

AN INEQUALITY FOR DISTANCES AMONG FIVE POINTS AND DISTANCE PRESERVING MAPPINGS

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Abstract. Using properties of norm and inner product, we prove a new inequality for distances between five points arbitrarily given in an inner product space. Moreover, we investigate the Aleksandrov-Rassias problem by proving that if the distance 1 is contractive and the golden ratio is extensive by a mapping f , then f is a linear isometry up to translation.

1. Introduction

In this paper, assume that V is a real (or complex) inner product space with the inner product $\langle \cdot, \cdot \rangle$ and $\| \cdot \|$ is the norm on V defined as $\|x\| = \sqrt{\langle x, x \rangle}$ for all $x \in V$. When \mathbb{E}^2 is the two dimensional Euclidean space and if three points (vectors) x, y, z are the vertices of an acute triangle or a right triangle in \mathbb{E}^2 , then the inequality

$$\|x - z\|^2 \leq \|x - y\|^2 + \|y - z\|^2$$

is true. Especially, the equality sign in the last inequality holds if and only if x, y, z are the vertices of a right triangle and the vectors $x - y$ and $y - z$ are orthogonal to each other. This is called the Pythagorean theorem which is one of the most famous theorems in mathematics.

In regard to this subject, Jung [5] and Jung and Lee [6] proved the following theorems dealing with inequalities for the distances between every two points among the given $2n$ points.

THEOREM 1.1. (Jung [5]) *For any real (or complex) inner product space V , the following inequality is true for all six points $x_1, x_2, x_3, x_4, x_5, x_6$ in V :*

$$\begin{aligned} & 2(\|x_6 - x_1\|^2 + \|x_4 - x_2\|^2 + \|x_5 - x_3\|^2) \\ & \leq \|x_2 - x_1\|^2 + \|x_6 - x_2\|^2 + \|x_4 - x_6\|^2 + \|x_1 - x_4\|^2 \\ & \quad + \|x_3 - x_2\|^2 + \|x_4 - x_3\|^2 + \|x_5 - x_4\|^2 + \|x_2 - x_5\|^2 \\ & \quad + \|x_3 - x_1\|^2 + \|x_6 - x_3\|^2 + \|x_5 - x_6\|^2 + \|x_1 - x_5\|^2 \end{aligned}$$

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In addition, the equality sign is true if and only if each $\{x_2 - x_1, x_6 - x_2, x_4 - x_6, x_1 - x_4\}$, $\{x_3 - x_1, x_6 - x_3, x_5 - x_6, x_1 - x_5\}$, $\{x_3 - x_2, x_4 - x_3, x_5 - x_4, x_2 - x_5\}$ comprises the sides of an appropriate (possibly degenerate) parallelogram such that $x_6 - x_1$ and $x_4 - x_2$, resp., $x_6 - x_1$ and $x_5 - x_3$, resp., $x_4 - x_2$ and $x_5 - x_3$ are the diagonals of the corresponding parallelogram.

THEOREM 1.2. (Jung and Lee [6]) *Assume that $n \geq 2$ is an integer and V is a real (or complex) inner product space. The following inequality is true for any distinct $2n$ points $x_{11}, x_{21}, \dots, x_{n1}, x_{12}, x_{22}, \dots, x_{n2}$ in V :*

$$\sum_{\substack{i, j \in \{1, \dots, n\} \\ k, \ell \in \{1, 2\} \\ i < j}} \|x_{ik} - x_{j\ell}\|^2 \geq (n - 1) \sum_{i \in \{1, \dots, n\}} \|x_{i1} - x_{i2}\|^2$$

In addition, the equality sign holds if and only if for all $i, j \in \{1, \dots, n\}$ with $i < j$, the pair of four points $\{x_{i1}, x_{i2}, x_{j1}, x_{j2}\}$ comprises the vertices of an appropriate (possibly degenerate) parallelogram such that x_{i1} and x_{j1} are the opposite vertices to x_{i2} and x_{j2} , respectively.

Moreover, Jung and Lee [6] made use of these inequalities to solve the Aleksandrov-Rassias problem. (We refer the reader to Section 3 of this paper for the exact definition of the Aleksandrov-Rassias problem.)

