Banach algebras*, Journal of Functional Analysis, in press.
- [3] A. BÖTTCHER AND B. SILBERMANN, *Analysis of Toeplitz operators*, Springer-Verlag, Berlin, 1990.
- [4] R. G. DOUGLAS, *On the  $C^*$ -algebra of a one-parameter semigroup of isometries*, Acta Mathematica **128**, 3–4 (1972), 143–151.
- [5] R. G. DOUGLAS, *Banach algebra techniques in the theory of Toeplitz operators*, Conference Board of the Mathematical Sciences Regional Conference Series in Mathematics, No. 15. American Mathematical Society, Providence, R.I., 1973.
- [6] A. K. EL-SAKKARY, *The gap metric: robustness of stabilization of feedback systems*, IEEE Transactions on Automatic Control **30**, 3 (1985), 240–247.
- [7] T. T. GEORGIU, *On the computation of the gap metric*, Systems Control Letters **11**, 4 (1988), 253–257.
- [8] T. T. GEORGIU AND M. C. SMITH, *Optimal robustness in the gap metric*, IEEE Transactions on Automatic Control **35**, 6 (1990), 673–686.
- [9] B. JESSEN AND H. TORNEHAVE, *Mean motions and zeros of almost periodic functions*, Acta Mathematica **77** (1945), 137–279.
- [10] K. M. MIKKOLA, *Infinite-dimensional linear systems, optimal control and algebraic Riccati equations*, Doctoral dissertation, Technical Report A452, Institute of Mathematics, Helsinki University of Technology, 2002.
- [11] N. K. NIKOLSKI, *Treatise on the shift operator*, Spectral function theory. With an appendix by S.V. Khrushchëv and V. V. Peller. Grundlehren der Mathematischen Wissenschaften 273, Springer-Verlag, Berlin, 1986.
- [12] N. K. NIKOLSKI, *Operators, functions, and systems: an easy reading. Volume 1*. Mathematical Surveys and Monographs, 92. American Mathematical Society, Providence, RI, 2002.
- [13] J. R. PARTINGTON, *Linear operators and linear systems. An analytical approach to control theory*, London Mathematical Society Student Texts 60, Cambridge University Press, Cambridge, 2004.
- [14] M. VIDYASAGAR, *The graph metric for unstable plants and robustness estimates for feedback stability*, IEEE Transactions on Automatic Control **29**, 5 (1984), 403–418.
- [15] G. VINNICOMBE, *Frequency domain uncertainty and the graph topology*, IEEE Transactions on Automatic Control **38**, 9 (1993), 1371–1383.

- [16] G. ZAMES AND A. K. EL-SAKKARY, *Unstable systems and feedback: The gap metric*, In Proceedings of the Allerton Conference, 380–385, Oct. 1980.