

L -OPERATOR INTEGRO-DIFFERENTIAL INEQUALITY FOR DISSIPATIVITY OF STOCHASTIC INTEGRO-DIFFERENTIAL EQUATIONS

LIGUANG XU AND FAJIN QIN

(Communicated by N. Elezović)

Abstract. In this paper, Itô stochastic integro-differential equations are considered. By establishing an L -operator integro-differential inequality and using the properties of M -cone and stochastic analysis technique, we obtain some new sufficient conditions ensuring the exponential p -dissipativity of the stochastic integro-differential equations. An example is also discussed to illustrate the efficiency of the obtained results.

1. Introduction

Integro-differential equations arise widely in scientific fields, where it is necessary to take into account aftereffect or delay such as control theory, biology, ecology, medicine, etc. (cf. [1–4]). Especially, one always describes a model which possesses hereditary properties by integro-differential equations in practice.

Recently, the asymptotic behavior of dynamical systems has been widely studied (for instance, see [5–9]). As is well known, dissipativity is one of the most important components in the theory of asymptotic behavior. It has good application in many areas, such as stability theory, chaos and synchronization theory, system norm estimation and robust control [10]. In particular, delay effect on the dissipativity and other behaviors of integro-differential equations have been attracted the interest of many authors and various results are reported (for instance, see [4, 11–14]). However, besides delay effect, stochastic effect likewise exists in real system. A lot of dynamical systems have variable structures subject to stochastic abrupt changes, which may result from abrupt phenomena such as stochastic failures and repairs of the components, changes in the interconnections of subsystems, sudden environment changes, etc. Many interesting results on stochastic effect have been reported, e.g., see [15–21].

Therefore, it is necessary to consider both stochastic and delay effect on the dissipativity of integro-differential equations. However, to the best of our knowledge, there are no results on the problems of the exponential p -dissipativity of stochastic

Mathematics subject classification (2010): 60H20, 34K50.

Keywords and phrases: Stochastic; P -dissipativity; Integro-differential; L -operator; integro-differential inequality.

The work is supported by National Natural Science Foundation of China under Grant 10971147.

integro-differential equations. This paper presents one such method by establishing an L -operator integro-differential inequality and employing M -cone. Based on the obtained method, we shall give sufficient conditions for the exponential p -dissipativity of a class of stochastic integro-differential equations. An example is given to illustrate the efficiency of the results.

2. Model and preliminaries

To begin with, we introduce some notation and recall some basic definitions. Let I denote the n -dimensional unit matrix, $\mathcal{N} \triangleq \{1, 2, \dots, n\}$, $R_+ = [0, \infty)$. For $A, B \in R^{m \times n}$ or $A, B \in R^n$, $A \geq B (A \leq B, A > B, A < B)$ means that each pair of corresponding elements of A and B satisfies the inequality “ \geq ($\leq, >, <$)”. Especially, A is called a nonnegative matrix if $A \geq 0$, and z is called a positive vector if $z > 0$.

$C[X, Y]$ denote the space of continuous mappings from the topological space X to the topological space Y . In particular, let $C \triangleq C[(-\infty, 0], R^n]$ denote the family of all bounded continuous R^n -valued functions φ defined on $(-\infty, 0]$ with the norm $\|\varphi\| = \sup_{-\infty < \theta \leq 0} |\varphi(\theta)|$, where $|\cdot|$ is Euclidean norm on R^n .

For $x \in R^n$, $\varphi \in C$, $p > 0$, we define

$$\begin{aligned} [x]_+^p &= (|x_1|^p, \dots, |x_n|^p)^T, \quad \text{especially, } [x]_+^1 = (|x_1|, \dots, |x_n|)^T, \\ \text{col}\{x_i\}_n &= \text{col}(x_1, x_2, \dots, x_n), \quad [\varphi(t)]_\infty = ([\varphi_1(t)]_\infty, \dots, [\varphi_n(t)]_\infty)^T, \\ [\varphi(t)]_+^\infty &= [[\varphi(t)]_+^1]_\infty, \quad [\varphi_i(t)]_\infty = \sup_{-\infty < s \leq 0} \{\varphi_i(t+s)\}, \quad i \in \mathcal{N}, \end{aligned}$$

and $D^+ \varphi(t)$ denote the upper right derivative of $\varphi(t)$ at time t .

Let $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq t_0}, P)$ be a complete probability space with a filtration $\{\mathcal{F}_t\}_{t \geq t_0}$ satisfying the usual conditions (i.e., it is right continuous and \mathcal{F}_{t_0} contains all P -null sets). $w(t) = (w_1(t), \dots, w_m(t))^T$ is an m -dimensional Brownian motion defined on $(\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq t_0}, P)$. Let $C_{\mathcal{F}_{t_0}}^b[(-\infty, 0], R^n]$ denote the family of all bounded \mathcal{F}_{t_0} -measurable, $C[(-\infty, 0], R^n]$ -valued random variables φ , satisfying $\|\varphi\|_{L^p}^p = \sup_{-\infty < \theta \leq 0} E|\varphi(\theta)|^p < \infty$, where E denotes the expectation of stochastic process.