In Section 2 of this paper, using basic properties of norm and inner product, we prove a new inequality for distances between five points which are arbitrarily given in an inner product space. We devote Section 3 to a study of the Aleksandrov-Rassias problem. Indeed, we prove that if the distance 1 is contractive and the golden ratio $(\frac{1+\sqrt{5}}{2})$ is extensive by a mapping f , then f is a linear isometry up to translation, while Xiang proved in his paper [11] that if either distances 1 and $\sqrt{2}$ are preserved by a mapping f or 1 and $\sqrt{3}$ are preserved by f , then f is a linear isometry up to translation.

2. Inequality for distances among five points

From now on, we denote by ϕ the golden ratio, i.e., $\phi = \frac{1+\sqrt{5}}{2}$. Then $\phi^2 - \phi - 1 = 0$, and ϕ is the ratio of a diagonal to a side in a regular pentagon. It is somewhat surprising that the golden ratio appears in an inequality for the distances between every two points among five points.

THEOREM 2.1. *For a real (or complex) inner product space $(V, \langle \cdot, \cdot \rangle)$, the inequality*

$$\begin{aligned} \phi^2 \{ \|x_1 - x_2\|^2 + \|x_2 - x_3\|^2 + \|x_3 - x_4\|^2 + \|x_4 - x_5\|^2 + \|x_5 - x_1\|^2 \} \\ \geq \|x_1 - x_3\|^2 + \|x_2 - x_4\|^2 + \|x_3 - x_5\|^2 + \|x_4 - x_1\|^2 + \|x_5 - x_2\|^2 \end{aligned} \tag{2.1}$$

is true for any five points x_1, x_2, x_3, x_4, x_5 in V . Moreover, the equality sign holds if and only if

$$x_4 = x_1 - \phi x_2 + \phi x_3 \quad \text{and} \quad x_5 = \phi x_1 - \phi x_2 + x_3 \quad (2.2)$$

for any $x_1, x_2, x_3 \in V$.

Proof. We will prove this theorem when V is a complex inner product space. For notational convenience, we set $x_6 = x_1$, $x_7 = x_2$ and $x_8 = x_3$. Let $S_j = \sum_{i=1}^5 \langle x_i, x_{i+j} \rangle$ for each $j \in \{0, 1, 2\}$. Then for any $j \in \{0, 1, 2\}$, we get

$$\begin{aligned} \sum_{i=1}^5 \|x_i - x_{i+j}\|^2 &= \sum_{i=1}^5 \langle x_i - x_{i+j}, x_i - x_{i+j} \rangle \\ &= \sum_{i=1}^5 \{ \langle x_i, x_i \rangle - \langle x_i, x_{i+j} \rangle - \overline{\langle x_i, x_{i+j} \rangle} + \langle x_{i+j}, x_{i+j} \rangle \} \\ &= \sum_{i=1}^5 \{ 2\langle x_i, x_i \rangle - \langle x_i, x_{i+j} \rangle - \overline{\langle x_i, x_{i+j} \rangle} \} \\ &= 2S_0 - S_j - \bar{S}_j, \end{aligned} \quad (2.3)$$

where \bar{c} denotes the complex conjugation of a complex number c .

On account of (2.3), $\phi^2 = \phi + 1$ and $2\phi = 1 + \sqrt{5}$, inequality (2.1) becomes

$$\begin{aligned} 0 &\leq \phi^2 \sum_{i=1}^5 \|x_i - x_{i+1}\|^2 - \sum_{i=1}^5 \|x_i - x_{i+2}\|^2 \\ &= \phi^2(2S_0 - S_1 - \bar{S}_1) - (2S_0 - S_2 - \bar{S}_2) \\ &= (2\phi^2 - 2)S_0 - \phi^2(S_1 + \bar{S}_1) + (S_2 + \bar{S}_2) \\ &= 2\phi S_0 - (\phi + 1)(S_1 + \bar{S}_1) + (S_2 + \bar{S}_2), \end{aligned}$$

i.e., it is to prove that

$$(1 + \sqrt{5})S_0 - \frac{3 + \sqrt{5}}{2}(S_1 + \bar{S}_1) + (S_2 + \bar{S}_2) \geq 0. \quad (2.4)$$

