

WHEN DOES THE MOORE–PENROSE INVERSE FLIP?

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Abstract. In this paper, we give necessary and sufficient conditions for the matrix $\begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$, over a $*$ -regular ring, to have a Moore-Penrose inverse of four different types, corresponding to the four cases where the zero element can stand. In particular, we study the case where the Moore-Penrose inverse of the matrix flips.

1. Introduction

Let R be a regular $*$ -ring with 1, that is, for all $a \in R$ there exist a^- such that $aa^-a = a$, and with an involutory anti-isomorphism $(\cdot)^*$ on R , such that $(a^*)^* = a$, $(a+b)^* = a^* + b^*$ and $(ab)^* = b^*a^*$.

It is well known [9, Lemma 4], that if the involution on R satisfies the one term *star-cancellation law*

$$SC_1 : a^*a = 0 \Rightarrow a = 0, \tag{1}$$

then the Moore-Penrose inverse a^\dagger can be defined. It is the unique solution to the four equations

$$(i) \ axa = a, \quad (ii) \ xax = x, \quad (iii) \ (ax)^* = ax, \quad (iv) \ (xa)^* = xa. \tag{2}$$

We say x is a 1-3 inverse of a if it satisfies equations (i) and (iii) above, and y is a 1-4 inverse of a if it satisfies equations (i) and (iv) above. From the well known result due to Urquhart (cf. [1, page 48]), if x and y are a 1-3 and 1-4 inverse of a , respectively, then $a^\dagger = yax$.

We note that regular rings that satisfy SC_1 are exactly those for which all of its elements are Moore-Penrose invertible. Such a ring is said to be a $*$ -regular ring. We use $R_{2 \times 2}$ to denote the ring of 2×2 matrices over R .

A matrix $M = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$ with coefficients in R is said to be of $(i, j, 0)$ type if the (i, j) entry $(M)_{ij}$ of M is zero.

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In this note we will be interested in the questions of when the matrix $\begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$ has a Moore-Penrose inverse of $(i, j, 0)$ type, for $i, j \in \{1, 2\}$. In particular, we will address to the case when this inverse has the “flipped” form $\begin{bmatrix} * & * \\ 0 & * \end{bmatrix}$. We will repeatedly use Cline’s results ([3] and [4]) in order to express the Moore-Penrose inverse of a semi-orthogonal sum and of a column matrix. The expressions derived are simpler when compared with [7].

We only consider the special involution on $R_{2 \times 2}$ of the form $\begin{bmatrix} a & c \\ b & d \end{bmatrix}^* = \begin{bmatrix} a^* & b^* \\ c^* & d^* \end{bmatrix}$.

2. Existence of the Moore-Penrose inverse

Consider the matrix $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$. In order to guarantee the existence and to be able to give a formula of M^\dagger , we assume the following extra conditions on the regular R :

1. $SC_2 : a^*a + b^*b = 0 \Rightarrow a = 0 = b$ (two term star-cancellation)
2. for each $a \in R$, there is $c \in R$ such that $1 + a^*a = c^*c = cc^*$ (square root axiom)

We note the following consequences:

- (i) $1 + a^*a$ is a unit for all $a \in R$, that is, R has the symmetry property (see [2, page 9]). Indeed, if R is regular and satisfies SC_2 then it also satisfies SC_1 , which in turn implies all its elements are Moore-Penrose invertible. Let $u = 1 + a^*a$. If $ux = 0$, then $x^*x + (ax)^*(ax) = 0$ and hence, using condition SC_2 , $x = 0$. Thus u is not a divisor of 0. But $u(1 - u^\dagger u) = 0$ and hence $1 - u^\dagger u = 0$. Likewise $1 - uu^\dagger = 0$ and u is a unit.
- (ii) Since $1 + a^*a = cc^* = c^*c$ is a unit, then the square root c must be a unit as well.
- (iii) $1 + a^*a + b^*b = c^*c + b^*b = c^*[1 + (bc^{-1})^*(bc^{-1})]c$, which is again a unit.
- (iv) If R satisfies SC_2 and is regular, then every 2×2 matrix over R is Moore-Penrose invertible. This follows from the facts that
 - (a) SC_2 holds in R if and only if SC_1 holds in $R_{2 \times 2}$.
 - (b) R is regular if and only if the ring $R_{2 \times 2}$ is regular.
- (v) The previous item shows that the regularity of the involutory ring R together with SC_2 is sufficient to guarantee the existence of A^\dagger , for any 2×2 matrix A over R , with respect to the special involution in $R_{2 \times 2}$ induced by the involution on R . In the remainder of this paper we will give an expression for the Moore-Penrose inverse of a 2×2 matrix over R , and for this we will need the symmetry of $R_{2 \times 2}$.

