# INEQUALITIES FOR THE WEIGHTED $A$-NUMERICAL RADIUS OF SEMI-HILBERTIAN SPACE OPERATORS 

Fugen Gao and Xianqin Liu

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#### Abstract

In this paper, we introduce the weighted $A$-numerical radius $\omega_{(A, v)}(\cdot)$ for semi-Hilbertian space operators. Further we obtain some basic properties and inequalities for $\omega_{(A, v)}(\cdot)$, which will be matched with earlier results about $\omega_{A}(\cdot)$. Moreover, we provide a refinement and generalization for inequalities obtained in $[6,16]$.


## 1. Introduction

In this article, we introduce the weighted $A$-numerical radius $\omega_{(A, v)}(\cdot)$, which generalizes the $A$-numerical radius and numerical radius. We present some interesting properties of $\omega_{(A, v)}(\cdot)$. Meanwhile, we derive upper and lower bounds for this numerical radius. Some inequalities obtained for $\omega_{(A, v)}(\cdot)$ will be matched with known inequalities for $\omega_{A}(\cdot)$. We first introduce the notions and terminologies.

Let $(\mathscr{H},\langle\cdot, \cdot\rangle)$ be a complex Hilbert space equipped with the norm $\|\cdot\|$, and let $B(\mathscr{H})$ be the algebra of all bounded linear operators on $\mathscr{H}$. We assume $A$ is a positive operator on $\mathscr{H}$. The positive operator $A$ induces semi-inner product $\langle x, y\rangle_{A}=\langle A x, y\rangle$ for all $x, y \in \mathscr{H}$. Let $\|\cdot\|_{A}$ denote seminorm on $\mathscr{H}$, that is, $\|x\|_{A}=\sqrt{\langle x, x\rangle_{A}}$. About more, we refer readers to see $[8,11,16]$.

For $T \in B(\mathscr{H})$, the null space of every operator $T$ is denoted by $N(T)$, its range by $R(T)$. By $\overline{R(T)}$ we denote the norm closure of $R(T)$ in $\mathscr{H}$. For $T \in B(\mathscr{H})$, $A$-operator seminorm of $T$, denoted by $\|T\|_{A}$, is defined as

$$
\|T\|_{A}=\sup _{x \in \overline{R(A)}, x \neq 0} \frac{\|T x\|_{A}}{\|x\|_{A}} .
$$

Here, given $T \in B(\mathscr{H})$, if there exists $c>0$ such that $\|T x\|_{A} \leqslant c\|x\|_{A}$ for all $x \in \overline{R(A)}$, then $\|T\|_{A}<\infty$. We set $B^{A}(\mathscr{H})=\left\{T \in B(\mathscr{H}):\|T\|_{A}<\infty\right\}$. Let $T \in B(\mathscr{H})$, an operator $R \in B(\mathscr{H})$ is called an $A$-adjoint of $T$ if $\langle T x, y\rangle_{A}=\langle x, R y\rangle_{A}$ for every $x, y \in$ $\mathscr{H}$, that is $A R=T^{*} A$. An operator $T \in B(\mathscr{H})$ is said to be $A$-selfadjoint if $A T$ is selfadjoint, that is $A T=T^{*} A$, where $T^{*}$ is the adjoint of $T$.

[^0]The existence of an $A$-adjoint of $T$ is not guaranteed. In fact, an operator $T \in$ $B(\mathscr{H})$ may admit none, one or many $A$-adjoints. The set of all operators that admit $A$-adjoints is denoted by $B_{A}(\mathscr{H})$. By Douglas theorem [7], it follows that

$$
B_{A}(\mathscr{H})=\left\{T \in B(\mathscr{H}): R\left(T^{*} A\right) \subseteq R(A)\right\} .
$$

If $T \in B_{A}(\mathscr{H})$, then the operator equation $A X=T^{*} A$ has a unique solution, denoted by $T^{\sharp_{A}}$, satisfying $R\left(T^{\sharp A}\right) \subseteq \overline{R(A)}$. Note that $T^{\sharp_{A}}=A^{\dagger} T^{*} A$, where $A^{\dagger}$ is the MoorePenrose inverse of $A$ and the $A$-adjoint operator $T^{\sharp A}$ verifies

$$
A T^{\sharp_{A}}=T^{*} A, R\left(T^{\sharp_{A}}\right) \subseteq \overline{R(A)} \text { and } N\left(T^{\sharp_{A}}\right)=N\left(T^{*} A\right) .
$$

Notice that if $T \in B_{A}(\mathscr{H})$, then $T^{\sharp_{A}} \in B_{A}(\mathscr{H}),\left(T^{\sharp_{A}}\right)^{\sharp_{A}}=P T P$ and $\left(\left(T^{\sharp_{A}}\right)^{\sharp_{A}}\right)^{\sharp_{A}}=T^{\sharp_{A}}$, the $P$ is the orthogonal projection onto $\overline{R(A)}$. For $T \in B_{A}(\mathscr{H}), T T^{\sharp_{A}}$ and $T^{\sharp_{A}} T$ are $A$-selfadjoint and $A$-positive, so we have

$$
\left\|T T^{\sharp_{A}}\right\|_{A}=\left\|T^{\sharp_{A}} T\right\|_{A}=\|T\|_{A}^{2}=\left\|T^{\sharp_{A}}\right\|_{A}^{2} .
$$

For more about this class of operators, we refer the interested readers to see [11, 16].
DEFINITION 1.1. Let $0 \leqslant v \leqslant 1$ and $T \in B_{A}(\mathscr{H})$. The weighted real and imaginary parts of $T$ are defined as

$$
\mathfrak{R}_{(A, v)}(T)=v T+(1-v) T^{\sharp_{A}} \text { and } \mathfrak{I}_{(A, v)}(T)=v(-i T)+(1-v) i T^{\sharp_{A}}
$$

respectively. When $v=\frac{1}{2}$, we can see that $\mathfrak{R}_{(A, v)}(T)=\mathfrak{\Re}_{A}(T)$ and $\mathfrak{I}_{(A, v)}(T)=$ $\mathfrak{I}_{A}(T)$.