Since

$$\begin{aligned} &\sum_{i=1}^5 \langle x_i - x_{i+3}, x_{i+1} - x_{i+2} \rangle \\ &= \sum_{i=1}^5 \{ \langle x_i, x_{i+1} \rangle + \overline{\langle x_{i+2}, x_{i+3} \rangle} - \overline{\langle x_{i+1}, x_{i+3} \rangle} - \langle x_i, x_{i+2} \rangle \} \\ &= \sum_{i=1}^5 \langle x_i, x_{i+1} \rangle + \sum_{i=1}^5 \overline{\langle x_i, x_{i+1} \rangle} - \sum_{i=1}^5 \langle x_i, x_{i+2} \rangle - \sum_{i=1}^5 \overline{\langle x_i, x_{i+2} \rangle} \\ &= (S_1 + \bar{S}_1) - (S_2 + \bar{S}_2), \end{aligned}$$

the following inequality is obviously true:

$$\begin{aligned}
 0 &\leq \sum_{i=1}^5 \|x_i - x_{i+3} - \phi(x_{i+1} - x_{i+2})\|^2 \\
 &= \sum_{i=1}^5 \langle (x_i - x_{i+3}) - \phi(x_{i+1} - x_{i+2}), (x_i - x_{i+3}) - \phi(x_{i+1} - x_{i+2}) \rangle \\
 &= \sum_{i=1}^5 \|x_{i+3} - x_i\|^2 - \phi \sum_{i=1}^5 \langle x_i - x_{i+3}, x_{i+1} - x_{i+2} \rangle \\
 &\quad - \phi \sum_{i=1}^5 \overline{\langle x_i - x_{i+3}, x_{i+1} - x_{i+2} \rangle} + \phi^2 \sum_{i=1}^5 \|x_{i+1} - x_{i+2}\|^2 \\
 &= \sum_{i=1}^5 \|x_i - x_{i+2}\|^2 - 2\phi(S_1 + \bar{S}_1 - S_2 - \bar{S}_2) + \phi^2 \sum_{i=1}^5 \|x_i - x_{i+1}\|^2 \\
 &= (2\phi^2 + 2)S_0 - (\phi^2 + 2\phi)S_1 - (\phi^2 + 2\phi)\bar{S}_1 + (2\phi - 1)S_2 + (2\phi - 1)\bar{S}_2 \\
 &= (5 + \sqrt{5})S_0 - \frac{5 + 3\sqrt{5}}{2}S_1 - \frac{5 + 3\sqrt{5}}{2}\bar{S}_1 + \sqrt{5}S_2 + \sqrt{5}\bar{S}_2
 \end{aligned} \tag{2.5}$$

When we divide inequality (2.5) by $\sqrt{5}$, the resulting inequality is just the inequality (2.4), which is equivalent to our main inequality (2.1).

Equality condition. The right-hand side of (2.5) is 0 if and only if $x_i - x_{i+3} - \phi(x_{i+1} - x_{i+2}) = 0$ for all $i \in \{1, 2, \dots, 5\}$, which is again equivalent to

$$x_{i+3} = x_i - \phi x_{i+1} + \phi x_{i+2} \tag{2.6}$$

for all $i \in \{1, 2, \dots, 5\}$. Assume that the right-hand side of (2.5) is 0 and x_1, x_2, x_3 are given points in V . Then by (2.6), we have

$$x_4 = x_1 - \phi x_2 + \phi x_3$$

and

$$\begin{aligned}
 x_5 &= x_2 - \phi x_3 + \phi x_4 = x_2 - \phi x_3 + \phi(x_1 - \phi x_2 + \phi x_3) \\
 &= \phi x_1 + (-\phi^2 + 1)x_2 + (\phi^2 - \phi)x_3 \\
 &= \phi x_1 - \phi x_2 + x_3.
 \end{aligned}$$

Thus, the conditions in (2.2) are true.

On the other hand, we should check under the assumptions in (2.2) that the equation (2.6) is also true when $i \in \{1, 2, \dots, 5\}$. Indeed, our assumption (2.2) implies that the equation (2.6) is true for $i \in \{1, 2\}$ as we see in the last paragraph. If $i = 3$, then

$$\begin{aligned}
 x_3 - \phi x_4 + \phi x_5 &= x_3 - \phi(x_1 - \phi x_2 + \phi x_3) + \phi(\phi x_1 - \phi x_2 + x_3) \\
 &= (\phi^2 - \phi)x_1 + (\phi^2 - \phi^2)x_2 + (-\phi^2 + \phi + 1)x_3 \\
 &= x_1,
 \end{aligned}$$

which is just the case of (2.6) for $i = 3$ (notice that $x_6 = x_1$, $x_7 = x_2$ and $x_8 = x_3$). For $i = 4$, we have

$$\begin{aligned} x_4 - \phi x_5 + \phi x_1 &= (x_1 - \phi x_2 + \phi x_3) - \phi(\phi x_1 - \phi x_2 + x_3) + \phi x_1 \\ &= (-\phi^2 + \phi + 1)x_1 + (\phi^2 - \phi)x_2 + (\phi - \phi)x_3 \\ &= x_2, \end{aligned}$$

which is just the case of (2.6) for $i = 4$. When $i = 5$, then we get

$$x_5 - \phi x_1 + \phi x_2 = (\phi x_1 - \phi x_2 + x_3) - \phi x_1 + \phi x_2 = x_3,$$

which is the case of (2.6) for $i = 5$.

