HERMITE-HADAMARD INEQUALITY FOR A FRUSTUM OF A SIMPLEX

MONIKA NOWICKA AND ALFRED WITKOWSKI*

Dedicated to Academician Josip Pečarić on the occasion of his 70th birthday

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Abstract. In this paper, we establish a refinement of the Hermite-Hadamard inequality for convex functions of several variables defined on a frustum of a simplex.

1. Introduction

Let $f \colon [a,b] \to \mathbb{R}$ be a convex function, then the inequality

$$f\left(\frac{a+b}{2}\right) \leqslant \frac{1}{b-a} \int_{a}^{b} f(t) \, \mathrm{d}t \leqslant \frac{f(a)+f(b)}{2} \tag{1.1}$$

is known as the Hermite-Hadamard inequality. The paper [1] gives some generalization of (1.1). It says that if $\Delta \subset \mathbb{R}^n$ is a simplex with barycenter b_Δ and vertices x_0, \ldots, x_n and $f \colon \Delta \to \mathbb{R}$ is convex, then

$$f(b_{\Delta}) \leqslant \frac{1}{\operatorname{Vol}\Delta} \int_{\Delta} f(x) \, \mathrm{d}x \leqslant \frac{f(x_0) + \ldots + f(x_n)}{n+1},$$
 (1.2)

where Vol Δ denotes the volume of Δ .

The Hermite-Hadamard inequality has been extended to many other convex (and not only convex) bodies. For more details see the monograph [3], paper [5] and the references therein. In this paper we establish two types of Hermite-Hadamard inequality for a frustum of a simplex.

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^{*} Corresponding author.

2. Definitions and notations

We begin with some definitions and notations. For $x_0, ..., x_n \in \mathbb{R}^n$ in general position the set $\Delta = \text{conv}\{x_0, ..., x_n\}$ is called a *simplex*. Every point $x \in \Delta$ admits a unique representation of the form

$$x = \alpha_0 x_0 + \ldots + \alpha_n x_n$$
, $\alpha_i \geqslant 0$, $\alpha_0 + \ldots + \alpha_n = 1$.

The coefficients $(\alpha_0, \dots, \alpha_n)$ are called *barycentric coordinates* of x. The point

$$b_{\Delta} = \frac{1}{n+1}(x_0 + \ldots + x_n)$$

is called the *barycenter* of Δ .

Define a one-to-one mapping from the standard simplex $E_n = \{(\alpha_1, \dots, \alpha_n) : \alpha_i \ge 0, \ \alpha_1 + \dots + \alpha_n \le 1\}$ to Δ given by

$$\varphi(\alpha_1,\ldots,\alpha_n)=(1-\alpha_1-\ldots-\alpha_n)x_0+\alpha_1x_1+\ldots+\alpha_nx_n.$$

The following lemma holds.

LEMMA 2.1. If $f: \Delta \to \mathbb{R}$ is a Riemann-integrable function, then

$$\frac{1}{\operatorname{Vol}\Delta}\int_{\Delta}f(x)\,\mathrm{d}x = n!\int_{E_n}f(\varphi(\alpha))\,\mathrm{d}\alpha.$$

Proof. It is easy to see that the absolute value of the Jacobi determinant of φ equals $n! \operatorname{Vol} \Delta$ and the lemma follows from the change of variables formula. \square

Without loss of generality we assume $x_0 = 0$. For $0 < t \le 1$ let $\Delta_t = \text{conv}\{tx_1, \dots, tx_n\}$. Given $0 < A < B \le 1$ we shall call a *frustum of a simplex* the set $\Delta_{AB} = \text{conv}(\Delta_A \cup \Delta_B) = \bigcup_{A \le t \le B} \Delta_t$. The sets Δ_A and Δ_B will be called the *upper* and *lower bases* of a frustum, and the point x_0 its *apex*. If $\Sigma \subset \mathbb{R}^k$ and $f : \Sigma \to \mathbb{R}$ is a Riemann-integrable function, then by

$$\operatorname{Avg}(f,\Sigma) = \frac{1}{\operatorname{Vol}\Sigma} \int_{\Sigma} f(x) \, \mathrm{d}x$$

we shall denote its average value over Σ .