Some interesting relationships about $\mathfrak{R}_{(A, v)}(T), \mathfrak{I}_{(A, v)}(T)$ and $\mathfrak{R}_{A}(T), \mathfrak{I}_{A}(T)$ are as follows.

Proposition 1.2. Let $0 \leqslant v \leqslant 1$ and $T \in B_{A}(\mathscr{H})$. Then

$$
\begin{align*}
& \mathfrak{R}_{(A, v)}(T)=\mathfrak{R}_{A}(T)+i(2 v-1) \mathfrak{I}_{A}(T),  \tag{1.1}\\
& \mathfrak{I}_{(A, v)}(T)=\mathfrak{I}_{A}(T)-i(2 v-1) \mathfrak{\Re}_{A}(T) \tag{1.2}
\end{align*}
$$

and

$$
\begin{equation*}
\mathfrak{\Re}_{(A, v)}(T)+i \mathfrak{\Im}_{(A, v)}(T)=2 v T \tag{1.3}
\end{equation*}
$$

The $A$-numerical radius and the $A$-Crawford number of $T \in B(\mathscr{H})$ are defined by

$$
\omega_{A}(T)=\sup \left\{\left|\langle T x, x\rangle_{A}\right|: x \in \mathscr{H},\|x\|_{A}=1\right\}
$$

and

$$
c_{A}(T)=\inf \left\{\left|\langle T x, x\rangle_{A}\right|: x \in \mathscr{H},\|x\|_{A}=1\right\} .
$$

For $T \in B_{A}(\mathscr{H})$, it is well-known that $A$-numerical radius of $T$ is equivalent to $A$ operator seminorm of $T$, (see [16]), satisfying the following inequality:

$$
\begin{equation*}
\frac{1}{2}\|T\|_{A} \leqslant \omega_{A}(T) \leqslant\|T\|_{A} \tag{1.4}
\end{equation*}
$$

In [16], Zamani proved that

$$
\begin{equation*}
\omega_{A}(T)=\sup _{\theta \in \mathbb{R}}\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A} \tag{1.5}
\end{equation*}
$$

Recently, this identity (1.5) has been widely used, some novel $A$-numerical radius inequalities improved were found. There are some refinements of the inequalities (1.4) in references [6, 8, 11, 12, 16]. For example, in [16], let $T \in B_{A}(\mathscr{H})$, Zamani proved that

$$
\begin{equation*}
\omega_{A}(T) \leqslant \frac{1}{2} \sqrt{\left\|T T^{\sharp_{A}}+T^{\sharp_{A}} T\right\|_{A}+2 \omega_{A}\left(T^{2}\right)} \leqslant\|T\|_{A} . \tag{1.6}
\end{equation*}
$$

Another refinement of the inequalities (1.4) has been established in [6], Bhunia computed some inequalities for $\mathbb{A}$-numerical radius of $2 \times 2$ operator matrices, where $\mathbb{A}=\left(\begin{array}{ll}A & O \\ O & A\end{array}\right)$. Let $X, Y \in B_{A}(\mathscr{H})$, some results are as follows,

$$
\omega_{\mathbb{A}}^{2}\left(\begin{array}{rr}
O & X  \tag{1.7}\\
Y & 0
\end{array}\right) \geqslant \frac{1}{4} \max \left\{\left\|X X^{\sharp_{A}}+Y^{\sharp_{A}} Y\right\|_{A},\left\|X^{\sharp_{A}} X+Y Y^{\sharp_{A}}\right\|_{A}\right\}
$$

and

$$
\omega_{\mathbb{A}}^{2}\left(\begin{array}{cc}
O & X  \tag{1.8}\\
Y & 0
\end{array}\right) \leqslant \frac{1}{2} \max \left\{\left\|X X^{\sharp_{A}}+Y^{\sharp_{A}} Y\right\|_{A},\left\|X^{\sharp_{A}} X+Y Y^{\sharp_{A}}\right\|_{A}\right\} .
$$

It should be remarked that many mathematicians have developed various inequalities about $A$-numerical radius and other results on numerical radius inequalities of $2 \times 2$ operator matrices, see, e.g., $[1,2,3,4,9,15,17]$.

In this paper, motivated by [14], we define the weighted $A$-numerical radius, develop and generalize inequalities for the $A$-numerical radius of operators in $B_{A}(\mathscr{H})$. We obtain a generalization for inequality (1.6). Further, we derive the weighted $\mathbb{A}$ numerical radius inequalities of $2 \times 2$ operator matrices that refine the inequalities (1.7) and (1.8).

