

## RICCI CURVATURE OF LAGRANGIAN SUBMANIFOLDS IN COMPLEX SPACE FORMS

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*Abstract.* As we showed in [5] and [6], the basic inequalities, involving Riemannian invariants of a Lagrangian submanifold immersed in a complex space form, can be improved using optimization methods. Also in [1] is showed that the improved Chen's inequality from [5] is optimal. In this paper we find another proof for a Chen's inequality, regarding the Ricci curvature [2] and we improve this inequality in the Lagrangian case.

### 1. Optimizations on Riemannian submanifolds

Let  $(N, \tilde{g})$  be a Riemannian manifold,  $(M, g)$  a Riemannian submanifold of it, and

$$f : N \rightarrow R$$

a differentiable function. To these ingredients we attach the optimum problem

$$\min_{x \in M} f(x). \tag{1.1}$$

Let's remember the result obtained in [4].

**THEOREM 1.1.** *If  $x_0 \in M$  is a optimal solution of the problem (1), then*

i)  $(\text{grad } f)(x_0) \in T_{x_0}^\perp M,$

ii) *the bilinear form*

$$\alpha : T_{x_0} M \times T_{x_0} M \rightarrow R,$$

$$\alpha(X, Y) = \text{Hess}_f(X, Y) + \tilde{g}(h(X, Y), (\text{grad } f)(x_0))$$

*is positive semidefinite, where  $h$  is the second fundamental form of the submanifold  $M$  in  $N$ .*

**REMARK 1.1.** The bilinear form  $\alpha$  is nothing else but  $\text{Hess}_{f|_M}(x_0)$ .

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A very nice application of this result is the partial solution of the next problem: *find the 2-plane in the tangent space at the given point  $x$  of a Riemannian manifold  $(M, g)$  which minimize the sectional curvature.* A equivalent conditioned extremum problem is

$$\min R(X, Y, X, Y), \tag{1.2}$$

$$\text{subject to } \|X\| = 1, \|Y\| = 1, g(X, Y) = 0,$$

where  $X$  and  $Y$  are two vectors from  $T_xM$ .

A 2-plane  $\pi \subset T_xM$ ,  $\pi = \text{Sp}\{X, Y\}$  which verifies the first condition from Theorem 1 is called *critical plane for the sectional curvature at the point  $x$* . Using Theorem 1, in [4] we showed that a 2-plane  $\pi$  is a critical plane for the sectional curvature at the point  $x$  if and only if for every tangent vectors  $U, V, W \in \pi$  the vector  $R(U, V)W$  lies in  $\pi$ , where  $R$  is the curvature tensor of the Riemannian manifold  $(M, g)$ .

### 2. The Ricci curvature of a submanifold in a real space form

In this section we give a new proof of the next inequality

**THEOREM 2.1.** (Chen [2]). *Let  $M$  be a  $n$ -dimensional Riemannian submanifold of a real space form  $(\tilde{M}(c), g)$  and  $x$  a point in  $M$ . Then, for each unit vector  $X \in T_xM$ , we have*

$$\text{Ric}(X) \leq (n - 1)c + \frac{n^2}{4} \|H\|^2,$$

where  $H$  is the mean curvature vector of  $M$  in  $\tilde{M}(c)$  and  $\text{Ric}(X)$  the Ricci curvature of  $M$  at  $x$ .

*Proof.* We fix the point  $x$  in  $M$ , the vector  $X \in T_xM$ , with  $\|X\| = 1$ , the orthonormal frame  $\{e_1, e_2, \dots, e_n\}$  in  $T_xM$  such that  $e_1 = X$  and  $\{e_{n+1}, e_{n+2}, \dots, e_m\}$  a orthonormal frame in  $T_x^\perp M$ .