Hence, equation (2.6) is true for every $i \in \{1, 2, \dots, 5\}$. Since x_1, x_2, x_3 can be any element of V , the equality sign in (2.1) holds if and only if the conditions in (2.2) are true for any $x_1, x_2, x_3 \in V$. \square

3. Applications to Aleksandrov-Rassias problem

Assume that both V_1 and V_2 are either real normed spaces or complex normed spaces. A distance ρ is said to be contractive (or non-expanding) by a mapping $f : V_1 \rightarrow V_2$ if and only if $\|f(x) - f(y)\| \leq \rho$ for all $x, y \in V_1$ with $\|x - y\| = \rho$. In a similar way, we call a distance ρ extensive (or non-shrinking) by f if and only if $\|f(x) - f(y)\| \geq \rho$ for all $x, y \in V_1$ with $\|x - y\| = \rho$. Especially, ρ is said to be conservative (or preserved) provided ρ is contractive and extensive simultaneously.

Based on the fact that every distance ρ is conservative by an isometry, we may raise a question: *Is a mapping an isometry if the mapping preserves certain distances?* Indeed, Aleksandrov [1] raised a question whether a mapping $f : V_1 \rightarrow V_1$ is an isometry provided f preserves a distance ρ , which is known as the *Aleksandrov problem*. Without loss of generality, we may assume $\rho = 1$ when V_1 is a normed space (see [10]).

About twenty years earlier than Aleksandrov, Beckman and Quarles [2] investigated the Aleksandrov problem for the n -dimensional real Euclidean space \mathbb{E}^n .

THEOREM 3.1. (Beckman and Quarles [2]) *Assume that $n \geq 2$ is an integer and $\rho > 0$ is an arbitrary constant. Every mapping $f : \mathbb{E}^n \rightarrow \mathbb{E}^n$ preserving the distance ρ is a linear isometry up to translation.*

They could construct non-isometric mappings preserving unit distance for one-dimensional or for infinite-dimensional real Euclidean spaces (cf. [8]). Thereafter, Rassias [9] raised the question: *Is a mapping between normed spaces an isometry if it preserves two (or more) distances?* Such a problem is called the *Aleksandrov-Rassias problem*. For a strictly convex vector space, Benz gave an affirmative answer to this problem (see [3] and also [4]):

THEOREM 3.2. (Benz [3]) *Assume that V_1 is a real normed space with $\dim V_1 \geq 2$ and V_2 is a real normed space which is strictly convex. Suppose $N \geq 2$ is a fixed integer. If a distance ρ is contractive and $N\rho$ is extensive by a mapping $f : V_1 \rightarrow V_2$, then f is a linear isometry up to translation.*

Now, assume that V_1 is a real (or complex) inner product space and $c_1, c_2, c_3, c_4, c_5, e_1, e_2, e_3, e_4, e_5$ are positive numbers such that there exist points (vectors) x_1, x_2, x_3, x_4, x_5 of V_1 such that they satisfy the conditions in (2.2) as well as

$$\begin{aligned} \|x_1 - x_2\| &= c_1, \quad \|x_2 - x_3\| = c_2, \quad \|x_3 - x_4\| = c_3, \quad \|x_4 - x_5\| = c_4, \quad \|x_5 - x_1\| = c_5, \\ \|x_1 - x_3\| &= e_1, \quad \|x_2 - x_4\| = e_2, \quad \|x_3 - x_5\| = e_3, \quad \|x_4 - x_1\| = e_4, \quad \|x_5 - x_2\| = e_5, \end{aligned} \tag{3.1}$$

as we see in the following figure. (Obviously, due to (2.2), the five points x_1, x_2, x_3, x_4, x_5 lie on a two dimensional subspace of V_1 .)