## 2. Weighted $A$-numerical radius inequalities

DEfinition 2.1. Let $0 \leqslant v \leqslant 1$ and $T \in B_{A}(\mathscr{H})$. The weighted $A$-numerical radius of $T$ denoted by $\omega_{(A, v)}(T)$, is defined as

$$
\omega_{(A, v)}(T)=\sup _{\theta \in \mathbb{R}}\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}
$$

For $T \in B_{A}(\mathscr{H})$, obviously, $\omega_{\left(A, \frac{1}{2}\right)}(T)=\omega_{A}(T)$, and $\omega_{(A, 0)}(T)=\omega_{A(1)}(T)=\|T\|_{A}$.

Proposition 2.2. Let $0 \leqslant v \leqslant 1$ and $T \in B_{A}(\mathscr{H})$. Then

$$
\omega_{(A, v)}(T)=\sup _{\theta \in \mathbb{R}}\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}
$$

Proof. To prove this, we first prove that $\omega_{(A, v)}(\lambda T)=|\lambda| \omega_{(A, v)}(T)$ for all $\lambda \in \mathbb{C}$. For every nonzero $\lambda \in \mathbb{C}$, there exists $\varphi \in \mathbb{R}$ such that $\lambda=|\lambda| e^{i \varphi}$, we have

$$
\begin{aligned}
& \left.\omega_{(A, v)}(\lambda T)=\sup _{\theta \in \mathbb{R}} \| v\left(e^{i \theta} \lambda T\right)+(1-v)\left(e^{-i \theta}\right) \bar{\lambda} T^{\sharp_{A}}\right) \|_{A} \\
& \left.=\sup _{\theta \in \mathbb{R}} \| v e^{i \theta}|\lambda| e^{i \varphi} T+(1-v) e^{-i \theta}|\lambda| e^{-i \varphi} T^{\sharp A}\right) \|_{A} \\
& \left.=|\lambda| \sup _{\theta \in \mathbb{R}} \| v\left(e^{i(\theta+\varphi)} T\right)+(1-v)\left(e^{-i(\theta+\varphi)}\right) T^{\sharp A}\right) \|_{A} \\
& =|\lambda| \omega_{(A, v)}(T) \text {. }
\end{aligned}
$$

Then by replacing $T$ by $i T$ in $\omega_{(A, v)}(T)=\sup _{\theta \in \mathbb{R}}\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}$, we have

$$
\begin{aligned}
\omega_{(A, v)}(T) & =\sup _{\theta \in \mathbb{R}}\left\|v e^{i \theta} i T-(1-v) e^{-i \theta} i T^{\sharp A}\right\|_{A} \\
& =\sup _{\theta \in \mathbb{R}}\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A} .
\end{aligned}
$$

THEOREM 2.3. Let $0 \leqslant v \leqslant 1$ and $T \in B_{A}(\mathscr{H})$. Then for $\alpha, \beta \in \mathbb{R}$,

$$
\omega_{(A, v)}(T)=\sup _{\alpha^{2}+\beta^{2}=1}\left\|\alpha \Re_{(A, v)}(T)+\beta \mathfrak{I}_{(A, v)}(T)\right\|_{A}
$$

Proof. Let $\theta \in \mathbb{R}$. Put $\alpha=\cos \theta$ and $\beta=\sin \theta$. Then

$$
\begin{aligned}
v e^{i \theta} T+(1-v) e^{-i \theta} T^{\sharp_{A}} & =v(\cos \theta+i \sin \theta) T+(1-v)(\cos \theta-i \sin \theta) T^{\sharp_{A}} \\
& =\cos \theta\left(v T+(1-v) T^{\sharp_{A}}\right)-\sin \theta\left(-v i T+(1-v) i T^{\sharp_{A}}\right) \\
& =\cos \theta \Re_{(A, v)}(T)-\sin \theta \mathfrak{I}_{(A, v)}(T) .
\end{aligned}
$$

Therefore,

$$
\sup _{\theta \in \mathbb{R}}\left\|v e^{i \theta} T+(1-v) e^{-i \theta} T^{\sharp_{A}}\right\|_{A}=\sup _{\alpha^{2}+\beta^{2}=1}\left\|\alpha \Re_{(A, v)}(T)+\beta \mathfrak{I}_{(A, v)}(T)\right\|_{A} .
$$

Hence, we obtain the desired result by Definition 2.1.
Proposition 2.4. Let $T \in B_{A}(\mathscr{H}), 0 \leqslant v \leqslant 1$ and $\gamma=\max \{v, 1-v\}$. Then
(a) $\omega_{(A, v)}(T)=\omega_{(A, v)}\left(T^{\sharp_{A}}\right)$,
(b) $\omega_{(A, v)}(T)=\omega_{(A, 1-v)}(T)$,
(c) $\gamma\|T\|_{A} \leqslant \omega_{(A, v)}(T) \leqslant\|T\|_{A}$,
(d) $\omega_{A}(T) \leqslant \omega_{(A, v)}(T) \leqslant 2 \gamma \omega_{A}(T)$.

Proof. (a) and (b) can be easily obtained by definition and the properties of the $A$-seminorm.

