# STABILITY OF A NEW ADDITIVE FUNCTIONAL INEQUALITY IN BANACH SPACES 

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#### Abstract

We propose and solve a new type of additive functional inequality. We also obtain the Hyers-Ulam stability of such functional inequality in a complex Banach space by using two different approaches.


## 1. Introduction and preliminaries

In 1940, Ulam [29] mentioned a question regarding the stability of (group) homomorphisms which motivated the study of the stability problems of functional equations.

Every consequence of the Cauchy functional equation:

$$
g(u+v)=g(u)+g(u)
$$

is said to be an additive mapping. The properties of Cauchy functional equations are vigorous tools in almost every field of natural and social sciences. Hyers [12] obtained a partial answer to the question for additive mappings in Banach spaces. The stability of functional equations has been also known as Hyers-Ulam stability. It was later extended by Aoki [1] for additive mappings, and by Rassias [27] for linear mappings by concerning an unbounded Cauchy difference. Replacing the unbounded Cauchy difference by a general control function, Găvruta [10] also extended the Rassias theorem. Park [22,23] recently defined additive $\rho$-functional inequalities and proved the HyersUlam stability of those inequalities in non-Archimedean Banach spaces and Banach spaces. The stability results of the Jensen functional equation:

$$
g\left(\frac{u+v}{2}\right)=\frac{g(u)+g(v)}{2}
$$

have been scrutinized by several authors, see [14, 17, 18], for example.
Applications of stability theory of functional equations for proving fixed point theorems and applications in nonlinear analysis were introduced by Isac and Rassias [13]

[^0]in 1996. A large number of research articles concerning the stability problems of several functional equations for instance set-valued functional equation, Cauchy functional equation, Drygas functional equation, and various definitions of stability by using the fixed pointed technique have been widely studied in great details in [4, 5, 7, 24, 26, 28].

In this article, we let $\mathbb{N}, \mathbb{R}, \mathbb{R}^{+}$and $\mathbb{C}$ denote the set of positive integers, of real numbers, of positive real numbers and of complex numbers. Also, we let $\mathbb{N}_{0}=\mathbb{N} \cup\{0\}$ and $\mathbb{R}_{0}^{+}=\mathbb{R}^{+} \cup\{0\}$.

For $\left(\rho_{1}, \rho_{2}\right) \in\left\{\left(z, z^{\prime}\right) \in \mathbb{C} \backslash\{0\} \times \mathbb{C} \backslash\{0\}: \sqrt{2}|z|+\left|z^{\prime}\right|<1\right\}$, the following additive $\left(\rho_{1}, \rho_{2}\right)$-functional inequality:

$$
\begin{aligned}
\left\|2 g\left(\frac{u+v}{2}\right)-g(u)-g(v)\right\| \leqslant & \left\|\rho_{1}(g(u+v)+g(u-v)-2 g(u))\right\| \\
& +\left\|\rho_{2}(g(u+v)-g(u)-g(v))\right\|
\end{aligned}
$$

was introduced and solved in 2017 by Yun and Shin [30]. Recently, Park [25] also proposed and solved the additive $\left(\rho_{1}, \rho_{2}\right)$-functional inequality as follows:

$$
\begin{aligned}
\|g(u+v)-g(u)-g(v)\| \leqslant & \left\|\rho_{1}(g(u+v)+g(u-v)-2 g(u))\right\| \\
& +\left\|\rho_{2}\left(2 g\left(\frac{u+v}{2}\right)-g(u)-g(v)\right)\right\|
\end{aligned}
$$

Moreover, the Hyers-Ulam stability solutions for the additive ( $\rho_{1}, \rho_{2}$ )-functional inequalities are proved in a complex Banach space. The stability problems of varied functional equations and functional inequalities have been studied considerably; for instance, see $[2,8,9,15,16,19,21,31]$.

