

A PROBLEM CONCERNING RIEMANN SUMS

IOSIF PINELIS

Abstract. An open problem concerning Riemann sums, posed by O. Furdui, is considered.

Let $f: [0, 1] \rightarrow \mathbb{R}$ be a continuous function. For natural n , let

$$x_n := \sum_{k=1}^{n-1} f\left(\frac{k}{n}\right) \quad \text{and} \quad y_n := x_{n+1} - x_n. \quad (1)$$

One may note here that x_n/n is a Riemann sum approximating the integral $\int_0^1 f(x) dx$.

Part (a) of Problem 1.32 in the book [3] is to find $\lim_{n \rightarrow \infty} y_n$ if the function f is continuously differentiable. It is not hard to do a bit more:

PROPOSITION 1. *Whenever f is absolutely continuous, one has*

$$\lim_{n \rightarrow \infty} y_n = \int_0^1 f(x) dx. \quad (2)$$

On the other hand, it is even easier to show this:

PROPOSITION 2. *Whenever $\lim_{n \rightarrow \infty} y_n$ exists, equality (2) holds.*

Propositions 1 and 2 will be proved at the end of this note.

Part (b) of Problem 1.32 in [3] is the following question, which has so far remained apparently unanswered:

What is the limit [in (2)] when f is only continuous?

By Proposition 2, this limit, if it exists, may only be $\int_0^1 f(x) dx$. However, we have

THEOREM 3. *There are continuous functions $f: [0, 1] \rightarrow \mathbb{R}$ for which $\lim_{n \rightarrow \infty} y_n$ does not exist.*

Mathematics subject classification (2010): 26A06, 26A27, 26A42, 26A46, 60Exx, 60G15.

Keywords and phrases: Riemann sums, probabilistic method, Wiener process, Brownian motion, integrals, sequences, limits, continuity, absolute continuity, fractional part integrals.

This is a pure existence theorem, and its proof, given below, is non-constructive. So, the problem of explicitly constructing a continuous function for which $\lim_{n \rightarrow \infty} y_n$ does not exist remains open.

Proof of Theorem 3. It may come as a surprise that this proof uses a probabilistic method. Let f be the random function W that is a standard Wiener process (Brownian motion) over the interval $[0, 1]$. Then the probability that f is continuous everywhere on $[0, 1]$ is 1; see e.g. [4]. In fact, without loss of generality we may assume that all realizations of the random function $f = W$ are everywhere continuous.

Informally, the idea of this proof of Theorem 3 is that, while all realizations of W are everywhere continuous, they are rather non-smooth, not only in the sense of being nowhere differentiable, but also not being Hölder continuous with any exponent $\geq 1/2$, in view of the (local) law of the iterated logarithm [4].

Now back to the formal proof: actually, Theorem 3 follows immediately from

LEMMA 4. *For $f = W$, the distribution of the random variable $y_{4s} - y_{2s}$ converges to the centered normal distribution with variance $1/4$.*

(The convergence here and in the rest of the proof of Theorem 3 is as $\mathbb{N} \ni s \rightarrow \infty$.)

Indeed, if Theorem 3 were false, we would have $y_{4s} - y_{2s} \rightarrow 0$ almost surely and hence in distribution, which would contradict Lemma 4. So, to complete the proof of Theorem 3, it remains to prove the lemma.

Proof of Lemma 4. Since $y_{4s} - y_{2s}$ is a centered normal random variable, it suffices to show that

$$\mathbb{E}(y_{4s} - y_{2s})^2 \xrightarrow{(?)} 1/4. \quad (3)$$

The proof of (3) consists in direct calculations, which are somewhat involved, though, as we have to deal carefully enough with the discreteness in the definition of x_n . In carrying out this task, the choice of indices, $4s$ and $2s$, in the statement of Lemma 4 turns out to be sufficiently convenient.

The just mentioned calculations are based on the formula

$$\mathbb{E}W(u)W(v) = u \wedge v$$

for all u, v in $[0, 1]$. By (1), for $f = W$,

$$\mathbb{E}x_n^2 = \sum_{j,k=1}^{n-1} \mathbb{E}W\left(\frac{j}{n}\right)W\left(\frac{k}{n}\right) = \sum_{j,k=1}^{n-1} \left(\frac{j}{n} \wedge \frac{k}{n}\right) = \frac{2n^2 - 3n + 1}{6}. \quad (4)$$

Somewhat similarly,

$$\begin{aligned} \mathbb{E}x_n x_{n+1} &= \sum_{j=1}^{n-1} \sum_{k=1}^n \left(\frac{j}{n} \wedge \frac{k}{n+1}\right) \\ &= \sum_{j=1}^{n-1} \sum_{k=j+1}^n \frac{j}{n} + \sum_{j=1}^{n-1} \sum_{k=1}^j \frac{k}{n+1} = \frac{2n^2 - n - 1}{6}. \end{aligned} \quad (5)$$