Next, we prove (c), by Definition 2.1 and the triangle inequality, then $\omega_{(A, v)}(T) \leqslant$ $\|T\|_{A}$. Another, we have

$$
\omega_{(A, v)}(T)=\sup _{\alpha^{2}+\beta^{2}=1}\left\|\alpha \Re_{(A, v)}(T)+\beta \mathfrak{\Im}_{(A, v)}(T)\right\|_{A}
$$

Letting $\alpha=1, \beta=0$ and $\alpha=0, \beta=1$, we get that

$$
\omega_{(A, v)}(T) \geqslant\left\|\Re_{(A, v)}(T)\right\|_{A} \text { and } \omega_{(A, v)}(T) \geqslant\left\|\mathfrak{I}_{(A, v)}(T)\right\|_{A}
$$

By adding two inequalities, and the triangle inequality, we obtain

$$
2 \omega_{(A, v)}(T) \geqslant\left\|\Re_{(A, v)}(T)\right\|_{A}+\left\|\mathfrak{I}_{(A, v)}(T)\right\|_{A} \geqslant 2 v\|T\|_{A} .
$$

Then by replacing $v$ by $(1-v)$, we get

$$
\omega_{(A, v)}(T) \geqslant(1-v)\|T\|_{A}
$$

We start proving (d), for $\theta \in \mathbb{R}$, let $x \in \mathscr{H}$ with $\|x\|_{A}=1$ and $\frac{1}{2} \leqslant v \leqslant 1$, then

$$
\begin{aligned}
& \left\|\left(\Re_{A}\left(e^{i \theta} T\right)+i(2 v-1) \mathfrak{I}_{A}\left(e^{i \theta} T\right)\right) x\right\|_{A}^{2} \\
& =\left\|\Re_{A}\left(e^{i \theta} T\right) x\right\|_{A}^{2}+(2 v-1)^{2}\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right) x\right\|_{A}^{2}+2(2 v-1) \mathfrak{\Re}\left(\left\langle\Re_{A}\left(e^{i \theta} T\right) x, i \mathfrak{I}_{A}\left(e^{i \theta} T\right) x\right\rangle_{A}\right) \\
& \leqslant\left\|\Re_{A}\left(e^{i \theta} T\right) x\right\|_{A}^{2}+(2 v-1)^{2}\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right) x\right\|_{A}^{2}+2(2 v-1)\left|\left\langle\Re_{A}\left(e^{i \theta} T\right) x, \mathfrak{I}_{A}\left(e^{i \theta} T\right) x\right\rangle_{A}\right| \\
& \leqslant\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2}\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+2(2 v-1)\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A} \\
& \leqslant\left(2 v \omega_{A}(T)\right)^{2} .
\end{aligned}
$$

Taking the supremum over all $\|x\|_{A}=1$ and $\theta \in \mathbb{R}$, together with (1.1), we get

$$
\omega_{(A, v)}(T) \leqslant 2 v \omega_{A}(T)
$$

If $0 \leqslant v \leqslant \frac{1}{2}$, then, $\frac{1}{2} \leqslant 1-v \leqslant 1$, we can get $\omega_{(A, v)}(T) \leqslant 2(1-v) \omega_{A}(T)$. Therefore, $\omega_{(A, v)}(T) \leqslant 2 \gamma \omega_{A}(T)$.

On the other hand, similar to the method in the literature [14], first we prove that $f(v)=\omega_{(A, v)}(T)$ is a convex continuous function on $[0,1]$. For $0 \leqslant v_{1}, v_{2}, \lambda \leqslant 1$. Then

$$
\begin{aligned}
f & \left(\lambda v_{1}+(1-\lambda) v_{2}\right)=\omega_{\left(A, \lambda v_{1}+(1-\lambda) v_{2}\right)}(T) \\
& =\sup _{\theta \in \mathbb{R}}\left\|\left(\lambda v_{1}+(1-\lambda) v_{2}\right) e^{i \theta} T+\left(1-\lambda v_{1}-v_{2}+\lambda v_{2}\right) e^{-i \theta} T^{\sharp A}\right\|_{A} \\
& \leqslant \lambda \sup _{\theta \in \mathbb{R}}\left\|v_{1} e^{i \theta} T+\left(1-v_{1}\right) e^{-i \theta} T^{\sharp A}\right\|_{A}+(1-\lambda) \sup _{\theta \in \mathbb{R}}\left\|v_{2} e^{i \theta} T+\left(1-v_{2}\right) e^{-i \theta} T^{\sharp A}\right\|_{A} \\
& =\lambda \omega_{\left(A, v_{1}\right)}(T)+(1-\lambda) \omega_{\left(A, v_{2}\right)}(T) \\
& =\lambda f\left(v_{1}\right)+(1-\lambda) f\left(v_{2}\right) .
\end{aligned}
$$

Therefore, $f$ is convex on $[0,1]$. By the property of convex function, $f$ is continuous on $(0,1)$. According to (c), we have

$$
0 \leqslant\|T\|_{A}-\omega_{(A, v)}(T) \leqslant\|T\|_{A}(1-\gamma)
$$

Hence $f$ is continuous at $v=0$ and $v=1$, i.e. it is continuous on $[0,1]$. Also we know $f(v)=f(1-v), f$ is symmetric about $v=\frac{1}{2}$. It means that $f$ is decreasing on $\left[0, \frac{1}{2}\right]$ and increasing on $\left[\frac{1}{2}, 1\right]$. Therefore, we get that the minimum of $f$ is $f\left(\frac{1}{2}\right)$ and the maximum of $f$ is $f(1)$ and $f(0)$. It shows that $\omega_{A}(T) \leqslant \omega_{(A, v)}(T)$. This completes the proof.