We note that symmetry of $R_{2 \times 2}$ does not follow from R being regular and satisfying SC_2 . Indeed, set $R = \mathbb{Z}_7$ which is a field and thus regular. The involution we take is the identity map. The squares are $\{0, 1, 2, 4\}$. It is clear that $x^2 + y^2 = 0 \Rightarrow x = 0 = y$. That is, SC_2 holds. Now, let $M = \begin{bmatrix} 2 & 0 \\ 3 & 0 \end{bmatrix}$. Then $M^*M = M^T M = \begin{bmatrix} 2 & 3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 2 & 0 \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 6 & 0 \\ 0 & 0 \end{bmatrix}$. Hence $I_2 + M^*M = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$, which is not invertible.

- (vi) In a regular symmetric ring, idempotents e have a Moore-Penrose inverse via $e^\dagger = e^*[1 + (e - e^*)(e^* - e)]^{-1}$. Indeed, setting $u = 1 + (e - e^*)(e^* - e)$, then u and ee^* commute, and so do u^{-1} and ee^* , u and e^*e commute, and so do u^{-1} and e^*e , and also $u^{-1}ee^*ee = e = ee^*eu^{-1}$. Since $e(e^*u^{-1})$ and $(u^{-1}e^*)e$ are symmetric, and $e(e^*u^{-1})e = u^{-1}ee^*e = e = ee^*eu^{-1} = e(u^{-1}e^*)e$, then e^*u^{-1} is a 1-3 inverse of e and $u^{-1}e^*$ is a 1-4 inverse of e , which lead to $e^\dagger = (u^{-1}e^*)e(e^*u^{-1}) = u^{-1}e^*ee^*u^{-1} = e^*u^{-1}$.

As such the orthogonal projections P_{aR} and P_{Ra} can be defined as $p = (aa^-)(aa^-)^\dagger$ and $q = (a^-a)^\dagger(a^-a)$. It then follows that the Moore-Penrose inverse $a^\dagger = qa^-p$ exists and the SC_1 property follows.

2.1. The Moore-Penrose inverse of a sum

We recall that if $ca^* = 0$, then $a + c$ has a Moore-Penrose inverse, which takes the form

$$(a + c)^\dagger = (1 + y^*)(1 + yy^*)^{-1}s + u^\dagger, \tag{3}$$

where

$$\begin{aligned} u &= (1 - aa^\dagger)c \\ s &= a^\dagger(1 - cu^\dagger) \\ y &= a^\dagger c(1 - u^\dagger u) = sc. \end{aligned}$$