From Gauss equation we have

$$\begin{aligned} \tilde{R}(e_1, e_j, e_1, e_j) &= R(e_1, e_j, e_1, e_j) - \tilde{g}(h(e_1, e_1), h(e_j, e_j)) + \tilde{g}(h(e_1, e_j), h(e_1, e_j)) \\ &= R(e_1, e_j, e_1, e_j) - \sum_{r=n+1}^m (h_{11}^r h_{jj}^r - (h_{1j}^r)^2), \quad j \in \overline{2, n}. \end{aligned} \tag{2.1}$$

Using the fact that the sectional curvature of  $\tilde{M}(c)$  is constant, we obtain

$$(n - 1)c = \text{Ric}(X) - \sum_{r=n+1}^m \sum_{j=2}^n (h_{11}^r h_{jj}^r - (h_{1j}^r)^2), \tag{2.2}$$

therefore

$$\text{Ric}(X) - (n - 1)c = \sum_{r=n+1}^m \sum_{j=2}^n (h_{11}^r h_{jj}^r - (h_{1j}^r)^2) \leq \sum_{r=n+1}^m \sum_{j=2}^n h_{11}^r h_{jj}^r. \tag{2.3}$$

For  $r \in \overline{n+1, m}$ , let us consider the quadratic form

$$f_r : R^n \rightarrow R,$$

$$f_r(h_{11}^r, h_{22}^r, \dots, h_{nn}^r) = \sum_{j=2}^n h_{11}^r h_{jj}^r$$

and the constrained extremum problem

$$\max f_r,$$

subject to  $P : h_{11}^r + h_{22}^r + \dots + h_{nn}^r = k^r,$

where  $k^r$  is a real constant.

The gradient vector of  $f_r$  is given by

$$\text{grad } f_r = \left( \sum_{j=2}^n h_{jj}^r, h_{11}^r, \dots, h_{11}^r \right).$$

Let us denote with  $p = (h_{11}^r, h_{22}^r, \dots, h_{nn}^r)$  a optimal solution of the problem in question.

As  $\text{grad } f_r$  is normal to  $P$  at the point  $p$ , we obtain

$$h_{11}^r = \sum_{j=2}^n h_{jj}^r = \frac{k^r}{2}. \tag{2.4}$$

Let  $q \in P$  be an arbitrary point.

The bilinear form  $\alpha : T_q P \times T_q P \rightarrow R$  has the expression

$$\alpha(X, Y) = \text{Hess}(f_r)(X, Y) + \langle h'(X, Y), \text{grad } f_r(q) \rangle,$$

where  $h'$  is the second fundamental form of  $P$  in  $R^n$ , and  $\langle \cdot, \cdot \rangle$  is the standard inner-product on  $R^n$ .

In the standard frame of  $R^n$ , the Hessian of  $f_r$  has the matrix

$$\begin{pmatrix} 0 & 1 & \dots & 1 \\ 1 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 1 & 0 & \dots & 0 \end{pmatrix}.$$

A vector  $X \in T_q P$  satisfies  $\sum_{i=1}^n X^i = 0$ .

As  $P$  is totally geodesic in  $R^n$ , we have  $\alpha(X, X) = 2 \sum_{j=2}^n X^1 X^j = -2(X^1)^2$ .

So  $f_r|_P$  is a concave function, therefore the points which satisfies the relation (2.4) are global maximum points for  $f_r|_P$ .

One gets

$$f_r \leq \frac{(k^r)^2}{4} = \frac{1}{4} \left( \sum_{i=1}^n h_{ii}^r \right)^2 = \frac{n^2}{4} (H^r)^2. \tag{2.5}$$

Using (2.3) and (2.5) we find

$$\text{Ric}(X) - (n - 1)c \leq \sum_{r=n+1}^m \frac{n^2}{4} (H^r)^2 = \frac{n^2}{4} \|H\|^2. \tag{2.6}$$

**3. The Ricci curvature of a Lagrangian submanifold in a complex space form**

Let  $(\tilde{M}, \tilde{g}, J)$  be a Kähler manifold of real dimension  $2m$ . A submanifold  $M$  of dimension  $n$  of  $(\tilde{M}, \tilde{g}, J)$  is called a totally real submanifold if for any point  $x$  in  $M$  the relation  $J(T_x M) \subset T_x^\perp M$  holds.