Theorem 2.5. Let $T \in B_{A}(\mathscr{H}), 0 \leqslant v \leqslant 1$ and $\gamma=\max \{v, 1-v\}$. Then we have

$$
\omega_{(A, v)}(T) \geqslant \gamma\|T\|_{A}+\sup _{\theta \in \mathbb{R}} \frac{\left|\left\|\mathfrak{\Re}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}-\left\|\mathfrak{\Im}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}\right|}{2}
$$

Proof. Let $\theta \in \mathbb{R}$. Then

$$
\begin{aligned}
\omega_{(A, v)}(T) & \geqslant \max \left\{\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A},\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}\right\} \\
& =\frac{\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}+\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}}{2}+\frac{\left|\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}-\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}\right|}{2} \\
& \geqslant v\|T\|_{A}+\frac{\left|\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}-\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}\right|}{2}
\end{aligned}
$$

Furthermore, by replacing $v$ by $(1-v)$, we get

$$
\omega_{(A, v)}(T) \geqslant(1-v)\|T\|_{A}+\frac{\left|\left\|\Re_{A(1-v)}\left(e^{i \theta} T\right)\right\|_{A}-\left\|\mathfrak{I}_{A(1-v)}\left(e^{i \theta} T\right)\right\|_{A}\right|}{2}
$$

We also have

$$
\left\|\Re_{(A, 1-v)}\left(e^{i \theta} T\right)\right\|_{A}=\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A} \quad \text { and } \quad\left\|\mathfrak{I}_{(A, 1-v)}\left(e^{i \theta} T\right)\right\|_{A}=\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}
$$

Therefore,

$$
\omega_{(A, v)}(T) \geqslant \max \{v,(1-v)\}\|T\|_{A}+\frac{\left|\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}-\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}\right|}{2}
$$

This completes the proof.

Corollary 2.6. Let $T \in B_{A}(\mathscr{H}), 0 \leqslant v \leqslant 1$ and $\gamma=\max \{v, 1-v\}$. Then $\omega_{(A, v)}(T)=\gamma\|T\|_{A}$ if and only if $\left\|\mathfrak{R}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}=\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}=\gamma\|T\|_{A}$ for all $\theta \in \mathbb{R}$.

Proof. According to Definition 2.1, the sufficient part is trivial, we only prove the necessary part. For $v \in\left[\frac{1}{2}, 1\right]$, by Theorem $2.5, \omega_{(A, v)}(T)=\gamma\|T\|_{A}$, we get $\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}=\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}$, also

$$
\begin{aligned}
\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A} & \leqslant \omega_{(A, v)}(T)=v\|T\|_{A}=\left\|v e^{i \theta} T\right\|_{A} \\
& =\left\|\frac{\Re_{(A, v)}\left(e^{i \theta} T\right)+i \mathfrak{J}_{(A, v)}\left(e^{i \theta} T\right)}{2}\right\|_{A} \leqslant\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}
\end{aligned}
$$

for all $\theta \in \mathbb{R}$. For $v \in\left[0, \frac{1}{2}\right], 1-v \in\left[\frac{1}{2}, 1\right]$, similarly, we can prove the conclusion.
Theorem 2.7. Let $T \in B_{A}(\mathscr{H})$ and $0 \leqslant v \leqslant 1$. Then we have

$$
\omega_{(A, v)}(T) \leqslant \inf _{\theta \in \mathbb{R}} \sqrt{\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2}+\left\|\mathfrak{J}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2}}
$$

Proof. For $\alpha, \beta \in \mathbb{R}$, replacing $T$ by $e^{i \theta} T$ in Theorem 2.3, then

$$
\begin{aligned}
\omega_{(A, v)}(T) & =\sup _{\alpha^{2}+\beta^{2}=1}\left\|\alpha \mathfrak{\Re}_{(A, v)}\left(e^{i \theta} T\right)+\beta \mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A} \\
& \leqslant \sup _{\alpha^{2}+\beta^{2}=1}\left(|\alpha|\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}+|\beta|\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}\right)
\end{aligned}
$$

By the Cauchy-Schwarz inequality, we get that

$$
\omega_{(A, v)}(T) \leqslant \sup _{\alpha^{2}+\beta^{2}=1}\left(\sqrt{|\alpha|^{2}+|\beta|^{2}} \sqrt{\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2}+\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2}}\right)
$$

Thus,

$$
\omega_{(A, v)}(T) \leqslant \inf _{\theta \in \mathbb{R}} \sqrt{\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2}+\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2}}
$$

Theorem 2.8. Let $T \in B_{A}(\mathscr{H})$ and $0 \leqslant v \leqslant 1$. Then we have

$$
\begin{aligned}
& \omega_{(A, v)}^{2}(T) \\
\geqslant & \frac{1}{4}\left\|T^{\sharp}{ }^{\sharp_{A}} T+T T^{\sharp A}\right\|_{A}+\frac{(2 v-1)^{2}\left[c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)+c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)\right]}{2} \\
& +\frac{\left|\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}-\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2}\left[c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)-c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)\right]\right|}{2}
\end{aligned}
$$

for all $\theta \in \mathbb{R}$.
Proof. Let $\theta \in \mathbb{R}$, we first prove the following two inequalities:

$$
\begin{aligned}
& \omega_{(A, v)}^{2}(T) \geqslant\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2} c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right), \\
& \omega_{(A, v)}^{2}(T) \geqslant\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2} c_{A}^{2}\left(\mathfrak{\Re}_{A}\left(e^{i \theta} T\right)\right) .
\end{aligned}
$$