Indeed, and since $1 - y^*y(1 + y^*y)^{-1} = (1 + y^*y)^{-1}$, $(1 + y^*y)^{-1}$ and $1 - u^\dagger u$ commute, $y(1 - u^\dagger u) = y$, and $(1 + yy^*)^{-1} = 1 - y(1 + y^*y)^{-1}y^*$, then, using [4, Theorem 2],

$$\begin{aligned} (a + c)^\dagger &= a^\dagger - a^\dagger cu^\dagger - a^\dagger c(1 - u^\dagger u)(1 + y^*y)^{-1}c^*a^{\dagger*}a^\dagger(1 - cu^\dagger) + u^\dagger + \\ &\quad + (1 - u^\dagger u)(1 + y^*y)^{-1}c^*a^{\dagger*}a^\dagger(1 - cu^\dagger) \\ &= s - y(1 + y^*y)^{-1}c^*a^{\dagger*}s + u^\dagger + (1 - u^\dagger u)(1 + y^*y)^{-1}c^*a^{\dagger*}s \\ &= s - y(1 + y^*y)^{-1}(1 - u^\dagger u)c^*a^{\dagger*}s + u^\dagger + (1 - u^\dagger u)(1 - y^*y(1 + y^*y)^{-1})c^*a^{\dagger*}s \\ &= s - y(1 + y^*y)^{-1}y^*s + u^\dagger + y^*s + y^*y(1 + y^*y)^{-1}c^*a^{\dagger*}s \\ &= u^\dagger + (1 - y(1 + y^*y)^{-1}y^*)s + y^*(1 - y(1 + y^*y)^{-1}y^*)s \\ &= u^\dagger + (1 + yy^*)^{-1}s + y^*(1 + yy^*)^{-1}s \\ &= (1 + y^*)(1 + yy^*)^{-1}s + u^\dagger \end{aligned}$$

Moreover, we also have, from [3, Theorem 2] (also from [7, Lemma 2]),

$$\begin{bmatrix} a \\ b \end{bmatrix}^\dagger = [\xi a^*, \xi b^*] \text{ and } \begin{bmatrix} a \\ b \end{bmatrix}^\dagger \begin{bmatrix} a \\ b \end{bmatrix} = a^\dagger a + v^\dagger v, \tag{4}$$

where $\xi = (a^*a + b^*b)^\dagger$ and $v = b(1 - a^\dagger a)$. We may re-express the former element as

$$\xi = t\mu^{-1}t^* + (v^*v)^\dagger, \tag{5}$$

in which

$$t = (1 - v^\dagger b)a^\dagger, \quad x = (1 - vv^\dagger)ba^\dagger = bt, \quad \mu = 1 + x^*x. \tag{6}$$

Indeed, from [4, Theorem 1],

$$\xi = (a^*a + b^*b)^\dagger = t\ell t^* + v^\dagger(v^*)^\dagger,$$

where

$$\ell = 1 - ((1 - vv^\dagger)ba^\dagger)^*k(ba^\dagger)$$

and

$$k = (1 + (1 - vv^\dagger)ba^\dagger((1 - vv^\dagger)ba^\dagger)^*)^{-1} = (1 + xx^*)^{-1}.$$

Since $(1 - vv^\dagger)k = k(1 - vv^\dagger) = (1 - vv^\dagger)k(1 - vv^\dagger)$,

$$\begin{aligned} \ell &= 1 - (ba^\dagger)^*(1 - vv^\dagger)k(1 - vv^\dagger)ba^\dagger \\ &= 1 - ((1 - vv^\dagger)ba^\dagger)^*k(1 - vv^\dagger)ba^\dagger \\ &= 1 - x^*(1 + xx^*)^{-1}x \\ &= (1 + x^*x)^{-1} = \mu^{-1} \end{aligned}$$

Lastly, $v^\dagger(v^*)^\dagger = (v^*v)^\dagger$ by [5, Lemma 5], or simply by checking the Penrose equations (2).

2.2. The lower triangular case

Consider the 2×2 triangular matrix $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$. We may split M as

$$M = \begin{bmatrix} 0 & 0 \\ 0 & d \end{bmatrix} + \begin{bmatrix} a & 0 \\ b & 0 \end{bmatrix} = \mathcal{A} + \mathcal{C},$$

where $\mathcal{C}\mathcal{A}^* = 0$. In order to apply (3) to this semi-orthogonal splitting, we need to show that $I + A^*A$ is invertible for any matrix $A \in R_{2 \times 2}$. This we now undertake.