If, in addition,  $n = m$ , then  $M$  is called Lagrangian submanifold. For a Lagrangian submanifold, the relation  $J(T_x M) = T_x^\perp M$  occurs.

A Kähler manifold with constant holomorphic sectional curvature is called a complex space form and is denoted by  $\tilde{M}(c)$ . The Riemann curvature tensor  $\tilde{R}$  of  $\tilde{M}(c)$  satisfies the relation

$$\tilde{R}(X, Y)Z = \frac{c}{4} \{ \tilde{g}(Y, Z)X - \tilde{g}(X, Z)Y + \tilde{g}(JY, Z)JX - \tilde{g}(JX, Z)JY + 2\tilde{g}(X, JY)JZ \}.$$

A totally real submanifold of real dimension  $n$  in a complex space form  $\tilde{M}(c)$  of real dimension  $2m$  satisfies a Chen’s inequality

**THEOREM 3.1. (Chen).** *Let  $M$  be a  $n$ -dimensional Riemannian submanifold of a complex space form  $(\tilde{M}(c), g)$  and  $x$  a point in  $M$ . Then, for each unit vector  $X \in T_x M$ , we have*

$$\text{Ric}(X) \leq (n - 1)\frac{c}{4} + \frac{n^2}{4} \|H\|^2,$$

where  $H$  is the mean curvature vector of  $M$  in  $\tilde{M}(c)$  and  $\text{Ric}(X)$  the Ricci curvature of  $M$  at  $x$ .

**REMARK 3.1.** i) If  $M$  is a totally real submanifold of real dimension  $n$  in a complex space form  $\tilde{M}(c)$  of real dimension  $2m$ , then

$$A_{JY}X = -Jh(X, Y) = A_{JX}Y,$$

where  $X$  and  $Y$  are two arbitrary vector fields.

ii) Let  $m = n$  ( $M$  is Lagrangian in  $\tilde{M}(c)$ ). If we consider the point  $x \in M$ , the orthonormal frames  $\{e_1, \dots, e_n\}$  in  $T_x M$  and  $\{Je_1, \dots, Je_n\}$  in  $T_x^\perp M$ , then

$$h^i_{jk} = h^j_{ik}, \forall i, j, k \in \overline{1, n},$$

where  $h^i_{jk}$  is the component after  $Je_i$  of the vector  $h(e_j, e_k)$ .

With these ingredients we prove the next result which improve Chen’s inequality in the Lagrangian case.

**THEOREM 3.2.** *Let  $M$  be a Lagrangian submanifold in a complex space form  $\tilde{M}(c)$  of real dimension  $2n$ ,  $n \geq 2$ ,  $x$  a point in  $M$  and  $X$  a unit tangent vector in  $T_xM$ . Then we have*

$$\text{Ric}(X) \leq \frac{n-1}{4}(c+n\|H\|^2).$$

*Proof.* We fix the point  $x$  in  $M$ , the tangent vector  $X \in T_xM$ , with  $\|X\| = 1$ , the orthonormal frame  $\{e_1, e_2, \dots, e_n\}$  in  $T_xM$  such that  $e_1 = X$  and  $\{Je_1, Je_2, \dots, Je_n\}$  a orthonormal frame in  $T_x^\perp M$ .