Let $x \in \mathscr{H}$ with $\|x\|_{A}=1$. Then we have

$$
\begin{aligned}
\sup _{\theta \in \mathbb{R}}\left\|\Re_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A}^{2} & \geqslant\left\|\left(\operatorname{Re}_{A}\left(e^{i \theta} T\right)+i(2 v-1) \mathfrak{I}_{A}\left(e^{i \theta} T\right)\right) x\right\|_{A}^{2} \\
& \geqslant\left|\left\langle\left(\Re_{A}\left(e^{i \theta} T\right)+i(2 v-1) \mathfrak{I}_{A}\left(e^{i \theta} T\right)\right) x, x\right\rangle_{A}\right|^{2} \\
& =\left|\left\langle\Re_{A}\left(e^{i \theta} T\right) x, x\right\rangle_{A}\right|^{2}+(2 v-1)^{2}\left|\left\langle\mathfrak{I}_{A}\left(e^{i \theta} T\right) x, x\right\rangle_{A}\right|^{2} \\
& \geqslant\left|\left\langle\Re_{A}\left(e^{i \theta} T\right) x, x\right\rangle_{A}\right|^{2}+(2 v-1)^{2} c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right) .
\end{aligned}
$$

By taking the supremum over $x \in \mathscr{H}$ with $\|x\|_{A}=1$, implies that

$$
\omega_{(A, v)}^{2}(T) \geqslant\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2} c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)=a
$$

Similarly, by using (1.2), we get that

$$
\sup _{\theta \in \mathbb{R}}\left\|\mathfrak{I}_{(A, v)}\left(e^{i \theta} T\right)\right\|_{A} \geqslant\left\|\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)-i(2 v-1) \mathfrak{\Re}_{A}\left(e^{i \theta} T\right)\right) x\right\|_{A}
$$

Then

$$
\omega_{(A, v)}^{2}(T) \geqslant\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2} c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)=b
$$

Therefore, we have

$$
\begin{aligned}
& \omega_{(A, v)}^{2}(T) \\
\geqslant & \max \{a, b\} \\
= & \frac{\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}}{2}+\frac{(2 v-1)^{2}\left[c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)+c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)\right]}{2} \\
& +\frac{\left|\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}-\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2}\left[c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)-c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)\right]\right|}{2} \\
\geqslant & \frac{1}{4}\left\|T^{\not{ }_{A}} T+T T^{\sharp}\right\|_{A}+\frac{(2 v-1)^{2}\left[c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)+c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)\right]}{2} \\
& +\frac{\left|\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}-\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+(2 v-1)^{2}\left[c_{A}^{2}\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)-c_{A}^{2}\left(\Re_{A}\left(e^{i \theta} T\right)\right)\right]\right|}{2} .
\end{aligned}
$$

This completes the proof.

Corollary 2.9. Let $T \in B_{A}(\mathscr{H})$. Then $\omega_{A}^{2}(T)=\frac{1}{4}\left\|T^{\sharp_{A}} T+T T^{\sharp_{A}}\right\|_{A}$ if and only if $\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}=\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}=\frac{1}{4}\left\|T^{\sharp_{A}} T+T T^{\sharp_{A}}\right\|_{A}$ for all $\theta \in \mathbb{R}$.

Proof. The sufficient part is trivial, we only prove the necessary part. Taking $v=$ $\frac{1}{2}$ in Theorem 2.8, if $\omega_{A}^{2}(T)=\frac{1}{4}\left\|T^{\sharp_{A}} T+T T^{\sharp_{A}}\right\|_{A}$, then $\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}=\left\|\mathfrak{\Im}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}$
for all $\theta \in \mathbb{R}$. Also, we have $\left(\mathfrak{R}_{A}\left(e^{i \theta} T\right)\right)^{2}+\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)^{2}=\frac{T^{\sharp} A T+T T^{\sharp} A}{2}$. Then

$$
\begin{aligned}
\frac{1}{4}\left\|T^{\sharp} T+T T^{\sharp_{A}}\right\|_{A} & =\frac{1}{2}\left\|\left(\Re_{A}\left(e^{i \theta} T\right)\right)^{2}+\left(\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right)^{2}\right\|_{A} \\
& \leqslant \frac{1}{2}\left(\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}+\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}\right) \\
& \leqslant \frac{1}{2}\left(\omega_{A}^{2}(T)+\omega_{A}^{2}(T)\right) \\
& =\frac{1}{4}\left\|T^{\not{ }_{A}} T+T T^{\sharp}\right\|_{A} .
\end{aligned}
$$

Thus, $\left\|\Re_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}=\left\|\mathfrak{I}_{A}\left(e^{i \theta} T\right)\right\|_{A}^{2}=\frac{1}{4}\left\|T^{\sharp_{A}} T+T T^{\sharp_{A}}\right\|_{A}$ for all $\theta \in \mathbb{R}$.
REMARK 2.10. Very recently, as our work in progress, for an arbitrary norm $N(\cdot)$ on $B(H)$ and $0 \leqslant v \leqslant 1$, Zamani [18] defined the $w_{(N, v)}(\cdot)$ as a generalization of the weighted numerical radius. Mabrouk and Zamani [10] introduced an extension of the $a$-numerical radius on $C^{*}$-algebra. Theorem 2.5 (i) in [10] is an extension of Theorem 2.3. Theorem 2.6 in [18] and [10] are extensions of Proposition 2.4, respectively. Our approach here is different from theirs.