The key fact is the following factorization. If α is a unit then

$$\begin{bmatrix} \alpha & \beta^* \\ \beta & \delta \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ \beta\alpha^{-1} & 1 \end{bmatrix} \begin{bmatrix} \alpha & 0 \\ 0 & z \end{bmatrix} \begin{bmatrix} 1 & \alpha^{-1}\beta^* \\ 0 & 1 \end{bmatrix}, \tag{7}$$

where z is the Schur complement $z = \delta - \beta\alpha^{-1}\beta^*$. Now consider the matrix $A = [\mathbf{a}, \mathbf{b}] = \begin{bmatrix} a_1 & b_1 \\ a_2 & b_2 \end{bmatrix}$. Then

$$I + A^*A = \begin{bmatrix} 1 + \mathbf{a}^*\mathbf{a} & \mathbf{a}^*\mathbf{b} \\ \mathbf{b}^*\mathbf{a} & 1 + \mathbf{b}^*\mathbf{b} \end{bmatrix}. \quad (8)$$

and its Schur complement becomes

$$\begin{aligned} z &= 1 + \mathbf{b}^*\mathbf{b} - (\mathbf{b}^*\mathbf{a})(1 + \mathbf{a}^*\mathbf{a})^{-1}\mathbf{a}^*\mathbf{b} \\ &= 1 + \mathbf{b}^*[I_2 - \mathbf{a}(1 + \mathbf{a}^*\mathbf{a})^{-1}\mathbf{a}^*]\mathbf{b} \\ &= 1 + \mathbf{b}^*[I_2 + \mathbf{a}\mathbf{a}^*]^{-1}\mathbf{b}, \end{aligned}$$

since $(I_2 + \mathbf{a}\mathbf{a}^*)^{-1} = I_2 - \mathbf{a}(1 + \mathbf{a}^*\mathbf{a})^{-1}\mathbf{a}^*$.

We now turn to the matrix

$$\begin{aligned} G &= I + \mathbf{a}\mathbf{a}^* \\ &= \begin{bmatrix} 1 + a_1a_1^* & a_1a_2^* \\ a_2a_1^* & 1 + a_2a_2^* \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ \beta\alpha^{-1} & 1 \end{bmatrix} \begin{bmatrix} \alpha & 0 \\ 0 & \zeta \end{bmatrix} \begin{bmatrix} 1 & \alpha^{-1}\beta^* \\ 0 & 1 \end{bmatrix}, \end{aligned}$$

where $\alpha = 1 + a_1a_1^*$ is a unit, $\beta = a_2a_1^*$ and the Schur complement ζ takes the form

$$\begin{aligned} \zeta &= 1 + a_2a_2^* - a_2a_1^*(1 + a_1a_1^*)^{-1}a_1a_2^* \\ &= 1 + a_2(1 - a_1^*(1 + a_1a_1^*)^{-1}a_1)a_2^* \\ &= 1 + a_2(1 + a_1^*a_1)^{-1}a_2^*, \end{aligned}$$

since $(1 + a_1^*a_1)^{-1} = 1 - a_1^*(1 + a_1a_1^*)^{-1}a_1$.

By using the square root axiom, we may set $1 + a_1a_1^* = ee^*$ and therefore e is a unit. Consequently, there exists f such that $(1 + a_1a_1^*)^{-1} = ff^*$ and hence $\zeta = 1 + (a_2f)(a_2f)^*$. Again ζ is a unit, and by the square root axiom, $\zeta = hh^*$, which leads to $\zeta^{-1} = gg^*$, for some g .