In this paper, we consider the following $I\hat{\delta}$ stochastic integro-differential equations:

$$\begin{aligned} dx_i(t) &= \left[-a_i x_i(t) + \sum_{j=1}^n a_{ij} f_j(x_j(t)) + \sum_{j=1}^n \int_{-\infty}^t p_{ij}(t-s) g_j(x_j(s)) ds + J_i \right] dt \\ &+ \sum_{l=1}^m \sigma_{il}(t, x_i(t)) dw_l(t), \quad t \geq t_0, \end{aligned} \tag{1}$$

where $a_i > 0$, $J_i \geq 0$, a_{ij} , $i, j \in \mathcal{N}$ are constants, $f_j, g_j \in C[R, R]$, $j \in \mathcal{N}$; $p_{ij}(t)$, $i, j \in \mathcal{N}$ are continuous and satisfy

$$(H) : \int_0^\infty e^{\lambda_0 t} |p_{ij}(t)| dt < \infty, \quad i, j \in \mathcal{N},$$

in which λ_0 is a positive constant, and $\sigma_i(t, x_i) = (\sigma_{i1}(t, x_i), \dots, \sigma_{im}(t, x_i))$ is i -th row vector of a matrix $\sigma(t, x) = (\sigma_{il}(t, x_i))_{n \times m}$, $\sigma : R \times R^n \rightarrow R^{n \times m}$.

DEFINITION 2.1. For any given $t_0 \in R$, $\varphi \in C^b_{\mathcal{F}_{t_0}} [(-\infty, 0], R^n]$, an R^n -valued stochastic process $x(t)$ is called a solution of (1) on $(-\infty, T]$ through (t_0, φ) , if $x(t)$ has the following properties:

- (1⁰) $x : (-\infty, T] \times \Omega \rightarrow R^n$ is a measurable, sample-continuous process;
- (2⁰) $(x(t), t \in [t_0, T])$ is $(\mathcal{F})_{t_0 \leq t \leq T}$ -adapted, $x(s)$ is \mathcal{F}_{t_0} -measurable for all $s \leq t_0$;
- (3⁰) x satisfies, almost surely, Eq. (1) for $t \geq t_0$ and the initial conditions in the form

$$x(t_0 + s) = \varphi(s), \quad s \in (-\infty, 0]. \tag{2}$$

Throughout this paper, we assume that for any $\varphi \in C^b_{\mathcal{F}_{t_0}} [(-\infty, 0], R^n]$, there exists at least one solution of (1) with the initial condition (2). For conditions guaranteeing the existence of a solution see [22].

DEFINITION 2.2. System (1) is said to be exponentially p -dissipative with exponential convergent rate λ if there is a bounded set $M \subset C^b_{\mathcal{F}_{t_0}} [(-\infty, 0], R^n]$ and a pair of positive constants K, λ such that for any solution $x(t, t_0, \varphi)$ with the initial condition $\varphi \in C^b_{\mathcal{F}_{t_0}} [(-\infty, 0], R^n]$,

$$\text{dist}(E[x(t)]^p_+, M) \leq K \|\varphi\|^p_{L^p} e^{-\lambda(t-t_0)}, \quad t \geq t_0, \tag{3}$$

where

$$\text{dist}(\psi, M) = \inf_{\phi \in M} \sup_{s \in (-\infty, 0]} |\psi(t) - \phi(s)|, \text{ for } \psi \in C[R, R^n],$$

and the set M is called an exponential attracting set of system (1). Especially, system (1) is said to be exponentially dissipative in mean square when $p = 2$.

DEFINITION 2.3. System (1) is said to be exponentially p -stable with exponential convergent rate λ if there is a pair of positive constants λ and K such that for any solution $x(t, t_0, \varphi)$ with the initial condition $\varphi \in C^b_{\mathcal{F}_{t_0}} [(-\infty, 0], R^n]$,

$$E|x(t, t_0, \varphi)|^p \leq K \|\varphi\|^p_{L^p} e^{-\lambda(t-t_0)}, \quad t \geq t_0.$$

Especially, system (1) is said to be exponentially stable in mean square when $p = 2$.

DEFINITION 2.4. [23, p. 114]. Let the matrix $D = (d_{ij})_{n \times n}$, $d_{ii} > 0$ and $d_{ij} \leq 0$, $i \neq j$. Then D is called an M -matrix if one of the following conditions holds:

- (i) all the leading principal minors of D are positive;
- (ii) there exists a positive vector z such that $Dz > 0$;
- (iii) D is inverse positive; that is, D^{-1} exists and $D^{-1} \geq 0$.

