

MULTIPLE-SET SPLIT FEASIBILITY PROBLEMS FOR A FINITE FAMILY OF DEMICONTRACTIVE MAPPINGS IN HILBERT SPACES

LI-JUAN QIN AND GANG WANG*

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Abstract. In this paper, we introduce an iterative algorithm for solving the multiple-set split feasibility problems for a finite family demicontractive mappings in Hilbert spaces. The results presented in this paper improve and extend some recent corresponding results in [4], [7], [9], [10], [13], [14].

1. Introduction

Let H_1 and H_2 be two real Hilbert spaces and let C and Q be nonempty closed convex subset of H_1 and H_2 , respectively. The split feasibility problem (*SFP*) is formulated as finding a point x^* with the property

$$x^* \in C \quad Ax^* \in Q, \tag{1.1}$$

where $A : H_1 \rightarrow H_2$ is a bounded linear operator.

The *SFP* in finite-dimensional Hilbert spaces was first introduced by Censor and Elfving [1] for modeling inverse problems which arise from phase retrievals and in medical image reconstruction [2]. Recently, it has been found that the *SFP* can also be used in various disciplines such as image restoration, computer tomograph, and radiation therapy treatment planning [3–8].

The *SFP* in an infinite-dimensional Hilbert space can be found in [9–11].

Assuming that the *SFP* is consistent (i.e.(1.1)) has a solution), it is not hard to see that

$$x^* = P_C(I + \gamma A^*(P_Q - I)Ax^*, \forall x \in C, \tag{1.2}$$

where P_C and P_Q are the (orthogonal) projection onto C and Q , respectively, $\gamma > 0$, and A^* denotes the adjoint of A . That is, x^* solves the *SFP* (1.1) if and only if x^* solves the fixed point equation (1.2) [see 9]. This implies that we can use fixed point algorithms to solve *SFP*.

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* The corresponding author.

T is said to be demicontractive (see for example [12]) if there exists a constant $\beta \in [0, 1)$ such that

$$\|Tx - q\|^2 \leq \|x - q\|^2 + \beta \|x - Tx\|^2, \quad \forall (x, q) \in H \times \text{Fix}(T), \tag{1.3}$$

which is equivalent to

$$\langle x - Tx, x - q \rangle \geq \frac{1 - \beta}{2} \|x - Tx\|^2, \quad \forall (x, q) \in H \times \text{Fix}(T), \tag{1.4}$$

(1.3) is also equivalent to

$$\langle x - Tx, q - Tx \rangle \leq \frac{1 + \beta}{2} \|x - Tx\|^2, \quad \forall (x, q) \in H \times \text{Fix}(T), \tag{1.5}$$

An operator satisfying (1.3) will be referred to as a β -demicontractive mapping. It is worth noting that the class of demicontractive maps contains important operators such as the quasi-nonexpansive maps and the strictly pseudocontractive maps with fixed points.

The split common fixed point problems for quasi-nonexpansive mappings and demicontractive mappings in the setting of Hilbert space was introduced and studied by Moudafi [13, 14]. In [14], Moudafi proposed the following iterative algorithm for solving split common fixed problem for demicontractive mappings: for arbitrarily chosen $x^* \in H_1$,

$$\begin{cases} u_n = x_n + \gamma A^*(T - I)Ax_n, \\ x_{n+1} = (1 - \alpha_n)u_n + \alpha_n Uu_n, \quad n \in N \end{cases}$$

they proved that $\{x_n\}$ converges weakly to a split common fixed point x^* , where $U : H_1 \rightarrow H_1$ and $T : H_2 \rightarrow H_2$ are two demicontractive mappings, $A : H_1 \rightarrow H_2$ is a bounded linear operator, λ is the spectral radius of the operator AA^* . Inspired and motivated by the recent work of Moudafi [13,14], in this paper, we study the following multiple-set split feasibility problem (*MSSFP*) for a finite family of demicontractive mappings in Hilbert spaces.

$$x^* \in C \quad \text{such that} \quad Ax^* \in Q, \tag{1.6}$$

where $A : H_1 \rightarrow H_2$ is a bounded linear operator, $K_i : H_1 \rightarrow H_1$ and $T_i : H_2 \rightarrow H_2$, $i = 1, 2, \dots, N$ are demicontractive mappings, $C := \cap_{i=1}^N F(K_i) \neq \emptyset$ and $Q := \cap_{i=1}^N F(T_i) \neq \emptyset$. In the sequel, we use Γ to denote the set of solutions of *MSSFP* (1.6), i.e.,

$$\Gamma = \{x \in C, Ax \in Q\}. \tag{1.7}$$

The results presented in this paper improve and extend some recent corresponding results in [4], [7], [9], [10], [13], [14].