We begin with a useful result in theory of fixed point.
THEOREM 1. [3, 6] Let $(\mathscr{X}, d)$ be a complete generalized metric space, and let $u \in \mathscr{X}$. For a strict Lipschitz contraction $\mathscr{T}: \mathscr{X} \rightarrow \mathscr{X}$ with the Lipschitz constant $\mu<1$, either

- $d\left(\mathscr{T}^{n} u, \mathscr{T}^{n+1} u\right)=\infty$ for all $n \in \mathbb{N}_{0}$ or
- there exists $n_{0} \in \mathbb{N}$ for which $d\left(\mathscr{T}^{n} u, \mathscr{T}^{n+1} u\right)<\infty$ for all $n \geqslant n_{0}$; $\left\{\mathscr{T}^{n} u\right\} \rightarrow v^{*}$ where $v^{*}$ is a unique fixed point of $\mathscr{T}$ in $\mathscr{X}_{n_{0}}:=\left\{v \in \mathscr{X} \mid d\left(\mathscr{T}^{n_{0}} u, v\right)<\infty\right\}$; $d\left(v, v^{*}\right) \leqslant \frac{1}{1-\mu} d(v, \mathscr{T} v)$ for all $v \in \mathscr{X}_{n_{0}}$.
In this paper, we study the functional inequality (1). This inequality is called additive $\left(t_{1}, t_{2}\right)$-functional inequality. We prove the Hyers-Ulam stability of such functional inequality by applying the direct technique in Section 2. While in Section 3, the HyersUlam stability of (1) using the fixed point technique is given.

For all over this article, let $\mathscr{X}$ and $\mathscr{Y}$ be a (real or complex) normed space and a complex Banach space, respectively. We let $\left(t_{1}, t_{2}\right) \in\left\{\left(z, z^{\prime}\right) \in \mathbb{C} \backslash\{0\} \times \mathbb{C} \backslash\{0\}\right.$ : $\left.|z|+\left|z^{\prime}\right|<\frac{1}{\sqrt{2}}\right\}$. Also, we denote the class of mapping $\{f: \mathscr{X} \rightarrow \mathscr{Y}: f(0)=0\}$ by $\mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$, the class of mapping $f: \mathscr{X} \rightarrow \mathscr{Y}$ which is additive by $\mathscr{A}(\mathscr{X}, \mathscr{Y})$, and $\mathscr{A}_{0}(\mathscr{X}, \mathscr{Y}):=\mathscr{M}_{0}(\mathscr{X}, \mathscr{Y}) \cap \mathscr{A}(\mathscr{X}, \mathscr{Y})$.

## 2. Stability results: direct technique

In this section, the stability outcomes of the additive $\left(t_{1}, t_{2}\right)$-functional inequality (1) are solved and investigated by using the direct technique. We start with the following lemma:

LEMMA 1. If a mapping $g: \mathscr{X} \rightarrow \mathscr{Y}$ satisfies the following functional inequality:

$$
\begin{align*}
\|g(u+v)-g(u)-g(v)\| \leqslant & \left\|t_{1}(g(u+v)+g(u-v)-2 g(u))\right\| \\
& +\left\|t_{2}\left(2 g\left(\frac{u+v}{2}\right)+g(u-v)-2 g(u)\right)\right\| \tag{1}
\end{align*}
$$

for all $u, v \in \mathscr{X}$, then $g \in \mathscr{A}(\mathscr{X}, \mathscr{Y})$.

Proof. Putting $u=v=0$ into (1), we gain $\left(1-\left|t_{2}\right|\right)\|g(0)\| \leqslant 0$ and so $g(0)=0$, since $\left|t_{2}\right|<1$. Next, by taking $v=u$ in (1) and from $\left|t_{1}\right|<1$, we obtain

$$
\begin{equation*}
2 g(u)=g(2 u) \tag{2}
\end{equation*}
$$

for all $u \in \mathscr{X}$. From (1), it follows

$$
\begin{equation*}
\|g(u+v)-g(u)-g(v)\| \leqslant\left(\left|t_{1}\right|+\left|t_{2}\right|\right)\|g(u+v)+g(u-v)-2 g(u)\| \tag{3}
\end{equation*}
$$

for all $u, v \in \mathscr{X}$. Setting $\bar{u}=u+v$ and $\bar{v}=u-v$ in (1), we gain

$$
\left\|g(\bar{u})-g\left(\frac{\bar{u}+\bar{v}}{2}\right)-g\left(\frac{\bar{u}-\bar{v}}{2}\right)\right\| \leqslant\left(\left|t_{1}\right|+\left|t_{2}\right|\right)\left\|g(\bar{u})+g(\bar{v})-2 g\left(\frac{\bar{u}+\bar{v}}{2}\right)\right\| .
$$