From the Gauss equation we get

$$\begin{aligned} \tilde{R}(e_1, e_j, e_1, e_j) &= R(e_1, e_j, e_1, e_j) - \tilde{g}(h(e_1, e_1), h(e_j, e_j)) + \tilde{g}(h(e_1, e_j), h(e_1, e_j)) \\ &= R(e_1, e_j, e_1, e_j) - \sum_{r=1}^n (h_{11}^r h_{jj}^r - (h_{1j}^r)^2), \quad \forall j \in \overline{2, n}. \end{aligned} \tag{4.1}$$

Therefore

$$(n-1)\frac{c}{4} = \text{Ric}(X) - \sum_{r=1}^n \sum_{j=2}^n (h_{11}^r h_{jj}^r - (h_{1j}^r)^2) \tag{4.2}$$

which implies

$$\begin{aligned} \text{Ric}(X) - (n-1)\frac{c}{4} &= \sum_{r=1}^n \sum_{j=2}^n (h_{11}^r h_{jj}^r - (h_{1j}^r)^2) \\ &\leq \left( \sum_{r=1}^n \sum_{j=2}^n h_{11}^r h_{jj}^r \right) - \sum_{j=2}^n (h_{1j}^1)^2 - \sum_{j=2}^n (h_{1j}^j)^2 \\ &= \left( \sum_{r=1}^n \sum_{j=2}^n h_{11}^r h_{jj}^r \right) - \sum_{j=2}^n (h_{11}^j)^2 - \sum_{j=2}^n (h_{jj}^1)^2. \end{aligned} \tag{4.3}$$

Let us consider the quadratic forms

$$\begin{aligned} f_1, f_r &: R^n \rightarrow R, \\ f_1(h_{11}^1, h_{22}^1, \dots, h_{nn}^1) &= \sum_{j=2}^n h_{11}^1 h_{jj}^1 - \sum_{j=2}^n (h_{1j}^1)^2, \\ f_r(h_{11}^r, h_{22}^r, \dots, h_{nn}^r) &= \sum_{j=2}^n h_{11}^r h_{jj}^r - (h_{11}^r)^2, \end{aligned}$$

where  $r \in \overline{2, n}$ .

We need the maximum of  $f_1$  and  $f_2$ . For  $f_r$ ,  $r \in \overline{3, n}$ , we can solve similar problems.

We start with the problem

$$\begin{aligned} &\max f_1, \\ &\text{subject to } P : h_{11}^1 + h_{22}^1 + \dots + h_{nn}^1 = k^1, \end{aligned}$$

where  $k^1$  is a real constant.

The partial derivatives of the function  $f_1$  are

$$\frac{\partial f_1}{\partial h_{11}^1} = \sum_{j=2}^n h_{jj}^1, \quad (4.4)$$

$$\frac{\partial f_1}{\partial h_{jj}^1} = h_{11}^1 - 2h_{jj}^1, \quad \forall j \in \overline{2, n}. \quad (4.5)$$

As for a optimal solution  $(h_{11}^1, h_{22}^1, \dots, h_{nn}^1)$  of the problem in question the vector  $\text{grad } f_1$  is normal to  $P$ , we obtain

$$h_{22}^1 = h_{33}^1 = \dots = h_{nn}^1 = a^1 \quad (4.6)$$

and

$$h_{11}^1 - 2h_{22}^1 = \sum_{j=2}^n h_{jj}^1. \quad (4.7)$$

Using (4.6) and (4.7) we find

$$h_{11}^1 = (n+1)a^1. \quad (4.8)$$

From the relation  $h_{11}^1 + h_{22}^1 + \dots + h_{nn}^1 = k^1$ , we get

$$(n+1)a^1 + (n-1)a^1 = k^1, \quad (4.9)$$

therefore

$$a^1 = \frac{k^1}{2n}. \quad (4.10)$$

As  $f_1$  is obtained from the function studied in previous section by subtracting some square terms,  $f_1|_P$  will have the Hessian negative semidefinite. Consequently the point  $(h_{11}^1, h_{22}^1, \dots, h_{nn}^1)$  given by the relations (4.6), (4.8) and (4.10) is a maximum point, and hence

$$f_1 \leq (n+1)a^1(n-1)a^1 - (n-1)(a^1)^2 = \frac{n-1}{4n}(k^1)^2 = \frac{n(n-1)}{4}(H^1)^2. \quad (4.11)$$

Further on, we shall consider the problem

$$\max f_2,$$

$$\text{subject to } P : h_{11}^2 + h_{22}^2 + \dots + h_{nn}^2 = k^2,$$

where  $k^2$  is a real constant.