Substituting into z now gives

$$\begin{aligned} z &= 1 + \mathbf{b}^*(I + \mathbf{a}\mathbf{a}^*)^{-1}\mathbf{b} \\ &= 1 + \mathbf{b}^* \begin{bmatrix} 1 - \alpha^{-1}\beta^* \\ 0 & 1 \end{bmatrix} \begin{bmatrix} \alpha^{-1} & 0 \\ 0 & \zeta^{-1} \end{bmatrix} \begin{bmatrix} 1 & 0 \\ -\beta\alpha^{-1} & 1 \end{bmatrix} \mathbf{b} \\ &= 1 + \begin{bmatrix} b_1^* & w^* \end{bmatrix} \begin{bmatrix} ff^* & 0 \\ 0 & gg^* \end{bmatrix} \begin{bmatrix} b_1 \\ w \end{bmatrix} \\ &= 1 + b_1^*ff^*b_1 + w^*gg^*w, \end{aligned}$$

where $w = b_2 - \beta\alpha^{-1}b_1$, and therefore z is a unit. Thus $R_{2 \times 2}$ is again symmetric.

We now may apply (3) to our matrix M , giving

$$M^\dagger = \mathcal{U}^\dagger + (I + \mathcal{Y}^*)(I + \mathcal{Y}\mathcal{Y}^*)^{-1}S, \tag{9}$$

where

$$\mathcal{U} = (I - \mathcal{A}\mathcal{A}^\dagger)\mathcal{C} = \begin{bmatrix} a & 0 \\ B & 0 \end{bmatrix},$$

with $B = (1 - dd^\dagger)b$, and

$$\mathcal{Y} = \mathcal{A}^\dagger\mathcal{C}(I - \mathcal{U}^\dagger\mathcal{U}).$$

We next compute $\mathcal{U}^\dagger = \begin{bmatrix} \xi a^* & \xi B^* \\ 0 & 0 \end{bmatrix}$ in which

$$\begin{aligned} \xi &= (a^*a + B^*B)^\dagger = t\mu^{-1}t^* + (v^*v)^\dagger, \\ v &= B(1 - a^\dagger a), \quad t = (1 - v^\dagger B)a^\dagger, \\ \mu &= I + x^*x, \quad \text{and} \\ x &= (I - vv^\dagger)Ba^\dagger = Bt. \end{aligned}$$

By combining these, and by using the equalities in (4), we arrive at

$$\mathcal{U}^\dagger\mathcal{U} = \begin{bmatrix} a^\dagger a + v^\dagger v & 0 \\ 0 & 0 \end{bmatrix}$$

and

$$\mathcal{Y} = \begin{bmatrix} 0 & 0 \\ 0 & d^\dagger \end{bmatrix} \begin{bmatrix} a & 0 \\ b & 0 \end{bmatrix} \begin{bmatrix} 1 - a^\dagger a - v^\dagger v & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ f & 0 \end{bmatrix},$$

where

$$f = d^\dagger b(1 - a^\dagger a - v^\dagger v).$$

Likewise,

$$\begin{aligned} \mathcal{S} &= \mathcal{A}^\dagger - \mathcal{A}^\dagger\mathcal{C}\mathcal{U}^\dagger \\ &= \begin{bmatrix} 0 & 0 \\ 0 & d^\dagger \end{bmatrix} - \begin{bmatrix} 0 & 0 \\ 0 & d^\dagger \end{bmatrix} \begin{bmatrix} a & 0 \\ b & 0 \end{bmatrix} \begin{bmatrix} \xi a^* & \xi B^* \\ 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ -d^\dagger b \xi a^* & d^\dagger - d^\dagger b \xi B^* \end{bmatrix}. \end{aligned}$$

We then compute

$$(I + \mathcal{Y}^*)(I + \mathcal{Y}\mathcal{Y}^*)^{-1} = \begin{bmatrix} 1 & f^*(1 + ff^*)^{-1} \\ 0 & (1 + ff^*)^{-1} \end{bmatrix},$$

followed by

$$(I + \mathcal{Y}^*)(I + \mathcal{Y}\mathcal{Y}^*)^{-1}\mathcal{S} = \begin{bmatrix} 1 & f^*(1 + ff^*)^{-1} \\ 0 & (1 + ff^*)^{-1} \end{bmatrix} \begin{bmatrix} 0 & 0 \\ -d^\dagger b \xi a^* & d^\dagger - d^\dagger b \xi B^* \end{bmatrix}.$$