This implies by the equation (2) that

$$
\begin{equation*}
\frac{1}{2}\|g(\bar{u}+\bar{v})+g(\bar{u}-\bar{v})-2 g(\bar{u})\| \leqslant\left(\left|t_{1}\right|+\left|t_{2}\right|\right)\|g(\bar{u}+\bar{v})-g(\bar{u})-g(\bar{v})\| \tag{4}
\end{equation*}
$$

for all $\bar{u}, \bar{v} \in \mathscr{X}$. Using (3) and (4), we obtain

$$
\frac{1}{2}\|g(u+v)-g(u)-g(v)\| \leqslant\left(\left|t_{1}\right|+\left|t_{2}\right|\right)^{2}\|g(u+v)-g(u)-g(v)\|
$$

for all $u, v \in \mathscr{X}$. This follows from $\left|t_{1}\right|+\left|t_{2}\right|<\frac{1}{\sqrt{2}}$ that $g(u+v)=g(u)+g(v)$ for all $u, v \in \mathscr{X}$, that is, $g \in \mathscr{A}(\mathscr{X}, \mathscr{Y})$.

This time, we provide the main results.
THEOREM 2. Let a fixed function $\varphi: \mathscr{X} \times \mathscr{X} \rightarrow \mathbb{R}_{0}^{+}$satisfy

$$
\begin{equation*}
\Phi(u, v):=\sum_{j=1}^{\infty} 2^{j} \varphi\left(2^{-j} u, 2^{-j} v\right)<\infty \tag{5}
\end{equation*}
$$

for all $u, v \in \mathscr{X}$. If $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ and

$$
\begin{align*}
\|g(u+v)-g(u)-g(v)\| \leqslant & \left\|t_{1}(g(u+v)+g(u-v)-2 g(u))\right\| \\
& +\left\|t_{2}\left(2 g\left(\frac{u+v}{2}\right)+g(u-v)-2 g(u)\right)\right\|+\varphi(u, v) \tag{6}
\end{align*}
$$

for all $u, v \in \mathscr{X}$, then there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\begin{equation*}
\|g(u)-G(u)\| \leqslant \frac{\Phi(u, u)}{2\left(1-\left|t_{1}\right|\right)} \tag{7}
\end{equation*}
$$

for all $u \in \mathscr{X}$.

Proof. By taking $v=u$ in (6), for all $u \in \mathscr{X}$, we gain

$$
\begin{equation*}
\left(1-\left|t_{1}\right|\right)\|g(2 u)-2 g(u)\| \leqslant \varphi(u, u) \tag{8}
\end{equation*}
$$

and so

$$
\left\|g(u)-2 g\left(\frac{u}{2}\right)\right\| \leqslant \frac{1}{1-\left|t_{1}\right|} \varphi\left(\frac{u}{2}, \frac{u}{2}\right) .
$$

Then, for all $m, l \in \mathbb{N}_{0}$ with $m>l$ and all $u \in \mathscr{X}$,

$$
\begin{align*}
\left\|2^{l} g\left(2^{-l} u\right)-2^{m} g\left(2^{-m} u\right)\right\| & \leqslant \sum_{j=l}^{m-1}\left\|2^{j} g\left(2^{-j} u\right)-2^{j+1} g\left(2^{-(j+1)} u\right)\right\| \\
& \leqslant \frac{1}{2\left(1-\left|t_{1}\right|\right)} \sum_{j=l+1}^{m} 2^{j} \varphi\left(2^{-j} u, 2^{-j} u\right) \tag{9}
\end{align*}
$$

Thus, $\left\{2^{n} g\left(2^{-n} u\right)\right\}$ is a Cauchy sequence for all $u \in \mathscr{X}$ and hence a convergent sequence due to the completeness of $\mathscr{Y}$. Define $G: \mathscr{X} \rightarrow \mathscr{Y}$ by

$$
G(u):=\lim _{n \rightarrow \infty} 2^{n} g\left(2^{-n} u\right)
$$

for all $u \in \mathscr{X}$. Next, select $l=0$ and let $m \rightarrow \infty$ in (9). Then, we have that the mapping $G$ satisfies (7). That follows from (5) and (6) as

$$
\begin{aligned}
& \|G(u+v)-G(u)-G(v)\| \\
& =\lim _{n \rightarrow \infty} 2^{n}\left\|g\left(2^{-n}(u+v)\right)-g\left(2^{-n} u\right)-g\left(2^{-n} v\right)\right\| \\
& \leqslant \\
& \left|t_{1}\right| \lim _{n \rightarrow \infty} 2^{n}\left\|g\left(2^{-n}(u+v)\right)+g\left(2^{-n}(u-v)\right)-2 g\left(2^{-n} u\right)\right\| \\
& \quad+\left|t_{2}\right| \lim _{n \rightarrow \infty} 2^{n}\left\|2 g\left(2^{-(n+1)}(u+v)\right)+g\left(2^{-n}(u-v)\right)-2 g\left(2^{-n} u\right)\right\| \\
& \quad+\lim _{n \rightarrow \infty} 2^{n} \varphi\left(2^{-n} u, 2^{-n} v\right) \\
& =\left\|t_{1}(G(u+v)+G(u-v)-2 G(u))\right\|+\left\|t_{2}\left(2 G\left(\frac{u+v}{2}\right)+G(u-v)-2 G(u)\right)\right\|
\end{aligned}
$$