## 3. Weighted $A$-numerical radius inequalities for $2 \times 2$ operator matrices

To prove our results, we begin with the following results.
Lemma 3.1. [5, 6] Let $T, S, X, Y \in B_{A}(\mathscr{H})$. Then
(i) $\quad\left(\begin{array}{cc}T & X \\ Y & S\end{array}\right)^{\sharp_{\mathbb{A}}}=\left(\begin{array}{ll}T^{\sharp_{A}} & Y^{\sharp_{A}} \\ X^{\sharp_{A}} & S^{\sharp_{A}}\end{array}\right)$.
(ii)

$$
\left\|\left(\begin{array}{ll}
T & O \\
O & S
\end{array}\right)\right\|_{\mathbb{A}}=\left\|\left(\begin{array}{cc}
O & T \\
S & O
\end{array}\right)\right\|_{\mathbb{A}}=\max \left\{\|T\|_{A},\|S\|_{A}\right\}
$$

Lemma 3.2. [13] Let $X, Y \in B_{A}(\mathscr{H})$. Then

$$
\omega_{\mathbb{A}}\left(\begin{array}{cc}
O & X  \tag{i}\\
Y & O
\end{array}\right)=\omega_{\mathbb{A}}\left(\begin{array}{cc}
O & Y \\
X & O
\end{array}\right)
$$

(ii) $\quad \omega_{\mathbb{A}}\left(\begin{array}{ll}X & Y \\ Y & X\end{array}\right)=\max \left\{\omega_{A}(X+Y), \omega_{A}(X-Y)\right\}$.

In particular $\omega_{\mathbb{A}}\left(\begin{array}{cc}O & Y \\ Y & O\end{array}\right)=\omega_{A}(Y)$.
Theorem 3.3. Let $X, Y \in B_{A}(\mathscr{H})$. Then we have

$$
\begin{array}{r}
\omega_{(\mathbb{A}, v)}^{2}\left(\begin{array}{cc}
O & X \\
Y & O
\end{array}\right) \leqslant \max \left\{\left\|v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}} Y\right\|_{A}+2 v(1-v) \omega_{A}(X Y),\right. \\
\left.\left\|v^{2} Y Y^{\sharp_{A}}+(1-v)^{2} X^{\sharp_{A}} X\right\|_{A}+2 v(1-v) \omega_{A}(Y X)\right\} .
\end{array}
$$

In particular, if $v=\frac{1}{2}$, then

$$
\begin{align*}
& \omega_{\mathbb{A}}^{2}\left(\begin{array}{ll}
O & X \\
Y & O
\end{array}\right) \leqslant \max \left\{\frac{1}{4}\left\|X X^{\sharp_{A}}+Y^{\sharp_{A}} Y\right\|_{A}+\frac{1}{2} \omega_{A}(X Y),\right.  \tag{3.1}\\
& \left.\frac{1}{4}\left\|X^{\sharp_{A}} X+Y Y^{\sharp_{A}}\right\|_{A}+\frac{1}{2} \omega_{A}(Y X)\right\} . \tag{3.2}
\end{align*}
$$

Proof. Let $T=\left(\begin{array}{cc}O & X \\ Y & O\end{array}\right)$. By Lemma 3.1, we have

$$
\begin{aligned}
\omega_{(\mathbb{A}, v)}^{2}\left(\begin{array}{cc}
O & X \\
Y & O
\end{array}\right) & =\sup _{\theta \in \mathbb{R}}\left\|\left(\begin{array}{cc}
O & v e^{i \theta} X+(1-v) e^{-i \theta} Y^{\sharp_{A}} \\
v e^{i \theta} Y+(1-v) e^{-i \theta} X^{\sharp_{A}} & O
\end{array}\right)\right\|_{A}^{2} \\
& =\sup _{\theta \in \mathbb{R}}\left\|\left(\begin{array}{ll}
P & O \\
O & Q
\end{array}\right)\right\|_{A}
\end{aligned}
$$

where

$$
\begin{aligned}
& P=v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}}\left(Y^{\sharp_{A}}\right)^{\sharp_{A}}+2 v(1-v) \Re_{A}\left(e^{2 i \theta} X\left(Y^{\sharp_{A}}\right)^{\sharp_{A}}\right), \\
& Q=v^{2} Y Y^{\sharp_{A}}+(1-v)^{2} X^{\sharp_{A}}\left(X^{\sharp_{A}}\right)^{\sharp_{A}}+2 v(1-v) \Re_{A}\left(e^{2 i \theta} Y\left(X^{\sharp_{A}}\right)^{\sharp_{A}}\right) .
\end{aligned}
$$

Then, we can get

$$
\begin{aligned}
\|P\|_{A} & \leqslant\left\|v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}} Y\right\|_{A}+2 v(1-v)\left\|\Re_{A}\left(e^{2 i \theta} X\left(Y^{\sharp_{A}}\right)^{A_{A}}\right)\right\|_{A} \\
& \leqslant\left\|v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}} Y\right\|_{A}+2 v(1-v) \omega_{A}(X Y) . \\
\|Q\|_{A} & \leqslant\left\|v^{2} Y Y^{\sharp_{A}}+(1-v)^{2} X^{\sharp_{A}} X\right\|_{A}+2 v(1-v)\left\|\Re_{A}\left(e^{2 i \theta} Y\left(X^{\sharp_{A}}\right)^{\sharp_{A}}\right)\right\|_{A} \\
& \leqslant\left\|v^{2} Y Y^{\sharp_{A}}+(1-v)^{2} X^{\sharp_{A}} X\right\|_{A}+2 v(1-v) \omega_{A}(Y X) .
\end{aligned}
$$