LEMMA 2.1. [24] For an M -matrix D , $\Omega_M(D) \triangleq \{z \in R^n \mid Dz > 0, z > 0\}$ is nonempty and for any $z_1, z_2 \in \Omega_M(D)$, we have

$$k_1 z_1 + k_2 z_2 \in \Omega_M(D), \quad \forall k_1, k_2 > 0.$$

So $\Omega_M(D)$ is a cone without conical surface in R^n . We call it an “ M -cone”.

LEMMA 2.2.. (Arithmetic-mean–geometric-mean inequality [25])

For $x_i \geq 0, \alpha_i > 0$ and $\sum_{i=1}^n \alpha_i = 1$,

$$\prod_{i=1}^n x_i^{\alpha_i} \leq \sum_{i=1}^n \alpha_i x_i,$$

the sign of equality holds if and only if $x_i = x_j$ for all $i, j \in \mathcal{N}$.

3. L -operator integro-differential inequality

In this section, we will first establish an integro-differential inequality and then introduce an L -operator integro-differential inequality.

THEOREM 3.1. Let $P = (p_{ij})_{n \times n}$ and $p_{ij} \geq 0$ for $i \neq j, J = (J_1, \dots, J_n)^T \geq 0, Q(t) = (q_{ij}(t))_{n \times n}$, where $q_{ij}(t) \geq 0$ are continuous and satisfy

$$(H_0) : \int_0^\infty e^{\lambda_1 t} q_{ij}(t) dt < \infty, \quad i, j \in \mathcal{N},$$

in which λ_1 is a positive constant. Denote $Q = (q_{ij})_{n \times n} \triangleq (\int_0^\infty q_{ij}(t) dt)_{n \times n}$ and let $D = -(P + Q)$ be a nonsingular M -matrix and $u(t) = (u_1(t), \dots, u_n(t))^T \in C[[t_0, \infty), R^n]$ be a solution of the following integro-differential inequality with the initial condition $u(s) \in C, -\infty < s \leq t_0$

$$D^+ u(t) \leq Pu(t) + \int_0^\infty Q(s)u(t-s)ds + J, \quad t \geq t_0. \tag{4}$$

Then

$$u(t) \leq ze^{-\lambda(t-t_0)} - (P + Q)^{-1}J, \quad t \geq t_0, \tag{5}$$

provided that the initial conditions satisfy

$$u(t) \leq ze^{-\lambda(s-t_0)} - (P + Q)^{-1}J, \quad -\infty < s \leq t_0, \tag{6}$$

where $z = (z_1, z_2, \dots, z_n)^T \in \Omega_M(D)$ and the constant $\lambda \in (0, \lambda_1]$ satisfies the following inequality

$$\left[\lambda I + P + \int_0^\infty Q(s)e^{\lambda s} ds \right] z < 0. \tag{7}$$

Proof. Since D is a nonsingular M -matrix, there exists a vector $z \in \Omega_M(D)$ such that

$$Dz > 0 \text{ or } [P + Q]z < 0.$$

By using continuity and condition (H_0) , we obtain that there must exist a positive constant $\lambda \leq \lambda_1$ satisfying the inequality (7), that is,

$$\sum_{j=1}^n \left[p_{ij} + \int_0^\infty q_{ij}(s)e^{\lambda s} ds \right] z_j < -\lambda z_i, \quad i \in \mathcal{N}. \quad (8)$$

Let $N \triangleq -(P + Q)^{-1}J$, $N = (N_1, \dots, N_n)^T$. One can get that $(P + Q)N + J = 0$ or

$$\sum_{j=1}^n p_{ij}N_j + \sum_{j=1}^n q_{ij}N_j + J_i = 0, \quad i \in \mathcal{N}. \quad (9)$$

To prove (5), we first prove, for any given $\varepsilon > 0$, when $u(s) \leq ze^{-\lambda(s-t_0)} - (P + Q)^{-1}J$, $-\infty < s \leq t_0$,

$$u_i(t) < (1 + \varepsilon)[z_i e^{-\lambda(t-t_0)} + N_i] \triangleq y_i(t), \quad t \geq t_0, \quad i \in \mathcal{N}. \quad (10)$$

If (10) is not true, then there must be a $t_1 > t_0$ and some integer m such that

$$u_m(t_1) = y_m(t_1), \quad D^+ u_m(t_1) \geq y'_m(t_1), \quad (11)$$

$$u_i(t) \leq y_i(t), \quad -\infty < t \leq t_1, \quad i \in \mathcal{N}. \quad (12)$$