for all $u, v \in \mathscr{X}$. By the definition of $G$ with Lemma 1, we obtain that $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$. Finally, let another mapping $F \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ satisfy (7). Then,

$$
\begin{aligned}
\|G(u)-F(u)\| & =\left\|2^{p} G\left(2^{-p} u\right)-2^{p} F\left(2^{-p} u\right)\right\| \\
& \leqslant\left\|2^{p} G\left(2^{-p} u\right)-2^{p} g\left(2^{-p} u\right)\right\|+\left\|2^{p} F\left(2^{-p} u\right)-2^{p} g\left(2^{-p} u\right)\right\| \\
& \leqslant \frac{2^{p}}{\left(1-\left|t_{1}\right|\right)} \Phi\left(2^{-p} u, 2^{-p} u\right)
\end{aligned}
$$

for all $u \in \mathscr{X}$. Then, $\|G(u)-F(u)\| \rightarrow 0$ when $p \rightarrow \infty$ and this confirms the uniqueness of $G$.

Corollary 1. For $s, \vartheta \in \mathbb{R}_{0}^{+}$with $s>1$, let $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ and

$$
\begin{align*}
\|g(u+v)-g(u)-g(v)\| \leqslant & \left\|t_{1}(g(u+v)+g(u-v)-2 g(u))\right\| \\
& +\left\|t_{2}\left(2 g\left(\frac{u+v}{2}\right)+g(u-v)-2 g(u)\right)\right\| \\
& +\vartheta\left(\|u\|^{s}+\|v\|^{s}\right) \tag{10}
\end{align*}
$$

for all $u, v \in \mathscr{X}$. Then, there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\|g(u)-G(u)\| \leqslant \frac{2 \vartheta\|u\|^{s}}{\left(1-\left|t_{1}\right|\right)\left(2^{s}-2\right)}
$$

for all $u \in \mathscr{X}$.
Proof. Let $\varphi(u, v)=\vartheta\left(\|u\|^{s}+\|v\|^{s}\right)$ for all $u, v \in \mathscr{X}$, we immediately obtain the result.

The structure of the proof of the next result is analogous to the proof of Theorem 2. We include some details for convenience of the readers.

THEOREM 3. Let a fixed function $\varphi: \mathscr{X} \times \mathscr{X} \rightarrow \mathbb{R}_{0}^{+}$satisfy

$$
\Psi(u, v):=\sum_{j=0}^{\infty} 2^{-j} \varphi\left(2^{j} u, 2^{j} v\right)<\infty
$$

for all $u, v \in \mathscr{X}$, and let $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ satisfy (6). Then, there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\begin{equation*}
\|g(u)-G(u)\| \leqslant \frac{\Psi(u, u)}{2\left(1-\left|t_{1}\right|\right)} \tag{11}
\end{equation*}
$$

for all $u \in \mathscr{X}$.
Proof. It follows from (8) that

$$
\left\|g(u)-\frac{1}{2} g(2 u)\right\| \leqslant \frac{\varphi(u, u)}{2\left(1-\left|t_{1}\right|\right)}
$$

for all $u \in \mathscr{X}$. Then, for $m, l \in \mathbb{N}_{0}$ with $m>l$,

$$
\begin{align*}
\left\|2^{-l} g\left(2^{l} u\right)-2^{-m} g\left(2^{m} u\right)\right\| & \leqslant \sum_{j=l}^{m-1}\left\|2^{-j} g\left(2^{j} u\right)-2^{-(j+1)} g\left(2^{j+1} u\right)\right\| \\
& \leqslant \frac{1}{1-\left|t_{1}\right|} \sum_{j=l}^{m-1} 2^{-(j+1)} \varphi\left(2^{j} u, 2^{j} u\right) \tag{12}
\end{align*}
$$

for all $u \in \mathscr{X}$. Then, the completeness of $\mathscr{Y}$ implies that $\left\{2^{-n} g\left(2^{n} u\right)\right\}$ is convergent for all $u \in \mathscr{X}$. Next, we let a mapping $G: \mathscr{X} \rightarrow \mathscr{Y}$ by

$$
G(u):=\lim _{n \rightarrow \infty} 2^{-n} g\left(2^{n} u\right)
$$

for all $u \in \mathscr{X}$. Select $l=0$ and let $m \rightarrow \infty$ in (12). Then, we have that the mapping $G$ satisfies (11). The rest of the proof is analogous to that of the former.