THEOREM 3.3. *Let V_1 and V_2 be either real inner product spaces or complex inner product spaces. Assume that the distances c_1, c_2, c_3, c_4, c_5 are contractive and the distances e_1, e_2, e_3, e_4, e_5 are extensive by a mapping $f : V_1 \rightarrow V_2$, where c_i 's and e_i 's are given by (3.1) and the corresponding x_i 's satisfy the conditions in (2.2) (see Figure 3.1). Then f preserves all the distances c_i 's and e_i 's.*

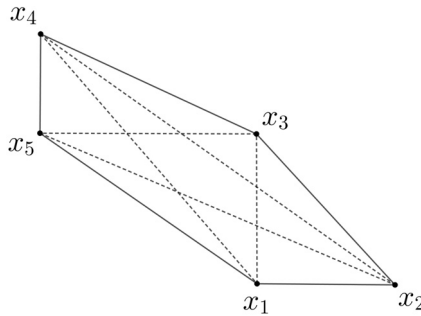


Figure 3.1: $x_4 = x_1 - \phi x_2 + \phi x_3$ and $x_5 = \phi x_1 - \phi x_2 + x_3$

Proof. First, we set $x'_i = f(x_i)$ for all $i \in \{1, 2, \dots, 5\}$. Because the distances c_1, c_2, c_3, c_4, c_5 are contractive by f , we can use Theorem 2.1 to get

$$\begin{aligned} &\phi^2 \{ \|x_1 - x_2\|^2 + \|x_2 - x_3\|^2 + \|x_3 - x_4\|^2 + \|x_4 - x_5\|^2 + \|x_5 - x_1\|^2 \} \\ &\geq \phi^2 \{ \|x'_1 - x'_2\|^2 + \|x'_2 - x'_3\|^2 + \|x'_3 - x'_4\|^2 + \|x'_4 - x'_5\|^2 + \|x'_5 - x'_1\|^2 \} \\ &\geq \|x'_1 - x'_3\|^2 + \|x'_2 - x'_4\|^2 + \|x'_3 - x'_5\|^2 + \|x'_4 - x'_1\|^2 + \|x'_5 - x'_2\|^2. \end{aligned}$$

Moreover, since the distances e_1, e_2, e_3, e_4, e_5 are extensive, we consider (3.1) to obtain

$$\begin{aligned}
 &\phi^2 \{ \|x_1 - x_2\|^2 + \|x_2 - x_3\|^2 + \|x_3 - x_4\|^2 + \|x_4 - x_5\|^2 + \|x_5 - x_1\|^2 \} \\
 &\geq \phi^2 \{ \|x'_1 - x'_2\|^2 + \|x'_2 - x'_3\|^2 + \|x'_3 - x'_4\|^2 + \|x'_4 - x'_5\|^2 + \|x'_5 - x'_1\|^2 \} \\
 &\geq \|x'_1 - x'_3\|^2 + \|x'_2 - x'_4\|^2 + \|x'_3 - x'_5\|^2 + \|x'_4 - x'_1\|^2 + \|x'_5 - x'_2\|^2 \\
 &\geq \|x_1 - x_3\|^2 + \|x_2 - x_4\|^2 + \|x_3 - x_5\|^2 + \|x_4 - x_1\|^2 + \|x_5 - x_2\|^2.
 \end{aligned}$$

Since x_4 and x_5 were given by (2.2) (see Figure 3.1), by the last two inequalities and Theorem 2.1, we conclude that

$$\begin{aligned}
 &\phi^2 \{ \|x_1 - x_2\|^2 + \|x_2 - x_3\|^2 + \|x_3 - x_4\|^2 + \|x_4 - x_5\|^2 + \|x_5 - x_1\|^2 \} \\
 &\geq \phi^2 \{ \|x'_1 - x'_2\|^2 + \|x'_2 - x'_3\|^2 + \|x'_3 - x'_4\|^2 + \|x'_4 - x'_5\|^2 + \|x'_5 - x'_1\|^2 \} \\
 &\geq \|x'_1 - x'_3\|^2 + \|x'_2 - x'_4\|^2 + \|x'_3 - x'_5\|^2 + \|x'_4 - x'_1\|^2 + \|x'_5 - x'_2\|^2 \tag{3.2} \\
 &\geq \|x_1 - x_3\|^2 + \|x_2 - x_4\|^2 + \|x_3 - x_5\|^2 + \|x_4 - x_1\|^2 + \|x_5 - x_2\|^2 \\
 &= \phi^2 \{ \|x_1 - x_2\|^2 + \|x_2 - x_3\|^2 + \|x_3 - x_4\|^2 + \|x_4 - x_5\|^2 + \|x_5 - x_1\|^2 \}.
 \end{aligned}$$