By using (4), (8)–(12) and $p_{ij} \geq 0 (i \neq j)$, $q_{ij}(t) \geq 0$, we obtain that

$$\begin{aligned} D^+ u_m(t_1) &\leq \sum_{j=1}^n p_{mj} u_j(t_1) + \sum_{j=1}^n \int_0^\infty q_{mj}(s) u_j(t_1 - s) ds + J_m \\ &\leq \sum_{j=1}^n p_{mj} (1 + \varepsilon) (z_j e^{-\lambda(t_1-t_0)} + N_j) \\ &\quad + \sum_{j=1}^n \int_0^\infty q_{mj}(s) (1 + \varepsilon) (z_j e^{-\lambda(t_1-s-t_0)} + N_j) ds + J_m \\ &= \sum_{j=1}^n \left[p_{mj} + \int_0^\infty q_{mj}(s) e^{\lambda s} ds \right] (1 + \varepsilon) z_j e^{-\lambda(t_1-t_0)} \\ &\quad + \sum_{j=1}^n \left[p_{mj} + \int_0^\infty q_{mj}(s) ds \right] N_j (1 + \varepsilon) + J_m \\ &= \sum_{j=1}^n \left[p_{mj} + \int_0^\infty q_{mj}(s) e^{\lambda s} ds \right] (1 + \varepsilon) z_j e^{-\lambda(t_1-t_0)} - \varepsilon J_m \\ &\leq \sum_{j=1}^n \left[p_{mj} + \int_0^\infty q_{mj}(s) e^{\lambda s} ds \right] (1 + \varepsilon) z_j e^{-\lambda(t_1-t_0)} \\ &< -\lambda z_m (1 + \varepsilon) z_j e^{-\lambda(t_1-t_0)} \\ &= y'_m(t_1), \end{aligned}$$

This contradicts the inequality (11), and so (10) holds. Letting $\varepsilon \rightarrow 0$, then (5) holds, and the proof is completed. \square

REMARK 3.1. Suppose that $J = 0$ in Theorem 3.1, then we get Theorem 1 in [26].

Let $C^{2,1}[R_+ \times R^n, R_+]$ denote the family of all nonnegative functions $V(t, x)$ on $R_+ \times R^n$ which are twice continuously differentiable in x and once in t . For each $V(t, x) \in C^{2,1}[R_+ \times R^n, R_+]$, we define an operator LV from $C^{2,1}[R_+ \times R^n, R_+]$ to $C[R, R]$, associated with the system (1), by

$$LV(t, x) = V_t(t, x) + V_x(t, x)F(t, x) + \frac{1}{2}\text{trace}[\sigma^T(t, x)V_{xx}\sigma(t, x)],$$

$$V_t(t, x) = \frac{\partial V(t, x)}{\partial t}, \quad V_x(t, x) = \left(\frac{\partial V(t, x)}{\partial x_1}, \dots, \frac{\partial V(t, x)}{\partial x_n} \right), \quad V_{xx} = \left(\frac{\partial^2 V(t, x)}{\partial x_i \partial x_j} \right)_{n \times n},$$

where

$$F(t, x) = \text{col}\{-a_i x_i(t) + \sum_{j=1}^n a_{ij} f_j(x_j(t)) + \sum_{j=1}^n \int_{-\infty}^t p_{ij}(t-s)g_j(x_j(s))ds + J_i\}_n.$$

THEOREM 3.2. Let matrices $P, J, Q(t)$ and the condition (H_0) be defined as in Theorem 3.1. Assume that there exist functions $V_i(x) \in C^2[R^n, R_+]$ such that for the operator LV which is associated with the system (1), such that

$$LV_i(x) \leq \sum_{j=1}^n \left(p_{ij} V_j(x) + \int_0^\infty q_{ij}(s) V_j(x(t-s)) ds \right) + J_i, \quad t \geq t_0, \quad i \in \mathcal{N}. \tag{13}$$

Then

$$EV_i(x(t)) \leq z_i e^{-\lambda(t-t_0)} + N_i, \quad t \geq t_0, \quad i \in \mathcal{N}, \tag{14}$$

provided that the initial conditions satisfy

$$EV_i(x(t)) \leq z_i e^{-\lambda(t-t_0)} + N_i, \quad -\infty < t \leq t_0, \quad i \in \mathcal{N}, \tag{15}$$

where $N = (N_1, \dots, N_n)^T = -(P + Q)^{-1}J$, $z = (z_1, z_2, \dots, z_n)^T \in \Omega_M(D)$ and the constant $\lambda \in (0, \lambda_1]$ satisfies the following inequality

$$\left[\lambda I + P + \int_0^\infty Q(s) e^{\lambda s} ds \right] z < 0. \tag{16}$$

Proof. Since $x(t)$ is the solution of the equation (1) and $V_i(x) \in C^2[R^n, R_+]$, by the Itô formula, we can get

$$V_i(x(t)) = V_i(x(t_0)) + \int_{t_0}^t LV_i(x(s)) ds + \int_{t_0}^t \frac{\partial V_i(x(s))}{\partial x} \sigma(s, x(s)) dw(s), \quad t \geq t_0, \quad i \in \mathcal{N}.$$