Finally, let $\varphi(u, v)=\vartheta\left(\|u\|^{s}+\|v\|^{s}\right)$ for all $u, v \in \mathscr{X}$. Then, we yield the following corollary.

Corollary 2. Let $s, \vartheta \in \mathbb{R}_{0}^{+}$with $s<1$. If $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ satisfies $(10)$, then there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\|g(u)-G(u)\| \leqslant \frac{2 \vartheta\|u\|^{s}}{\left(1-\left|t_{1}\right|\right)\left(2-2^{s}\right)}
$$

for all $u \in \mathscr{X}$.

## 3. Stability results: fixed point technique

In this part, we use the fixed point technique to prove the Hyers-Ulam stability of the additive $\left(t_{1}, t_{2}\right)$-functional inequality (1).

THEOREM 4. Let $\varphi: \mathscr{X} \times \mathscr{X} \rightarrow \mathbb{R}_{0}^{+}$be a function such that there exists $L \in \mathbb{R}_{0}^{+}$ with $L<1$ satisfying

$$
\begin{equation*}
\varphi\left(\frac{u}{2}, \frac{v}{2}\right) \leqslant \frac{L}{2} \varphi(u, v) \tag{13}
\end{equation*}
$$

for all $u, v \in \mathscr{X}$. Then, for a mapping $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ satisfying (6), there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\begin{equation*}
\|g(u)-G(u)\| \leqslant \frac{L \varphi(u, u)}{2(1-L)\left(1-\left|t_{1}\right|\right)} \tag{14}
\end{equation*}
$$

for all $u \in \mathscr{X}$.

Proof. We equip the set $\mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ with the generalized metric defined by

$$
d(h, k)=\inf \left\{\beta \in \mathbb{R}^{+}:\|h(u)-k(u)\| \leqslant \beta \varphi(u, u), \text { for all } u \in \mathscr{X}\right\}
$$

where $\inf \emptyset=\infty$ as typical. Then, $\left(\mathscr{M}_{0}(\mathscr{X}, \mathscr{Y}), d\right)$ is complete, in [20]. Define a mapping $\mathscr{T}: \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y}) \rightarrow \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ by

$$
\mathscr{T} h(u):=2 h\left(\frac{u}{2}\right)
$$

for all $u \in \mathscr{X}$. Let $h, k \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ where $d(h, k)=\varepsilon$. Then,

$$
\|h(u)-k(u)\| \leqslant \varepsilon \varphi(u, u)
$$

for all $u \in \mathscr{X}$. Consequently,

$$
\begin{aligned}
\|\mathscr{T} h(u)-\mathscr{T} k(u)\| & =\left\|2 h\left(\frac{u}{2}\right)-2 k\left(\frac{u}{2}\right)\right\| \leqslant 2 \varepsilon \varphi\left(\frac{u}{2}, \frac{u}{2}\right) \\
& \leqslant 2 \varepsilon \frac{L}{2} \varphi(u, u)=\operatorname{L\varepsilon \varphi }(u, u)
\end{aligned}
$$

for all $u \in \mathscr{X}$. Then $d(\mathscr{T} h, \mathscr{T} k) \leqslant L \varepsilon$ which means

$$
d(\mathscr{T} h, \mathscr{T} k) \leqslant L d(h, k)
$$

for all $h, k \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$. It follows from (8) and (13) that

$$
\left\|g(u)-2 g\left(\frac{u}{2}\right)\right\| \leqslant \frac{1}{1-\left|t_{1}\right|} \varphi\left(\frac{u}{2}, \frac{u}{2}\right) \leqslant \frac{L}{2\left(1-\left|t_{1}\right|\right)} \varphi(u, u)
$$

for all $u \in \mathscr{X}$. Thus

$$
d(g, \mathscr{T} g) \leqslant \frac{L}{2\left(1-\left|t_{1}\right|\right)}
$$

From Theorem 1, there exists $G: \mathscr{X} \rightarrow \mathscr{Y}$ satisfying as follows:
(1) $G$ is a unique fixed point of $\mathscr{T}$, i.e.,