On the other hand, our hypotheses imply that

$$\begin{aligned}
 c_1 &= \|x_1 - x_2\| \geq \|x'_1 - x'_2\|, & c_2 &= \|x_2 - x_3\| \geq \|x'_2 - x'_3\|, \\
 c_3 &= \|x_3 - x_4\| \geq \|x'_3 - x'_4\|, & c_4 &= \|x_4 - x_5\| \geq \|x'_4 - x'_5\|, \\
 c_5 &= \|x_5 - x_1\| \geq \|x'_5 - x'_1\|, & e_1 &= \|x_1 - x_3\| \leq \|x'_1 - x'_3\|, \\
 e_2 &= \|x_2 - x_4\| \leq \|x'_2 - x'_4\|, & e_3 &= \|x_3 - x_5\| \leq \|x'_3 - x'_5\|, \\
 e_4 &= \|x_4 - x_1\| \leq \|x'_4 - x'_1\|, & e_5 &= \|x_5 - x_2\| \leq \|x'_5 - x'_2\|.
 \end{aligned} \tag{3.3}$$

By combining (3.2) and (3.3), we conclude that

$$\begin{aligned}
 \|x_1 - x_2\| &= c_1 = \|x'_1 - x'_2\|, & \|x_2 - x_3\| &= c_2 = \|x'_2 - x'_3\|, \\
 \|x_3 - x_4\| &= c_3 = \|x'_3 - x'_4\|, & \|x_4 - x_5\| &= c_4 = \|x'_4 - x'_5\|, \\
 \|x_5 - x_1\| &= c_5 = \|x'_5 - x'_1\|, & \|x_1 - x_3\| &= e_1 = \|x'_1 - x'_3\|, \\
 \|x_2 - x_4\| &= e_2 = \|x'_2 - x'_4\|, & \|x_3 - x_5\| &= e_3 = \|x'_3 - x'_5\|, \\
 \|x_4 - x_1\| &= e_4 = \|x'_4 - x'_1\|, & \|x_5 - x_2\| &= e_5 = \|x'_5 - x'_2\|.
 \end{aligned}$$

For arbitrarily given $x_1, x_2 \in V_1$ with $\|x_1 - x_2\| = c_1$, we can select three points (vectors) x_3, x_4, x_5 in V_1 such that x_1, x_2, x_3, x_4, x_5 determine a geometrical figure congruent to the one in Figure 3.1. In view of the above argument, we may conclude that $\|x'_1 - x'_2\| = c_1$. For other distances such as $c_2, c_3, c_4, c_5, e_1, e_2, e_3, e_4$ and e_5 , we can apply a similar argument. Therefore, f preserves the distances $c_1, c_2, c_3, c_4, c_5, e_1, e_2, e_3, e_4$ and e_5 . \square

REMARK 3.1. Assume that x_1, x_2, x_3, x_4, x_5 are the vertices of a regular pentagon with a unit side length as we see in Figure 3.2 below. If we let $c_1 = c_2 = c_3 = c_4 = c_5 = 1$ and $e_1 = e_2 = e_3 = e_4 = e_5 = \phi$ in Theorem 3.3, then we see that f preserves the distances 1 and ϕ .

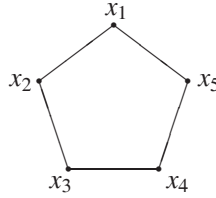


Figure 3.2: regular pentagon

THEOREM 3.4. *Assume that V_1 and V_2 are real Hilbert spaces with $\dim V_1 \geq 3$. If the distance 1 is contractive and the distance ϕ is extensive by a mapping $f : V_1 \rightarrow V_2$, then f is a linear isometry up to translation.*

Proof. By regarding Theorem 3.3 and Remark 3.1, f preserves both the distances 1 and ϕ . We will show that f preserves the distance $\sqrt{2}\phi$. Then because f preserves the distances ϕ and $\sqrt{2}\phi$, we can conclude that f is an isometry up to translation by [11, Theorem 2.8].

Assume that the distance between v_1 and v_3 of V_1 is $\sqrt{2}\phi$, i.e., $\|v_1 - v_3\| = \sqrt{2}\phi$. Because $\dim V_1 \geq 3$, there exists a subspace U of V_1 containing v_1 and v_3 that is (inner product) isomorphic to 3-dimensional Euclidean space \mathbb{E}^3 .