Then we have

$$EV_i(x(t)) = EV_i(x(t_0)) + \int_{t_0}^t ELV_i(x(s))ds, \quad t \geq t_0, i \in \mathcal{N}. \tag{17}$$

So, for small enough $\Delta t > 0$, we have

$$EV_i(x(t + \Delta t)) = EV_i(x(t_0)) + \int_{t_0}^{t+\Delta t} ELV_i(x(s))ds, \quad t \geq t_0, i \in \mathcal{N}. \tag{18}$$

Thus from (13), (17) and (18), we have

$$\begin{aligned} EV_i(x(t + \Delta t)) - EV_i(x(t)) &= \int_t^{t+\Delta t} ELV_i(x(s))ds \\ &\leq \int_t^{t+\Delta t} \left\{ \sum_{j=1}^n \left[p_{ij}EV_j(x(r)) + \int_0^\infty q_{ij}(s)EV_j(x(r-s))ds \right] + J_i \right\} dr, \quad t \geq t_0, i \in \mathcal{N}. \end{aligned} \tag{19}$$

From (19), we obtain that

$$D^+EV_i(x(t)) \leq \sum_{j=1}^n \left(p_{ij}EV_j(x(t)) + \int_0^\infty q_{ij}(s)EV_j(x(t-s))ds \right) + J_i, \quad t \geq t_0, i \in \mathcal{N}. \tag{20}$$

Since *D* is a nonsingular *M*-matrix, there exists a vector $z \in \Omega_M(D)$ such that

$$Dz > 0 \quad \text{or} \quad [P + Q]z < 0.$$

By using continuity, we obtain that (16) has at least one positive solution λ . Thus from Theorem 3.1, we know Theorem 3.2 is true. \square

4. Exponential *P*-dissipativity

In this section, we will obtain several sufficient conditions ensuring the exponential *p*-dissipativity of stochastic integro-differential equations (1) by employing Theorem 3.2. Here, we first introduce the following assumptions.

(A₁) There exist nonnegative constants u_j, v_j such that for $x_j \in R$,

$$|f_j(x_j)| \leq u_j|x_j|, \quad |g_j(x_j)| \leq v_j|x_j|, \quad j \in \mathcal{N}. \tag{21}$$

(A₂) There exist nonnegative constants \hat{c}_i such that for $x_i \in R$,

$$|(\sigma_i(t, x_i))^T (\sigma_i(t, x_i))| \leq \hat{c}_i|x_i|^2, \quad i \in \mathcal{N}.$$

(A₃) Let $\bar{D} = -(\hat{A} + \hat{B})$ be an M -matrix, where

$$\begin{aligned} \hat{A} &= (\hat{a}_{ij})_{n \times n}, \hat{a}_{ij} = |a_{ij}u_j|, i \neq j, \\ \hat{a}_{ii} &= -pa_i + \sum_{j=1}^n |a_{ij}u_j|(p-1) + \sum_{j=1}^n \int_0^\infty |p_{ij}(s)|v_j(p-1)ds + (p-1) \\ &\quad + \frac{1}{2}p(p-1)\hat{c}_i + |a_{ii}u_i|, \\ \hat{B} &= (\hat{b}_{ij})_{n \times n} \triangleq \left(\int_0^\infty \hat{b}_{ij}(t)dt \right)_{n \times n}, \hat{b}_{ij}(t) = |p_{ij}(t)|v_j, i, j \in \mathcal{N}. \end{aligned}$$

THEOREM 4.1. *Assume that the hypothesis (H) and the conditions (A₁)–(A₃) hold. Then the system (1) is exponentially p -dissipative with the exponential convergent rate λ which is determined by (22), and the exponential attracting set*

$$M = \left\{ \phi \in C^b_{\mathcal{F}_0} [(-\infty, 0], \mathbb{R}^n] \mid [\phi]_+^\infty \leq (-\hat{A} - \hat{B})^{-1} \hat{J} \right\},$$

where $\hat{J} = (\hat{J}_1, \dots, \hat{J}_n)^T$ and $\hat{J}_i = J_i^p, i \in \mathcal{N}$.