$$
G(u)=2 G\left(\frac{u}{2}\right)
$$

for all $u \in \mathscr{X}$. Thus, there exists $\beta \in(0, \infty)$ satisfying

$$
\|g(u)-G(u)\| \leqslant \beta \varphi(u, u)
$$

for all $u \in \mathscr{X}$;
(2) $d\left(\mathscr{T}^{l} g, G\right) \rightarrow 0$ as $l \rightarrow \infty$, which implies that

$$
\lim _{l \rightarrow \infty} 2^{l} g\left(2^{-l} u\right)=G(u)
$$

for all $u \in \mathscr{X}$;
(3) $d(g, G) \leqslant \frac{1}{1-L} d(g, \mathscr{T} g)$, which can be implied that

$$
\|g(u)-G(u)\| \leqslant \frac{L \varphi(u, u)}{2(1-L)\left(1-\left|t_{1}\right|\right)}
$$

for all $u \in \mathscr{X}$. By using the same technique as in the proof of Theorem 2, we can conclude that $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$.

Corollary 3. Let $s, \vartheta \in \mathbb{R}_{0}^{+}$with $s>1$. If $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ satisfies $(10)$, then there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\|g(u)-G(u)\| \leqslant \frac{2 \vartheta\|u\|^{s}}{\left(1-\left|t_{1}\right|\right)\left(2^{s}-2\right)}
$$

for all $u \in \mathscr{X}$.

Proof. The proof follows from Theorem 4 by taking $L=2^{1-s}$ and $\varphi(u, v)=$ $\vartheta\left(\|u\|^{s}+\|v\|^{s}\right)$ for all $u, v \in \mathscr{X}$.

Theorem 5. Let $\varphi: \mathscr{X} \times \mathscr{X} \rightarrow \mathbb{R}_{0}^{+}$be a function such that there exists $L \in \mathbb{R}_{0}^{+}$ with $L<1$ satisfying

$$
\begin{equation*}
\varphi(u, v) \leqslant 2 L \varphi\left(\frac{u}{2}, \frac{v}{2}\right) \tag{15}
\end{equation*}
$$

for all $u, v \in \mathscr{X}$. Then, for a mapping $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ satisfying (6), there is a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\begin{equation*}
\|g(u)-G(u)\| \leqslant \frac{\varphi(u, u)}{2(1-L)\left(1-\left|t_{1}\right|\right)} \tag{16}
\end{equation*}
$$

for all $u \in \mathscr{X}$.
Proof. Regard the complete metric space $\left(\mathscr{M}_{0}(\mathscr{X}, \mathscr{Y}), d\right)$ given as in the proof of Theorem 4 . We consider a mapping $\mathscr{T}: \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y}) \rightarrow \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ defined by

$$
\mathscr{T} h(u):=\frac{1}{2} h(2 u)
$$

for all $u \in \mathscr{X}$. As follows from (8),

$$
\left\|g(u)-\frac{1}{2} g(2 u)\right\| \leqslant \frac{\varphi(u, u)}{2\left(1-\left|t_{1}\right|\right)}
$$

for all $u \in \mathscr{X}$. Also, in the proof of Theorems 2 and 4, there exists a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ satisfying (16).

Let $L=2^{s-1}$ and $\varphi(u, v)=\vartheta\left(\|u\|^{s}+\|v\|^{s}\right)$ for all $u, v \in \mathscr{X}$. The following corollary is obtained.

Corollary 4. Let $s, \vartheta \in \mathbb{R}_{0}^{+}$with $s<1$, and let $g \in \mathscr{M}_{0}(\mathscr{X}, \mathscr{Y})$ be a mapping satisfying (10). Then there exists a unique mapping $G \in \mathscr{A}_{0}(\mathscr{X}, \mathscr{Y})$ such that

$$
\|g(u)-G(u)\| \leqslant \frac{2 \vartheta\|u\|^{s}}{\left(1-\left|t_{1}\right|\right)\left(2-2^{s}\right)}
$$

for all $u \in \mathscr{X}$.

## Conclusion

We have proposed the additive $\left(t_{1}, t_{2}\right)$-functional inequality (1) and have proved the Hyers-Ulam stability of the proposed functional inequality (1) in a complex Banach space.

Conflicts of Interest. The authors declare that there are no conflicts of interest regarding the publication of this paper.

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