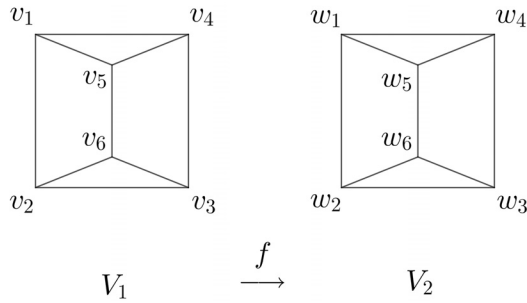


Figure 3.3.

In the first (roof-shaped) figure of Figure 3.3, $\{v_1, v_5, v_6, v_2\}$ is a part of vertices of a regular pentagon of unit side length in U and also $\{v_4, v_5, v_6, v_3\}$ is a part of vertices of another regular pentagon of unit side length in U such that $\|v_1 - v_4\| = \|v_2 - v_3\| = \phi$. In full detail, we have

$$\begin{aligned} &\|v_1 - v_5\| = 1, \quad \|v_4 - v_5\| = 1, \quad \|v_5 - v_6\| = 1, \quad \|v_2 - v_6\| = 1, \quad \|v_3 - v_6\| = 1, \\ &\|v_1 - v_2\| = \phi, \quad \|v_2 - v_3\| = \phi, \quad \|v_3 - v_4\| = \phi, \quad \|v_4 - v_1\| = \phi, \\ &\|v_1 - v_6\| = \phi, \quad \|v_2 - v_5\| = \phi, \quad \|v_3 - v_5\| = \phi, \quad \|v_4 - v_6\| = \phi. \end{aligned}$$

Denote $w_i = f(v_i)$ for $i \in \{1, 2, \dots, 6\}$. Because f preserves the distances 1 and ϕ ,

$$\begin{aligned}
\|w_1 - w_5\| = 1, \quad \|w_4 - w_5\| = 1, \quad \|w_5 - w_6\| = 1, \quad \|w_2 - w_6\| = 1, \quad \|w_3 - w_6\| = 1, \\
\|w_1 - w_2\| = \phi, \quad \|w_2 - w_3\| = \phi, \quad \|w_3 - w_4\| = \phi, \quad \|w_4 - w_1\| = \phi, \\
\|w_1 - w_6\| = \phi, \quad \|w_2 - w_5\| = \phi, \quad \|w_3 - w_5\| = \phi, \quad \|w_4 - w_6\| = \phi.
\end{aligned} \tag{3.4}$$

Let $x_i = w_i - w_1$ for $i \in \{2, 3, \dots, 6\}$. Then

$$x_j - x_k = (w_j - w_1) - (w_k - w_1) = w_j - w_k \tag{3.5}$$

for any $j, k \in \{2, 3, \dots, 6\}$. The distances between 4 points w_1 , w_2 , w_5 , and w_6 are given:

$$\begin{aligned}
\|x_2\| = \|w_2 - w_1\| = \phi, \quad \|x_5 - x_2\| = \|w_5 - w_2\| = \phi, \\
\|x_5\| = \|w_5 - w_1\| = 1, \quad \|x_6 - x_2\| = \|w_6 - w_2\| = 1, \\
\|x_6\| = \|w_6 - w_1\| = \phi, \quad \|x_6 - x_5\| = \|w_6 - w_5\| = 1.
\end{aligned} \tag{3.6}$$

Since

$$\|x_j - x_k\|^2 = \|x_j\|^2 - 2\langle x_j, x_k \rangle + \|x_k\|^2$$

for any $j, k \in \{2, 3, \dots, 6\}$, by using (3.6), we have

$$\langle x_2, x_5 \rangle = \frac{1}{2}(\|x_2\|^2 + \|x_5\|^2 - \|x_2 - x_5\|^2) = \frac{1}{2}(\phi^2 + 1 - \phi^2) = \frac{1}{2}. \tag{3.7}$$

Similarly, we have $\langle x_2, x_6 \rangle = \frac{1}{2}(2\phi^2 - 1)$ and $\langle x_5, x_6 \rangle = \frac{1}{2}\phi^2$.