This then gives, using equation (9),

$$\begin{bmatrix} a & 0 \\ b & d \end{bmatrix}^\dagger = (I + \mathcal{Y}^*)(I + \mathcal{Y}\mathcal{Y}^*)^{-1}\mathcal{S} + \mathcal{W}^\dagger = \begin{bmatrix} p & q \\ s & r \end{bmatrix}, \quad (10)$$

where

$$p = \xi a^* - (1 + f^*f)^{-1}f^*d^\dagger b\xi a^* \quad (11)$$

$$s = -(1 + ff^*)^{-1}d^\dagger b\xi a^* \quad (12)$$

$$q = \xi b^*(1 - dd^\dagger) + (1 + f^*f)^{-1}f^*d^\dagger[1 - b\xi b^*(1 - dd^\dagger)] \quad (13)$$

$$r = (1 + ff^*)^{-1}d^\dagger[1 - b\xi b^*(1 - dd^\dagger)] \quad (14)$$

in which

$$\xi = [a^*a + b^*(1 - dd^\dagger)b]^\dagger = \xi^* = t(1 + x^*x)^{-1}t^* + (v^*v)^\dagger \quad (15)$$

$$x = (1 - vv^\dagger)(1 - dd^\dagger)ba^\dagger \quad (16)$$

$$t = [1 - v^\dagger(1 - dd^\dagger)b]a^\dagger \quad (17)$$

$$f = d^\dagger b(1 - a^\dagger a - v^\dagger v) \text{ and} \quad (18)$$

$$v = (1 - dd^\dagger)b(1 - a^\dagger a) \text{ (corner stone).} \quad (19)$$

We have presented an alternative expression to main theorem of [7] for the Moore-Penrose inverse of a 2×2 lower triangular matrix.

For later use, we observe that

- (a) $va^* = 0$, $(v^*v)^\dagger a^* = 0$.
- (b) $\xi a^* = t\mu^{-1}t^*a^*$, where $\mu = 1 + x^*x$.
- (c) $t = [1 - v^\dagger(1 - dd^\dagger)b]a^\dagger = (1 - v^\dagger b)a^\dagger = a^\dagger - v^\dagger ba^\dagger$.
- (d) $taa^\dagger = t$ and $at = aa^\dagger - av^\dagger ba^\dagger = aa^\dagger = (at)^*$
- (e) $xaa^\dagger = x$ and so $aa^\dagger x^* = x^*$, and
- (f) $\mu aa^\dagger = aa^\dagger \mu$ and $\mu^{-1}aa^\dagger = aa^\dagger \mu^{-1}$.

From the above,

$$\xi a^* = t\mu^{-1}(at)^* = t\mu^{-1}aa^\dagger = taa^\dagger \mu^{-1} = t\mu^{-1}.$$

The equality

$$\xi a^* = t\mu^{-1} \quad (20)$$

will be used later in this document.

3. The four “faces” of M^\dagger

We now examine the four cases where the block lower triangular matrix $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$ has a Moore-Penrose inverse of the form:

(i) $M^\dagger = \begin{bmatrix} * & 0 \\ * & * \end{bmatrix}$ the (1,2,0) case (unflipped),

(ii) $M^\dagger = \begin{bmatrix} * & * \\ 0 & * \end{bmatrix}$ the (2,1,0) case (flipped),

(iii) $M^\dagger = \begin{bmatrix} 0 & * \\ * & * \end{bmatrix}$ the (1,1,0) case,

(iv) $M^\dagger = \begin{bmatrix} * & * \\ * & 0 \end{bmatrix}$ the (2,2,0) case.

3.1. The (1,2,0) case (unflipped)

The Moore-Penrose inverse of the block lower triangular matrix $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$ is again of (1,2,0) type if and only if $b = dd^\dagger b = ba^\dagger a$ (see [12]).