The first two partial derivatives of the function  $f_2$  are

$$\frac{\partial f_2}{\partial h_{11}^2} = \sum_{j=2}^n h_{jj}^2 - 2h_{11}^2, \quad (4.12)$$

$$\frac{\partial f_2}{\partial h_{jj}^2} = h_{11}^2, \quad \forall j \in \overline{2, n}. \tag{4.13}$$

As for a optimal solution  $(h_{11}^2, h_{22}^2, \dots, h_{nn}^2)$  of the problem in question the vector  $\text{grad} f_2$  is normal to  $P$ , we obtain

$$3h_{11}^2 = \sum_{j=2}^n h_{jj}^2 = 3a^2. \tag{4.14}$$

Using the relation  $h_{11}^2 + h_{22}^2 + \dots + h_{nn}^2 = k^2$ , one gets

$$a^2 + 3a^2 = k^2, \tag{4.15}$$

therefore

$$a^2 = \frac{k^2}{4}. \tag{4.16}$$

With an similar argument to those in the previous problem we obtain that the points  $(h_{11}^2, h_{22}^2, \dots, h_{nn}^2)$  given by the relations (4.14) and (4.16) are global maximum points. Therefore

$$f_2 \leq a^2 3a^2 - (a^2)^2 = 2(a^2)^2 = \frac{(k^2)^2}{8} = \frac{n^2}{8} (H^2)^2. \tag{4.17}$$

Similarly one gets

$$f_r \leq \frac{n^2}{8} (H^r)^2, \quad \forall r \in \overline{2, n}. \tag{4.18}$$

As  $\frac{n(n-1)}{4} \geq \frac{n^2}{8}, \forall n \geq 2$ , using (4.11) and (4.18) we find

$$f_r \leq \frac{n(n-1)}{4} (H^r)^2, \quad \forall r \in \overline{1, n}. \tag{4.19}$$

From (4.3) and (4.19) it follows

$$\text{Ric}(X) - (n-1)\frac{c}{4} \leq \frac{n(n-1)}{4} \sum_{r=1}^n (H^r)^2 = \frac{n(n-1)}{4} \|H\|^2, \tag{4.20}$$

therefore

$$\text{Ric}(X) \leq \frac{n-1}{4} (c + n \|H\|^2). \tag{4.21}$$

REMARK 3.2. i) If the mean curvature vector field  $H$  vanish at the point  $x \in M$ , then in precedent inequality the equality occurs for a tangent vector  $X \in T_x M$  if and only if  $h(X, Y) = 0, \forall Y \in T_x M$ .

ii) If  $n \geq 3$ , the mean curvature vector field  $H$  don't vanish at the point  $x \in M$  and the tangent vector  $X \in T_x M$  satisfies

$$\text{Ric}(X) = \frac{n-1}{4} (c + n \|H\|^2),$$

then  $X = \frac{\pm JH}{\|H\|}$ . Indeed, the above equality implies that  $H^2, H^3, \dots, H^n$  are 0. Consequently, the mean curvature vector  $H$  is colinear with  $Je_1$ . It follows that  $JH$  is colinear with  $X$ , therefore  $X = \frac{\pm JH}{\|H\|}$ .

iii) If  $n \geq 3$ , in theorem 4 the equality occurs for any tangent vector  $X \in T_xM$  if and only if  $x$  is a totally geodesic point.

iv) If  $n = 2$ , in theorem 4 the equality occurs for any tangent vector  $X \in T_xM$  if and only if there is an orthonormal frame  $\{e_1, e_2\}$  in  $T_xM$  in which the Weingarten operators take the following form

$$A_{Je_1} = \begin{pmatrix} 3a^1 & a^2 \\ a^2 & a^1 \end{pmatrix}, \quad A_{Je_2} = \begin{pmatrix} a^2 & a^1 \\ a^1 & 3a^2 \end{pmatrix}.$$

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