Proof. Since $\bar{D} = -(\hat{A} + \hat{B})$ is a nonsingular M -matrix, there exists a vector $z \in \Omega_M(\bar{D})$ such that

$$\bar{D}z > 0 \quad \text{or} \quad (\hat{A} + \hat{B})z < 0.$$

By using continuity and hypothesis (H), we obtain that there must exist a positive constant $\lambda \leq \lambda_0$ satisfying the following inequality

$$\left[\lambda I + \hat{A} + \int_0^\infty \hat{B}(s)e^{\lambda s} ds \right] z < 0. \tag{22}$$

Let $\hat{N} \triangleq -(\hat{A} + \hat{B})^{-1} \hat{J}$, $\hat{N} = (\hat{N}_1, \dots, \hat{N}_n)^T$. Then from the definition of M -matrix, we have

$$\hat{N} \geq 0 \quad \text{or} \quad \hat{N}_i \geq 0, \quad i \in \mathcal{N}. \tag{23}$$

Let $V_i(x(t)) = |x_i(t)|^p, i \in \mathcal{N}$, where $x(t) = (x_1(t), \dots, x_n(t))^T$ is the solution of (1). Then

$$\frac{\partial V_i(x)}{\partial x_i} = p|x_i|^{p-1} \text{sgn}(x_i) = p|x_i|^{(p-2)}x_i, \quad \frac{\partial V_i^2(x)}{\partial x_i^2} = p(p-1)|x_i|^{(p-2)} \text{sgn}(x_i),$$

where $\text{sgn}(\cdot)$ is the sign function. Thus, by the conditions $(A_1), (A_2)$ and Lemma 2.2, we have

$$\begin{aligned}
 & LV_i(x(t)) \\
 &= p|x_i(t)|^{(p-2)}x_i(t) \left[-a_i x_i(t) + \sum_{j=1}^n a_{ij} f_j(x_j(t)) + \sum_{j=1}^n \int_{-\infty}^t p_{ij}(t-s) g_j(x_j(s)) ds + J_i \right] \\
 &\quad + \frac{1}{2} p(p-1) |x_i(t)|^{p-2} \text{sgn}(x_i(t)) \sigma_i^T(t, x_i(t)) \sigma_i(t, x_i(t)) \\
 &\leq -pa_i |x_i(t)|^p + p|x_i(t)|^{(p-1)} \left[\sum_{j=1}^n |a_{ij} u_j| |x_j(t)| + \sum_{j=1}^n \int_{-\infty}^t |p_{ij}(t-s)| v_j |x_j(s)| ds + J_i \right] \\
 &\quad + \frac{1}{2} p(p-1) |x_i(t)|^{p-2} |\sigma_i^T(t, x_i(t)) \sigma_i(t, x_i(t))| \\
 &\leq -pa_i |x_i(t)|^p + p|x_i(t)|^{(p-1)} \left[\sum_{j=1}^n |a_{ij} u_j| |x_j(t)| + \sum_{j=1}^n \int_0^\infty |p_{ij}(s)| v_j |x_j(t-s)| ds + J_i \right] \\
 &\quad + \frac{1}{2} p(p-1) \hat{c}_i |x_i(t)|^p \\
 &\leq -pa_i |x_i(t)|^p + \sum_{j=1}^n |a_{ij} u_j| [(p-1)|x_i(t)|^p + |x_j(t)|^p] \\
 &\quad + \sum_{j=1}^n \int_0^\infty |p_{ij}(s)| v_j [(p-1)|x_i(t)|^p + |x_j(t-s)|^p] ds \\
 &\quad + (p-1) |x_i(t)|^p + J_i^p + \frac{1}{2} p(p-1) \hat{c}_i |x_i(t)|^p \\
 &= \left[-pa_i + \sum_{j=1}^n |a_{ij} u_j| (p-1) + \sum_{j=1}^n \int_0^\infty |p_{ij}(s)| v_j (p-1) ds + (p-1) + \frac{1}{2} p(p-1) \hat{c}_i \right] |x_i(t)|^p \\
 &\quad + \sum_{j=1}^n |a_{ij} u_j| |x_j(t)|^p + \sum_{j=1}^n \int_0^\infty |p_{ij}(s)| v_j |x_j(t-s)|^p ds + J_i^p \\
 &= \sum_{j=1}^n \hat{a}_{ij} V_j(x) + \sum_{j=1}^n \int_0^\infty \hat{b}_{ij}(s) V_j(x(t-s)) ds + \hat{J}_i. \tag{24}
 \end{aligned}$$

So from the condition (A_3) , we know that the inequality (13) holds. For the initial condition $\varphi \in C_{\mathcal{F}_0}^b [(-\infty, 0], R^n]$, we can get

$$EV_i(x(t)) \leq h z_i \|\varphi\|_{L^p}^p e^{-\lambda(t-t_0)} \leq h z_i \|\varphi\|_{L^p}^p e^{-\lambda(t-t_0)} + \hat{N}_i, \quad t \in (-\infty, t_0], \quad i \in \mathcal{N}, \tag{25}$$

where, $h = \frac{1}{\min_{1 \leq i \leq n} \{z_i\}}$, $z = (z_1, \dots, z_n)^T \in \Omega_M(\bar{D})$ and λ satisfies (22).