Let us recall some inequalities.

THEOREM 2.1. (Chebyshev's inequality, see [2]) If $f,g:[a,b] \to \mathbb{R}$ are two monotonic functions of the opposite monotonicity, then

$$\frac{1}{b-a} \int_a^b f(x)g(x) \, \mathrm{d}x \leqslant \left(\frac{1}{b-a} \int_a^b f(x) \, \mathrm{d}x\right) \left(\frac{1}{b-a} \int_a^b g(x) \, \mathrm{d}x\right).$$

If f and g are of the same monotonicity, then the above inequality works in the reverse way.

THEOREM 2.2. (Steffensen's inequality, see [7]) Let $f,g:[a,b]\to\mathbb{R}$ be integrable functions such that f is decreasing and $0 \le g(x) \le 1$ for $x \in [a,b]$. Then

$$\int_{b-\lambda}^{b} f(x) \, \mathrm{d}x \leqslant \int_{a}^{b} f(x) g(x) \, \mathrm{d}x \leqslant \int_{a}^{a+\lambda} f(x) \, \mathrm{d}x,$$

where $\lambda = \int_a^b g(x) dx$.

THEOREM 2.3. (Grüss' inequality, see [4]) Let $f,g:[a,b]\to\mathbb{R}$ be integrable functions such that $\phi\leqslant f(x)\leqslant\Phi$, $\gamma\leqslant g(x)\leqslant\Gamma$, for all $x\in[a,b]$, where $\phi,\Phi,\gamma,\Gamma\in\mathbb{R}$. Then

$$\left|\frac{1}{b-a}\int_a^b f(x)g(x)\,\mathrm{d}x - \frac{1}{(b-a)^2}\int_a^b f(x)\,\mathrm{d}x\int_a^b g(x)\,\mathrm{d}x\right| \leqslant \frac{(\Phi-\phi)(\Gamma-\gamma)}{4}.$$

THEOREM 2.4. (see [6]) Let f and g be real-valued, nonnegative and convex functions on [a,b]. Then

$$2f\left(\frac{a+b}{2}\right)g\left(\frac{a+b}{2}\right) - \frac{1}{6}M(a,b) - \frac{1}{3}N(a,b) \leqslant \frac{1}{b-a}\int_a^b f(x)g(x)\,\mathrm{d}x$$
$$\leqslant \frac{1}{3}M(a,b) + \frac{1}{6}N(a,b),$$

where M(a,b) = f(a)g(a) + f(b)g(b), N(a,b) = f(a)g(b) + f(b)g(a).

3. Bounds by averages over upper and lower bases

The main theorem of this section is the following.

THEOREM 3.1. *If* $f: \Delta_{AB} \to \mathbb{R}$ *is convex, then*

$$\operatorname{Avg}(f, \Delta_{AB}) \leq \alpha \operatorname{Avg}(f, \Delta_A) + (1 - \alpha) \operatorname{Avg}(f, \Delta_B),$$

where $\alpha = \frac{1}{n+1} \frac{B}{B-A} - \frac{n}{n+1} \frac{A^n}{B^n - A^n}$.

Proof. Of course

$$Vol \Delta_t = t^{n-1} Vol \Delta_1 \text{ and } Vol \Delta_{AB} = (B^n - A^n) Vol \Delta.$$
 (3.1)

For every point $x \in \Delta_{AB}$ the line passing through x_0 and x meets Δ_1 at the point $x_\alpha = \sum_{i=1}^n \alpha_i x_i$ and the bases of Δ_{AB} at points $A_\alpha = A x_\alpha$ and $B_\alpha = B x_\alpha$ respectively. So x is a convex combination of A_α and A_α that can be uniquely written as

$$x = tx_{\alpha} = \frac{B - t}{B - A}A_{\alpha} + \frac{t - A}{B - A}B_{\alpha},$$

or equivalently

$$x = tx_{\alpha} = t(\alpha_1x_1 + \ldots + \alpha_{n-1}x_{n-1} + (1 - \alpha_1 - \ldots - \alpha_{n-1})x_n),$$

where $A \leq t \leq B$, $\alpha_1, \dots, \alpha_{n-1} > 0$ and $\alpha_1 + \dots + \alpha_{n-1} \leq 1$.