It follows from (1), (4), and (5) that

$$E y_n^2 = E x_{n+1}^2 + E x_n^2 - 2 E x_n x_{n+1} = 1/2. \tag{6}$$

Now take any natural s . Similarly to (5), we have

$$\begin{aligned} E x_{4s} x_{2s} &= \sum_{j=1}^{4s-1} \sum_{k=1}^{2s-1} \left(\frac{j}{4s} \wedge \frac{k}{2s} \right) \\ &= \sum_{k=1}^{2s-1} \sum_{j=1}^{2k} \frac{j}{4s} + \sum_{k=1}^{2s-1} \sum_{j=2k+1}^{4s-1} \frac{k}{2s} = \frac{32s^2 - 18s + 1}{12}, \\ E x_{4s+1} x_{2s+1} &= \sum_{j=1}^{4s} \sum_{k=1}^{2s} \left(\frac{j}{4s+1} \wedge \frac{k}{2s+1} \right) \\ &= \sum_{k=1}^{2s} \sum_{j=1}^{2k-1} \frac{j}{4s+1} + \sum_{k=1}^{2s} \sum_{j=2k}^{4s-1} \frac{k}{2s+1} = \frac{32s^3 + 14s^2}{12s+3}, \end{aligned}$$

$$\begin{aligned} E x_{4s+1} x_{2s} &= \sum_{j=1}^{4s} \sum_{k=1}^{2s-1} \left(\frac{j}{4s+1} \wedge \frac{k}{2s} \right) \\ &= \sum_{k=1}^{2s-1} \sum_{j=1}^{2k} \frac{j}{4s+1} + \sum_{k=1}^{2s-1} \sum_{j=2k+1}^{4s} \frac{k}{2s} = \frac{32s^3 - 2s^2 - 5s - 1}{12s+3}, \end{aligned}$$

$$\begin{aligned} E x_{4s} x_{2s+1} &= \sum_{j=1}^{4s-1} \sum_{k=1}^{2s} \left(\frac{j}{4s} \wedge \frac{k}{2s+1} \right) \\ &= \sum_{k=1}^s \sum_{j=1}^{2k-1} \frac{j}{4s} + \sum_{k=1}^s \sum_{j=2k}^{4s-1} \frac{k}{2s+1} \\ &\quad + \sum_{k=s+1}^{2s} \sum_{j=1}^{2k-2} \frac{j}{4s} + \sum_{k=s+1}^{2s} \sum_{j=2k-1}^{4s-1} \frac{k}{2s+1} = \frac{64s^3 + 28s^2 - 7s - 1}{24s+12}. \end{aligned}$$

So,

$$\begin{aligned} E y_{4s} y_{2s} &= E x_{4s} x_{2s} + E x_{4s+1} x_{2s+1} - E x_{4s+1} x_{2s} - E x_{4s} x_{2s+1} \\ &= \frac{12s^2 + 9s + 2}{32s^2 + 24s + 4} \longrightarrow \frac{12}{32}. \end{aligned}$$

Thus, in view of (6),

$$E (y_{4s} - y_{2s})^2 = E y_{4s}^2 + E y_{2s}^2 - 2 E y_{4s} y_{2s} \longrightarrow \frac{1}{2} + \frac{1}{2} - 2 \times \frac{12}{32} = \frac{1}{4},$$

so that (3) is verified, which completes the proof of Lemma 4. \square

The proof of Theorem 3 is now complete as well. \square

To conclude this note, it remains to prove Propositions 1 and 2.

Proof of Proposition 1. Since f is absolutely continuous, there is a function $g \in L^1[0, 1]$ such that

$$f(x) = f(0) + \int_0^x g(u) du = f(0) + \int_0^1 g(u) \mathbf{I}\{u < x\} du \quad (7)$$

for all $x \in [0, 1]$, where $\mathbf{I}\{\cdot\}$ denotes the indicator. So, by (1),

$$x_n = (n-1)f(0) + \int_0^1 g(u) \sum_{k=1}^{n-1} \mathbf{I}\left\{u < \frac{k}{n}\right\} du$$

and hence

$$y_n = f(0) + I_n(g) - J_n(g), \quad (8)$$

where

$$I_n(g) := \int_0^1 g(u) \mathbf{I}\left\{u < \frac{n}{n+1}\right\} du, \quad J_n(g) := \int_0^1 g(u) h_n(u) du,$$

and

$$h_n(u) := \sum_{k=1}^{n-1} \mathbf{I}\left\{\frac{k}{n+1} \leq u < \frac{k}{n}\right\}. \quad (9)$$

Clearly,

$$I_n(g) = f\left(\frac{n}{n+1}\right) - f(0) \longrightarrow f(1) - f(0). \quad (10)$$

Here and in the rest of this proof, the convergence is as $n \rightarrow \infty$.