From Lemma 2.1 and $z = (z_1, \dots, z_n)^T \in \Omega_M(\bar{D})$, we have $h \|\varphi\|_{L^p}^p z \in \Omega_M(\bar{D})$. Then, all conditions of Theorem 3.2 are satisfied by (24), (25) and (A_3) , so

$$EV_i(x(t)) \leq h z_i \|\varphi\|_{L^p}^p e^{-\lambda(t-t_0)} + \hat{N}_i, \quad t \in [t_0, \infty), \quad i \in \mathcal{N}, \tag{26}$$

that is

$$E[x(t)]_+^p \leq h \|\varphi\|_{L^p}^p z e^{-\lambda(t-t_0)} - (\hat{A} + \hat{B})^{-1} \hat{f}, t \in [t_0, \infty). \tag{27}$$

This implies that the conclusion holds and the proof is completed. \square

COROLLARY 4.1. *Assume that the hypothesis (H) and the conditions (A₁)–(A₃) hold. Then the system (1) with J = 0 is exponentially p-stable with exponential convergent rate λ .*

5. Example

The following illustrative example will demonstrate the effectiveness of our results.

EXAMPLE 5.1. Consider the following stochastic integro-differential equations:

$$\begin{cases} dx_1(t) = \left[-10x_1(t) + (|x_1(t) + 1| - |x_1(t) - 1|) - \int_{-\infty}^t e^{-(t-s)} |x_1(s)| ds \right. \\ \qquad \qquad \qquad \left. + \int_{-\infty}^t 4e^{-2(t-s)} |x_2(s)| ds + 7 \right] dt + 2x_1(t) dw_1(t), \\ dx_2(t) = \left[-8x_2(t) + (|x_2(t) + 1| - |x_2(t) - 1|) - \int_{-\infty}^t 6e^{-2(t-s)} |x_1(s)| ds \right. \\ \qquad \qquad \qquad \left. + \int_{-\infty}^t e^{-(t-s)} |x_2(s)| ds + 8 \right] dt + x_2(t) dw_2(t). \end{cases} \tag{28}$$

For system (28), we have

$$f_i(x_i) = |x_i(t) + 1| - |x_i(t) - 1|, \quad g_i(x_i) = |x_i(t)|, \quad i = 1, 2, \\ \sigma(t, x) = \text{diag} \{2x_1(t), x_2(t)\}.$$

and

$$|f_i(x_i)| \leq 2|x_i|, \quad |g_i(x_i)| \leq |x_i|, \quad i = 1, 2, \\ |\sigma_1(t, x_1)\sigma_1(t, x_1)^T| \leq 4|x_1(t)|^2, \quad |\sigma_2(t, x_2)\sigma_2(t, x_2)^T| \leq |x_2(t)|^2.$$

So, it is easy to check that the conditions (A₁) - (A₃) are satisfied by taking $a_1 = 10, a_2 = 8, p = 2, J_1 = 7, J_2 = 8, a_{11} = a_{22} = 1, a_{12} = a_{21} = 0, u_1 = u_2 = 2, v_1 = v_2 = 1, \hat{c}_1 = 4, \hat{c}_2 = 1, p_{11}(s) = -e^{-s}, p_{12}(s) = 4e^{-2s}, p_{21}(s) = -6e^{-2s}, p_{22}(s) = e^{-s}$.

Then

$$\hat{A} = \begin{pmatrix} -8 & 0 \\ 0 & -6 \end{pmatrix}, \quad \hat{B} = \begin{pmatrix} 1 & 2 \\ 3 & 1 \end{pmatrix}, \quad \bar{D} = -(\hat{A} + \hat{B}) = \begin{pmatrix} 7 & -2 \\ -3 & 5 \end{pmatrix},$$

and (H) is satisfied with $0 < \lambda_0 < 1$. In this example, we may let $\lambda_0 = 0.8$. It is easy to prove that \bar{D} is an M-matrix and

$$\Omega_M(\bar{D}) = \left\{ (z_1, z_2)^T > 0 \mid \frac{2}{7}z_2 < z_1 < \frac{5}{3}z_2 \right\}.$$

Clearly, all the conditions of the Theorem 4.1 are satisfied, so system (28) is exponentially dissipative in mean square.

In order to determine the exponential convergent rate λ , we choose $z^* = (1, 2)^T \in \Omega_M(\bar{D})$. From (22), that is,

$$\left[\lambda I + \hat{A} + \int_0^\infty \hat{B}(s)e^{\lambda s} ds \right] z^* < 0,$$

we obtain $\lambda = 0.5 < 0.8$.

Acknowledgements. The authors are very grateful to the referees for their helpful comments. The authors also thank Professor Daoyi Xu (Sichuan University) for his helpful suggestions.