Consider the mapping $\Phi: [A,B] \times E_{n-1} \to \Delta_{AB}$ given by the formula $\Phi(t,\alpha) = tx_{\alpha}$. The absolute value of its Jacobi determinant equals

$$\begin{vmatrix} x_n + \sum_{i=1}^{n-1} \alpha_i(x_i - x_n) \\ t(x_1 - x_n) \\ \vdots \\ t(x_{n-1} - x_n) \end{vmatrix} = t^{n-1} \begin{vmatrix} x_n \\ x_1 - x_n \\ \vdots \\ x_{n-1} - x_n \end{vmatrix} = t^{n-1} \begin{vmatrix} x_n \\ x_1 \\ \vdots \\ x_{n-1} \end{vmatrix} = n!t^{n-1} \operatorname{Vol} \Delta. \quad (3.2)$$

Using formula (3.2), the convexity of f and Lemma 2.1 we obtain

$$\frac{1}{n! \operatorname{Vol}\Delta} \int_{\Delta_{AB}} f(x) \, \mathrm{d}x = \int_{A}^{B} \int_{E_{n-1}} f\left(\frac{B-t}{B-A}A_{\alpha} + \frac{t-A}{B-A}B_{\alpha}\right) t^{n-1} \, \mathrm{d}\alpha \, \mathrm{d}t \\
\leqslant \frac{1}{B-A} \int_{A}^{B} (B-t)t^{n-1} \, \mathrm{d}t \int_{E_{n-1}} f(A_{\alpha}) \, \mathrm{d}\alpha \\
+ \frac{1}{B-A} \int_{A}^{B} (t-A)t^{n-1} \, \mathrm{d}t \int_{E_{n-1}} f(B_{\alpha}) \, \mathrm{d}\alpha \\
= \frac{B(B^{n}-A^{n}) - n(B-A)A^{n}}{n(n+1)(B-A)} \cdot \frac{1}{(n-1)! \operatorname{Vol}\Delta_{A}} \int_{\Delta_{A}} f(x) \, \mathrm{d}x \\
+ \frac{n(B-A)B^{n} - A(B^{n}-A^{n})}{n(n+1)(B-A)} \cdot \frac{1}{(n-1)! \operatorname{Vol}\Delta_{B}} \int_{\Delta_{B}} f(x) \, \mathrm{d}x. \tag{3.3}$$

We complete the proof by dividing both sides of (3.3) by $B^n - A^n$ and taking into account (3.1). \square

Setting n = 2 we obtain the result below.

COROLLARY 3.1. If PQRS is a trapezoid with $PQ \parallel RS$, |PQ| = p, |RS| = r and f is a convex function, then

$$\begin{split} \operatorname{Avg}(f, PQRS) \leqslant \frac{1}{3} \left\{ \frac{2p+r}{p+r} \operatorname{Avg}(f, PQ) + \frac{p+2r}{p+r} \operatorname{Avg}(f, RS) \right\} \\ \leqslant \frac{1}{6} \left\{ \frac{2p+r}{p+r} (f(P) + f(Q)) + \frac{p+2r}{p+r} (f(R) + f(S)) \right\}. \end{split}$$

4. Bounds by values on certain line segments

In this section we apply the Hermite-Hadamard inequalities to the sections of a frustum by hyperplanes parallel to its bases (that are also simplices). Applying (1.2) to Δ_f , we obtain

$$f(b_{\Delta_t}) \leqslant \operatorname{Avg}(f, \Delta_t) \leqslant \frac{1}{n} \sum_{i=1}^n f(tx_i).$$
 (4.1)