By using Lemma 3.1, we have

$$
\omega_{(\mathbb{A}, v)}^{2}\left(\begin{array}{cc}
O & X \\
Y & O
\end{array}\right)=\sup _{\theta \in \mathbb{R}} \max \left\{\|P\|_{A},\|Q\|_{A}\right\}
$$

In conclusion, we obtain the desired inequality.
REMARK 3.4. Letting $v=\frac{1}{2}$ and $X=Y=T$ in Theorem 3.3, and by Lemma 3.2, we get the inequality (1.6) proved by Zamani in [16]. Together with (3.1) and (3.2), we can see that the bound provided in Theorem 3.3 is sharper than (1.8) given in [6].

Theorem 3.5. Let $X, Y \in B_{A}(\mathscr{H})$. Then we have

$$
\begin{array}{r}
\omega_{(\mathbb{A}, v)}^{2}\left(\begin{array}{cc}
O & X \\
Y & O
\end{array}\right) \geqslant \max \left\{\left\|v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}} Y\right\|_{A}+2 v(1-v) c_{A}(X Y),\right. \\
\left.\left\|v^{2} Y Y^{\sharp_{A}}+(1-v)^{2} X^{\sharp_{A}} X\right\|_{A}+2 v(1-v) c_{A}(Y X)\right\} .
\end{array}
$$

In particular, if $v=\frac{1}{2}$, then

$$
\begin{array}{r}
\omega_{\mathbb{A}}^{2}\left(\begin{array}{cc}
O & X \\
Y & O
\end{array}\right) \geqslant \max \left\{\begin{array}{l}
\frac{1}{4}\left\|X X^{\sharp_{A}}+Y^{\sharp_{A}} Y\right\|_{A}+\frac{1}{2} c_{A}(X Y), \\
\left.\frac{1}{4}\left\|X^{\sharp_{A}} X+Y Y^{\sharp_{A}}\right\|_{A}+\frac{1}{2} c_{A}(Y X)\right\} .
\end{array} .\left\{\begin{array}{l}
\end{array},\right.\right.
\end{array}
$$

Proof. From the proof of Theorem 3.3 we know that

$$
\omega_{(\mathbb{A}, v)}^{2}\left(\begin{array}{cc}
O & X \\
Y & O
\end{array}\right)=\sup _{\theta \in \mathbb{R}} \max \left\{\|P\|_{A},\|Q\|_{A}\right\}
$$

Here, $P$ and $Q$ are the same as Theorem 3.3.
Let $x \in \mathscr{H}$ with $\|x\|_{A}=1$. For all $\theta \in \mathbb{R}$, we have that

$$
\begin{aligned}
\|P\|_{A} & \geqslant\left|\langle P x, x\rangle_{A}\right| \\
& =\left|\left\langle\left(v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}}\left(Y^{\sharp_{A}}\right)^{\sharp_{A}}+2 v(1-v) \Re_{A}\left(e^{2 i \theta} X\left(Y^{\sharp_{A}}\right)^{\sharp_{A}}\right)\right) x, x\right\rangle_{A}\right| .
\end{aligned}
$$

We assume that

$$
\left\langle e^{2 i \theta_{0}} X\left(Y^{\sharp A}\right)^{\sharp A} x, x\right\rangle_{A}=\left|\left\langle X\left(Y^{\sharp A}\right)^{\sharp A} x, x\right\rangle_{A}\right| .
$$

Thus, by replacing $\theta$ by $\theta_{0}$ in the above formula, we get

$$
\begin{aligned}
\|P\|_{A} & \geqslant\left|\left\langle v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}}\left(Y^{\sharp_{A}}\right)^{\sharp_{A}} x, x\right\rangle_{A}\right|+2 v(1-v)\left|\left\langle X\left(Y^{\sharp_{A}}\right)^{\sharp_{A}} x, x\right\rangle_{A}\right| \\
& \geqslant\left|\left\langle v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}}\left(Y^{\sharp_{A}}\right)^{\sharp_{A}} x, x\right\rangle_{A}\right|+2 v(1-v) c_{A}(Y X) .
\end{aligned}
$$

Taking the supremum over $x \in \mathscr{H}$ with $\|x\|_{A}=1$ in the above inequality, we get

$$
\|P\|_{A} \geqslant\left\|v^{2} X X^{\sharp_{A}}+(1-v)^{2} Y^{\sharp_{A}} Y\right\|_{A}+2 v(1-v) c_{A}(X Y) .
$$

In a similar way, we can get

$$
\|Q\|_{A} \geqslant\left\|v^{2} Y Y^{\sharp_{A}}+(1-v)^{2} X^{\sharp_{A}} X\right\|_{A}+2 v(1-v) c_{A}(Y X) .
$$

Thus, we complete the proof.
REMARK 3.6. Taking $v=\frac{1}{2}$ in Theorem 3.5, the inequalities (3.3) and (3.4) improve the inequality (1.7) obtained in [6].

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