We may also use the general triangular case (10) to rederive this consistency. Indeed this occurs precisely when

$$0 = q = \xi b^*(1 - dd^\dagger) + (1 + f^*f)^{-1} f^* d^\dagger [1 - b\xi b^*(1 - dd^\dagger)].$$

By post-multiplying by dd^\dagger gives $(1 + f^*f)^{-1} f^* d^\dagger = 0$ which reduces to $df = 0$. By substituting this back into q , then shows that also $\xi b^*(1 - dd^\dagger) = 0$. Thus M^\dagger has the desired lower triangular form if and only if

$$df = 0 \text{ and } \xi b^*(1 - dd^\dagger) = 0. \tag{21}$$

Now recall that if $B = (1 - dd^\dagger)b$ then $\xi = (a^*a + B^*B)^\dagger$. Hence the second consistency condition becomes $(a^*a + B^*B)^\dagger B^* = 0$, which is equivalent to $(a^*a + B^*B)B^* = 0$. This implies that $B(a^*a + B^*B)B^* = 0$ and hence by star-cancellation, $BB^* = 0$ and thus $B = 0$. This says that $b = dd^\dagger b$ and hence $v = 0$.

By substituting in $0 = df = dd^\dagger b[1 - a^\dagger a - v^\dagger v]$ then yields $0 = b(1 - a^\dagger a)$, and we recover the necessary condition $b = dd^\dagger ba^\dagger a$, which is also sufficient. We have proved

THEOREM 3.1. Given $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$, the following conditions are equivalent:

1. M^\dagger is of $(1, 2, 0)$ type.
2. $b \in dRa$.
3. $b = dd^\dagger ba^\dagger a$.
4. $dd^\dagger b = b = ba^\dagger a$.

In this case, $M^\dagger = \begin{bmatrix} a^\dagger & 0 \\ -d^\dagger ba^\dagger & d^\dagger \end{bmatrix}$.

This can be extended to the $n \times n$ case (as in [6]).

3.2. The $(2, 1, 0)$ case (flipped)

Next we examine the case here the Moore-Penrose inverse of the lower triangular matrix M “flips” and takes the form $M^\dagger = \begin{bmatrix} p & q \\ 0 & r \end{bmatrix}$ for some p, q , and r . We will give necessary and sufficient conditions for this to happen, in terms of the blocks a, b and d .

From (12) we see that a necessary and sufficient condition for M^\dagger to have the flipped form $\begin{bmatrix} p & q \\ 0 & r \end{bmatrix}$ is that $d^\dagger b \xi a^* = 0$.

We now observe from Equation (20), that the consistency condition collapses to $0 = d^* b t = d^* b (1 - v^\dagger b) a^\dagger$, which yields

$$d^* b a^* = d^* b v^\dagger b a^*, \tag{22}$$

or equivalently

$$dd^\dagger b (b^\dagger - v^\dagger) b a^\dagger a = 0.$$

We thus have

THEOREM 3.2. Given $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$, then M^\dagger is of $(2, 1, 0)$ type if and only if

$$dd^\dagger b (b^\dagger - v^\dagger) b a^\dagger a = 0,$$

in which case

$$M^\dagger = \begin{bmatrix} \xi a^* & \xi b^* (1 - dd^\dagger) + (1 + f^* f)^{-1} f^* d^\dagger [1 - b \xi b^* (1 - dd^\dagger)] \\ 0 & (1 + f f^*)^{-1} d^\dagger [1 - b \xi^* b^* (1 - dd^\dagger)] \end{bmatrix},$$

where ξ, f are as above.

If we set $e = a^\dagger a$ and $f = dd^\dagger$, then the consistency condition can be written as

$$\zeta = fbe - fb[(1 - f)b(1 - e)]^\dagger be = 0,$$

which is the (2,2) Schur complement in $\begin{bmatrix} fbe & be \\ fb & (1 - f)b(1 - e) \end{bmatrix}$. It only involves b , e and f . It is not clear how to simplify this condition. All we have is that $vv^\dagger = (1 - dd^\dagger)bv^\dagger$.