REFERENCES

- [1] K. GOPALSAMY, *Stability and Oscillations in Delay Differential Equations of Population Dynamics*, Kluwer Academic Publishers, Dordrecht, 1992.
- [2] J. K. HALE, *Theory of Functional Differential Equations*, Springer, New York, 1977.
- [3] V. B. KOLMANOVSKII, A. MYSHKIS, *Applied Theory of Functional Differential Equations*, Kluwer Academic Publishers, Dordrecht, 1992.
- [4] D. Y. XU, *Integro-differential equations and delay integral inequalities*, Tohoku Math. J., **44** (1992), 365–378.
- [5] H. Y. ZHAO, *Invariant set and attractor of nonautonomous functional differential systems*, J. Math. Anal. Appl., **282** (2003), 437–443.
- [6] D. Y. XU, H. Y. ZHAO, *Invariant set and attractivity of nonlinear differential equations with delays*, Appl. Math. Lett., **15** (2002), 321–325.
- [7] Y. M. HUANG, D. Y. XU, Z. C. YANG, *Dissipativity and periodic attractor for non-autonomous neural networks with time-varying delays*, Neurocomputing, **70** (2007), 2953–2958.
- [8] L. S. WANG, D. Y. XU, *Asymptotic behavior of a class of reaction-diffusion equations with delays*, J. Math. Anal. Appl., **281** (2003), 439–453.
- [9] Y. J. WANG, D. S. LI, P. E. KLOEDEN, *On the asymptotical behavior of nonautonomous dynamical systems*, Nonlinear Anal., **59** (2004), 35–53.
- [10] X. X. LIAO, J. WANG, *Global dissipativity of continuous-time recurrent neural networks with time delay*, Phys. Rev. E, **68** (2003), 1–7.
- [11] I.-G. E. KORDONIS, CH. G. PHILOS, *The behavior of solutions of linear integro-differential equations with unbounded delay*, Comput. Math. Appl., **38** (1999), 45–50.
- [12] X. Y. LOU, B. T. CUI, *Global robust dissipativity for integro-differential systems modeling neural networks with delays*, Chaos, Solitons & Fractals, **36** (2008), 469–478.
- [13] Q. K. SONG, Z. J. ZHAO, *Global dissipativity of neural networks with both variable and unbounded delays*, Chaos, Solitons & Fractals, **25** (2005), 393–401.
- [14] T. JANKOWSKI, *Delay integro-differential inequalities with initial time difference and applications*, J. Math. Anal. Appl., **291** (2004), 605–624.
- [15] X. R. MAO, M. RIEDLE, *Mean square stability of stochastic Volterra integro-differential equations*, Systems & Control Letters, **55** (2006), 459–465.
- [16] M. JOVANOVIĆ, S. JANKOVIĆ, *On perturbed nonlinear Itô type stochastic integrodifferential equations*, J. Math. Anal. Appl., **269** (2002), 301–316.
- [17] X. R. MAO, *Stochastic Differential Equations and Applications*, Horwood Publishing, 1997.
- [18] S.-E. A. MOHAMMED, *Stochastic Functional Differential Equations*, Longman, New York, 1986.
- [19] B. L. S. PRAKASA RAO, *Absolute stability of a stochastic integro-differential system*, J. Math. Anal. Appl., **54** (1976), 666–673.
- [20] K. BALACHANDRAN, S. KARTHIKEYAN, *Controllability of stochastic integrodifferential systems*, Int. J. Control, **80** (2007), 486–491.

- [21] A. RATHINASAMY, K. BALACHANDRAN, *Mean-square stability of Milstein method for linear hybrid stochastic delay integro-differential equations*, *Nonlinear Anal.: HS* (2008), doi:10.1016/j.nahs.2008.09.015.
- [22] F. Y. WEI, K. WANG, *The existence and uniqueness of the solution for stochastic functional differential equations with infinite delay*, *J. Math. Anal. Appl.*, **331** (2007), 516–531.
- [23] R. A. HORN, C. R. JOHNSON, *Topics in Matrix Analysis*, vol. 2, Cambridge Univ. Press, England, 1991.
- [24] Z. G. YANG, D. Y. XU, L. XIANG, *Exponential p -stability of impulsive stochastic differential equations with delays*, *Phys. Lett. A*, **359** (2006), 129–137.
- [25] E. BECKENBACH, R. BELLMAN, *Inequalities*, Springer-Verlag, New York, 1961.
- [26] D. Y. XU, W. ZHU, S. J. LONG, *Global exponential stability of impulsive integro-differential equation*, *Nonlinear Anal.*, **64** (2006), 2805–2816.

(Received November 14, 2008)

Liguang Xu
Department of Applied Mathematics
Zhejiang University of Technology
Hangzhou, 310023, PR China
e-mail: xlg132@126.com

Fajin Qin
Department of Mathematics and Computer Science
Liuzhou Teachers College
Liuzhou, 545004, PR China
e-mail: qinfajin@126.com