Multiplying both sides of (4.1) by $\frac{\text{Vol}\,\Delta_I}{\text{Vol}\,\Delta_{AB}}$, integrating the resulting inequality over [A,B], using (3.1) and taking into account that $\text{Vol}\,\Delta = \frac{1}{n}h\,\text{Vol}\,\Delta_1$, where h is the height of the simplex Δ from the apex x_0 , we have

$$\frac{n}{(B^{n} - A^{n})h} \int_{A}^{B} t^{n-1} f(b_{\Delta_{t}}) dt \leqslant \frac{\int_{A}^{B} \int_{\Delta_{t}} f(x) dx dt}{\text{Vol} \Delta_{AB}} \leqslant \frac{1}{(B^{n} - A^{n})h} \sum_{i=1}^{n} \int_{A}^{B} t^{n-1} f(tx_{i}) dt.$$
(4.2)

Multiplying both sides of (4.2) by h, we get

$$\frac{n}{(B^n - A^n)} \int_A^B t^{n-1} f(b_{\Delta_t}) dt \leqslant \operatorname{Avg}(f, \Delta_{AB}) \leqslant \frac{1}{B^n - A^n} \sum_{i=1}^n \int_A^B t^{n-1} f(tx_i) dt. \tag{4.3}$$

The factor t^{n-1} in both extreme integrals does not allow for a simple estimation of both sides by the mean values of f at the edges or on the line segment joining the barycenters of the bases. However under some additional assumptions on f we can obtain new upper bounds for the average value of f over the frustum of the simplex. In what follows the symbol Ax_iBx_i denotes the line segment between Ax_i and Bx_i .

COROLLARY 4.1. Let f be a convex function defined on a simplex $\Delta = \text{conv}\{x_0 = 0, x_1, \dots, x_n\}$. If additionally $f(tx_i)$ is a decreasing function for $t \in [A, B], i = 1, \dots, n$, then

$$\operatorname{Avg}(f, \Delta_{AB}) \leqslant \frac{1}{n} \sum_{i=1}^{n} \operatorname{Avg}(f, Ax_i Bx_i). \tag{4.4}$$

Proof. Applying Chebyshev's inequality (Theorem 2.1) to the right-hand side of (4.3), we obtain

$$\operatorname{Avg}(f, \Delta_{AB}) \leqslant \frac{1}{(B-A)n} \sum_{i=1}^{n} \int_{A}^{B} f(tx_i) \, \mathrm{d}t. \tag{4.5}$$

Note that

$$dt = \frac{(B-A)ds_i}{|Ax_iBx_i|},\tag{4.6}$$

where ds_i is an element of length of the *i*-th edge. From (4.5) and (4.6) we obtain (4.4). \square

COROLLARY 4.2. Under the assumptions of Corollary 4.1, we have

$$\operatorname{Avg}(f, \Delta_{AB}) \leqslant \frac{1}{n} \sum_{i=1}^{n} \operatorname{Avg}(f, Ax_i Cx_i),$$

where $C = A + \frac{B^n - A^n}{nB^{n-1}}$.

Proof. The result follows from the Steffensen's inequality (Theorem 2.2) applied to (4.3) with $g(t) = (t/B)^{n-1}$. \Box The Grüss inequality (Theorem 2.3) leads to.

COROLLARY 4.3. Let f be a convex function defined on a simplex Δ with vertices $x_0 = 0, x_1, \ldots, x_n$. Then if $\varphi_i \leqslant f(tx_i) \leqslant \Phi_i$ for all $t \in [A, B]$ and $i = 1, \ldots, n$, then

$$\operatorname{Avg}(f, \Delta_{AB}) \leqslant \sum_{i=1}^{n} \left(\frac{(\Phi_{i} - \varphi_{i})(B^{n-1} - A^{n-1})(B - A)}{4(B^{n} - A^{n})} + \frac{1}{n} \operatorname{Avg}(f, Ax_{i}Bx_{i}) \right).$$

And finally by Theorem 2.4 we deduce the following result.