3.3. The (2,2,0) case

From (10) we see that M^\dagger is of (2,2,0) type if and only if $r = 0$, which is equivalent to

$$d^\dagger = d^\dagger b \xi^* b^* (1 - dd^\dagger).$$

Right multiplication by dd^\dagger shows that necessarily $d^\dagger = 0$, that is, $d = 0$. The sufficiency is clear. We may thus state the following result:

THEOREM 3.3. *Given $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$, M^\dagger is of (2,2,0) type if and only if $d = 0$,*

*in which case $\begin{bmatrix} a & 0 \\ b & d \end{bmatrix}^\dagger = \begin{bmatrix} (a^*a + b^*b)^\dagger a^* & (a^*a + b^*b)^\dagger b^* \\ 0 & 0 \end{bmatrix}$.*

3.4. The (1,1,0) case

Lastly, we analyze the case where M^\dagger is of (1,1,0) type. This corresponds to

$$p = \xi a^* - (1 + f^*f)^{-1} f^* d^\dagger b \xi a^* = 0,$$

with $\xi = (a^*a + B^*B)^\dagger$, $B = (1 - dd^\dagger)b$, $f = d^\dagger b(1 - a^\dagger a - v^\dagger v)$ and $v = (1 - dd^\dagger)b(1 - a^\dagger a)$.

Now recall, from equation (20), that $\xi a^* = t\mu^{-1}$, where $\mu = 1 + x^*x = (1 - vv^\dagger)Ba^\dagger$ and $t = a^\dagger - v^\dagger ba^\dagger$. Thus $p = 0$ is equivalent to $t\mu^{-1} = (1 + f^*f)^{-1} f^* d^\dagger b t \mu^{-1}$, i.e. to

$$(1 + f^*f)t = f^* d^\dagger b t. \tag{23}$$

Since $va^\dagger = 0 = av^\dagger$ we know that $fa^\dagger = 0 = fv^\dagger$ and consequently $ft = 0$.

The equality (23) now reduces to $t = f^* d^\dagger b t$. Lastly, left multiplication by $a^\dagger a$ shows that necessarily $a^\dagger = 0$, that is, $a = 0$. This is, trivially, sufficient for $p = 0$. We may thus conclude that

THEOREM 3.4. *Given $M = \begin{bmatrix} a & 0 \\ b & d \end{bmatrix}$, M^\dagger is of (1,1,0) type if and only if $a = 0$,*

in which case $\begin{bmatrix} 0 & 0 \\ b & d \end{bmatrix}^\dagger = \begin{bmatrix} 0 & b^(bb^* + dd^*)^\dagger \\ 0 & d^*(bb^* + dd^*)^\dagger \end{bmatrix}$.*

It is easily seen that these reduce to Cline’s result.

4. Questions and remarks

1. The consistency condition for the Moore-Penrose inverse to flip involves the corner matrix $v = (1 - dd^\dagger)b(1 - a^\dagger a)$. Its Moore-Penrose inverse is a perturbation of b^\dagger .
2. Can we use the theory of Schur complements or partial orders, to simplify the consistency condition $fbe = fb[(1 - f)b(1 - e)]^\dagger be$?
3. No further simplification of the Condition (22) seems possible.
4. The unflipped case can be, inductively, generalized to the $n \times n$ case. What can be said for the flipped case for $n \times n$ matrices?
5. To ensure the symmetry of $R_{2 \times 2}$ with R regular and symmetric, we may replace the square-root axiom on R by the condition SC_4 .
6. $SC_2(R)$ does not imply $SC_n(R)$, nor implies the square root property, as remarked in Examples 2 and 3 in [13, page 215].
7. We have not used *any* of the other conditions that relate p , q , and r to a , b and d .

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