Hence, we can calculate $\|x_6 - x_5 - \frac{1}{\phi}x_2\|^2$:

$$\begin{aligned}
\left\|x_6 - x_5 - \frac{1}{\phi}x_2\right\|^2 &= \left\langle x_6 - x_5 - \frac{1}{\phi}x_2, x_6 - x_5 - \frac{1}{\phi}x_2 \right\rangle \\
&= \|x_6\|^2 + \|x_5\|^2 + \frac{1}{\phi^2}\|x_2\|^2 - 2\langle x_5, x_6 \rangle - \frac{2}{\phi}\langle x_2, x_6 \rangle + \frac{2}{\phi}\langle x_2, x_5 \rangle \\
&= \phi^2 + 1 + \frac{1}{\phi^2}\phi^2 - \phi^2 - \frac{1}{\phi}(2\phi^2 - 1) + \frac{1}{\phi} \\
&= 0.
\end{aligned}$$

Therefore,

$$x_6 = \frac{1}{\phi}x_2 + x_5. \tag{3.8}$$

Hence, we get

$$0 = x_6 - \frac{1}{\phi}x_2 - x_5 = w_6 - w_1 - \frac{1}{\phi}(w_2 - w_1) - (w_5 - w_1). \tag{3.9}$$

As we see in Figure 3.3, the structures of $\{w_1, w_2, w_5, w_6\}$ and $\{w_4, w_3, w_5, w_6\}$ are congruent. Thus, we can replace w_1, w_2, w_5, w_6 in (3.9) with w_4, w_3, w_5, w_6 , respectively, and use (3.5) to get

$$0 = w_6 - w_4 - \frac{1}{\phi}(w_3 - w_4) - (w_5 - w_4) = x_6 - x_4 - \frac{1}{\phi}(x_3 - x_4) - (x_5 - x_4).$$

Therefore, $x_6 - x_4 = \frac{1}{\phi}(x_3 - x_4) + (x_5 - x_4)$. And it follows from (3.8) and the last equality that

$$x_3 = x_2 + x_4. \quad (3.10)$$

In view of (3.4) and (3.6), the distances between 3 points w_1, w_4, w_5 are given below.

$$\|x_4\| = \|w_4 - w_1\| = \phi, \quad \|x_5\| = \|w_5 - w_1\| = 1, \quad \|x_5 - x_4\| = \|w_5 - w_4\| = 1. \quad (3.11)$$

Hence

$$\langle x_4, x_5 \rangle = \frac{1}{2}(\|x_4\|^2 + \|x_5\|^2 - \|x_4 - x_5\|^2) = \frac{1}{2}(\phi^2 + 1 - 1) = \frac{1}{2}\phi^2. \quad (3.12)$$

By (3.4), (3.6), (3.7), (3.8), (3.9), (3.11), and by (3.12), we have

$$\begin{aligned} \phi^2 &= \|w_6 - w_4\|^2 = \|x_6 - x_4\|^2 = \left\| \frac{1}{\phi}x_2 + x_5 - x_4 \right\|^2 \\ &= \frac{1}{\phi^2}\|x_2\|^2 + \|x_4\|^2 + \|x_5\|^2 + \frac{2}{\phi}\langle x_2, x_5 \rangle - \frac{2}{\phi}\langle x_2, x_4 \rangle - 2\langle x_4, x_5 \rangle \\ &= \frac{1}{\phi^2}\phi^2 + \phi^2 + 1 + \frac{1}{\phi} - \frac{2}{\phi}\langle x_2, x_4 \rangle - \phi^2 \\ &= 2 + \frac{1}{\phi} - \frac{2}{\phi}\langle x_2, x_4 \rangle \end{aligned}$$

and hence

$$\langle x_2, x_4 \rangle = \frac{\phi}{2} \left(2 + \frac{1}{\phi} - \phi^2 \right) = \frac{\phi}{2} \left(2 + \frac{1}{\phi} - \phi - 1 \right) = \frac{1}{2}(\phi + 1 - \phi^2) = 0.$$

Hence, by (3.4), (3.6), (3.10) and the last equality, we get

$$\|x_3\|^2 = \|x_2 + x_4\|^2 = \|x_2\|^2 + \|x_4\|^2 = \|x_2\|^2 + \|w_4 - w_1\|^2 = 2\phi^2,$$

i.e.,

$$\|x_3\| = \|w_3 - w_1\| = \sqrt{2}\phi.$$

Since f preserves distances ϕ and $\sqrt{2}\phi$, we conclude that f is an isometry up to translation by using [11, Theorem 2.8]. \square

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