COROLLARY 4.4. Let $f: \Delta = \text{conv}\{x_0 = 0, x_1, \dots, x_n\} \to \mathbb{R}$ be a convex function which is nonnegative on the line segment $Ax_iBx_i, i = 1, \dots, n$. Under those conditions the following inequality is valid

$$\operatorname{Avg}(f, \Delta_{AB}) \leqslant \frac{(B-A)(2A^{n-1}+B^{n-1})}{6(B^n-A^n)} \sum_{i=1}^n f(Ax_i) + \frac{(B-A)(A^{n-1}+2B^{n-1})}{6(B^n-A^n)} \sum_{i=1}^n f(Bx_i).$$

We can use similar mechanisms to obtain the left-hand side bounds. The Chebyshev inequality gives.

COROLLARY 4.5. Let f be a convex function defined on a simplex $\Delta = \text{conv}\{x_0 = 0, x_1, \dots, x_n\}$. If the function $t \mapsto f(tb_{\Delta_1})$ increases for $t \in [A, B]$, then

$$\operatorname{Avg}(f, b_{\Delta_A} b_{\Delta_B}) \leqslant \operatorname{Avg}(f, \Delta_{AB}).$$

Applying the Steffensen inequality to the left-hand side of (4.3) we get the following.

COROLLARY 4.6. Let f be a convex function defined on a simplex $\Delta = \text{conv}\{x_0 = 0, x_1, \dots, x_n\}$. If the function $t \mapsto f(tb_{\Delta_1})$ decreases for $t \in [A, B]$, then

$$\operatorname{Avg}(f, b_{\Delta_D} b_{\Delta_B}) \leqslant \operatorname{Avg}(f, \Delta_{AB}),$$

where $D = B - \frac{B^n - A^n}{nB^{n-1}}$.

COROLLARY 4.7. Let f be a convex function defined on a simplex $\Delta = \text{conv}\{x_0 = 0, x_1, \dots, x_n\}$ such that $\varphi \leqslant f(tb_{\Delta_1}) \leqslant \Phi$ for all $t \in [A, B]$, then

$$\operatorname{Avg}\left(f,b_{\Delta_{A}}b_{\Delta_{B}}\right)-\frac{n(\Phi-\varphi)(B^{n-1}-A^{n-1})(B-A)}{4(B^{n}-A^{n})}\leqslant\operatorname{Avg}(f,\Delta_{AB})$$

holds.

Theorem 2.4 applied to the left-hand side of (4.3) gives the following.

COROLLARY 4.8. Let f be a convex function defined on a simplex $\Delta = \text{conv}\{x_0 = 0, x_1, \dots, x_n\}$. Moreover, let f be a nonnegative function on the line segment $b_{\Delta_A}b_{\Delta_B}$. Then

$$\frac{n(B-A)}{B^{n}-A^{n}}\left[2f\left(b_{\Delta_{\underline{A}+\underline{B}}}\right)\left(\frac{A+B}{2}\right)^{n-1}-\frac{A^{n-1}+2B^{n-1}}{6}f\left(b_{\Delta_{A}}\right)\right.\\ \left.\left.-\frac{2A^{n-1}+B^{n-1}}{6}f\left(b_{\Delta_{B}}\right)\right]\right]\\ \leqslant \operatorname{Avg}(f,\Delta_{AB}).$$

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Monika Nowicka
Institute of Mathematics and Physics
UTP University of Science and Technology
al. prof. Kaliskiego 7, 85-796 Bydgoszcz, Poland
e-mail: monika.nowicka@utp.edu.pl

Alfred Witkowski
Institute of Mathematics and Physics
UTP University of Science and Technology
al. prof. Kaliskiego 7, 85-796 Bydgoszcz, Poland
e-mail: alfred.witkowski@utp.edu.pl