To deal with $J_n(g)$, take any real $\varepsilon > 0$. Since $g \in L^1[0, 1]$, by [1, Corollary 4.2.2], $\int_0^1 |g(u) - \tilde{g}(u)| du \leq \varepsilon$ for some continuous function $\tilde{g}: [0, 1] \rightarrow \mathbb{R}$. Note also that $0 \leq h_n \leq 1$, since $[\frac{k}{n+1}, \frac{k}{n}) \subset [\frac{k-1}{n}, \frac{k}{n})$ for $k = 1, \dots, n-1$. So,

$$|J_n(g) - J_n(\tilde{g})| \leq \int_0^1 |g(u) - \tilde{g}(u)| du \leq \varepsilon. \quad (11)$$

Introduce now the function \tilde{g}_n by the formula

$$\tilde{g}_n(u) := \sum_{k=1}^{n-1} \tilde{g}\left(\frac{k}{n}\right) \mathbf{I}\left\{\frac{k}{n+1} \leq u < \frac{k}{n}\right\}$$

for $u \in [0, 1]$. Since the function \tilde{g} is continuous, it is uniformly continuous on $[0, 1]$, so that, in view of (9), $\|\tilde{g}h_n - \tilde{g}_nh_n\|_\infty = \|\tilde{g}h_n - \tilde{g}_n\|_\infty \rightarrow 0$ and hence

$$|J_n(\tilde{g}) - J_n(\tilde{g}_n)| \longrightarrow 0. \quad (12)$$

On the other hand, using the continuity of \tilde{g} and integration by parts, we have

$$J_n(\tilde{g}_n) = \sum_{k=1}^{n-1} \tilde{g}\left(\frac{k}{n}\right) \frac{k}{n} \frac{1}{n} \frac{n}{n+1} \longrightarrow \int_0^1 \tilde{g}(u) u du = \tilde{f}(1) - \int_0^1 \tilde{f}'(u) du \quad (13)$$

where $\tilde{f}(x) := f(0) + \int_0^x \tilde{g}(u) du$ for $x \in [0, 1]$. By (7) and the second inequality in (11), we have $|\tilde{f} - f| \leq \varepsilon$ and hence $|\int_0^1 \tilde{f}(u) du - \int_0^1 f(u) du| \leq \varepsilon$. Collecting now (8), (10), (11), (12), and (13), we see that

$$\limsup_{n \rightarrow \infty} \left| y_n - \int_0^1 f(u) du \right| \leq 3\varepsilon$$

for any real $\varepsilon > 0$, which completes the proof of Proposition 1. \square

Proof of Proposition 2. The Stolz–Cesàro theorem ([5, pages 173–175] and [2, page 54]) states the following: if (a_n) and (b_n) are sequences of real numbers such that b_n is strictly increasing to ∞ and $\frac{a_{n+1} - a_n}{b_{n+1} - b_n} \rightarrow \ell \in \mathbb{R}$, then $\frac{a_n}{b_n} \rightarrow \ell$. Now Proposition 2 follows immediately by applying the Stolz–Cesàro theorem with $a_n = x_n$ and $b_n = n$, since $\frac{x_n}{n} \rightarrow \int_0^1 f(x) dx$. \square

REFERENCES

- [1] V. I. BOGACHEV, *Measure theory, Vol. I, II*, Springer-Verlag, Berlin, 2007.
- [2] E. CESÀRO, *Sur la convergence des séries*, Nouvelles annales de mathématiques, 7 (3): 49–59, 1888.
- [3] O. FURDUI, *Limits, series, and fractional part integrals*, Problem Books in Mathematics, Springer, New York, 2013, Problems in mathematical analysis.
- [4] P. MÖRTERS AND Y. PERES, *Brownian motion*, volume 30 of Cambridge Series in Statistical and Probabilistic Mathematics, Cambridge University Press, Cambridge, 2010, With an appendix by Oded Schramm and Wendelin Werner.
- [5] O. STOLZ, *Vorlesungen über allgemeine Arithmetik: nach den Neueren Ansichten*, Teubners, 1885.

(Received September 9, 2018)

Iosif Pinelis
 Department of Mathematical Sciences
 Michigan Technological University
 Houghton, Michigan 49931, USA
 e-mail: ipinelis@mtu.edu