2. Preliminaries

Throughout this paper, Let H_1 and H_2 be two real Hilbert spaces. We denote the strong convergence, weak convergence of a sequence $\{x_n\}$ to a point $x \in X$ by $x_n \rightarrow x$, $x_n \rightharpoonup x$, respectively, and $F(T)$ is the fixed point set of a mapping T .

Let E be a Banach space. A mapping $T : E \rightarrow E$ is said to be demi-closed at origin, if for any sequence $\{x_n\} \subset E$ with $x_n \rightharpoonup x^*$ and $\|(I - T)x_n\| \rightarrow 0$, then $x^* = Tx^*$.

A Banach space E is said to satisfy Opial's condition, if for any sequence $\{x_n\}$ in E , $x_n \rightharpoonup x^*$ implies that

$$\liminf_{n \rightarrow \infty} \|x_n - x^*\| < \liminf_{n \rightarrow \infty} \|x_n - y\|, \quad \forall y \in E \text{ with } y \neq x^*. \tag{2.1}$$

It is well known that every Hilbert space satisfies Opial's condition.

A mapping $T : C \rightarrow E$ is said to be semi-compact, if for any sequence $\{x_n\}$ in C such that $\|x_n - Tx_n\| \rightarrow 0, (n \rightarrow \infty)$, there exists subsequence $\{x_{n_j}\}$ of $\{x_n\}$ such that $\{x_{n_j}\}$ converges strongly to $x^* \in C$.

We state a key property of the relaxed operator $T_\alpha := (1 - \alpha)I + \alpha T$.

Let T be a β -demicontractive self-mapping on H with $Fix(T) \neq \emptyset$ and set $T_\alpha := (1 - \alpha)I + \alpha T$ for $\alpha \in (0, 1]$. Then, T_α is quasi-nonexpansive if $\alpha \in [0, 1 - \beta]$.

Indeed, for any arbitrary element $(x, q) \in H \times Fix(T)$, we have

$$\|T_\alpha x - q\|^2 = \|x - q\|^2 - 2\alpha \langle x - q, x - Tx \rangle + \alpha^2 \|Tx - x\|^2, \tag{2.2}$$

which according to (1.3) yields

$$\|T_\alpha x - q\|^2 \leq \|x - q\|^2 - \alpha(1 - \beta - \alpha) \|Tx - x\|^2. \tag{2.3}$$

Furthermore, it is obvious that $Fix(T) = Fix(T_\alpha)$ if $\alpha \neq 0$. As a consequence, the operator T_α is quasi-nonexpansive for $\alpha \in [0, 1 - \beta]$ and $Fix(T)$ is a closed convex subset of H .

3. Main Results

THEOREM 1. *Let H_1 and H_2 be two Hilbert spaces and A be a bounded linear operator from H_1 to H_2 , let $S_i : H_1 \rightarrow H_2$ be β_i -demicontractive and $T_i : H_2 \rightarrow H_2$ be μ_i -demicontractive satisfying $\cap_{i=1}^N F(S_i) = C$ and $\cap_{i=1}^N F(T_i) = Q$, $i = 1, 2, \dots, N$. For any $x_0 \in H_1$, $\{x_n\}$ is defined by*

$$\begin{cases} y_n = x_n + \gamma A^*(T_n - I)Ax_n, \\ x_{n+1} = (1 - \alpha_n)y_n + \alpha_n S_n y_n, \quad n \in N, \end{cases} \tag{3.1}$$

where λ is the spectral radius of the operator A^*A , $T_n = T_{n(mod N)}, S_n = S_{n(mod N)}, \forall n \geq 1$, γ and $\{\alpha_n\}$ satisfy the following conditions:

- (1) $C := \cap_{i=1}^N F(S_i) \neq \emptyset, Q := \cap_{i=1}^N F(T_i) \neq \emptyset$;
- (2) $\mu = \max_{1 \leq i \leq N} \mu_i < 1, \gamma \in (0, \frac{1-\mu}{\lambda})$;
- (3) $\beta = \max_{1 \leq i \leq N} \beta_i < 1, \alpha_n \in (\delta, 1 - \beta - \delta)$.

If $S_i - I$ and $T_i - I$ ($i = 1, 2, \dots, N$) are demi-closed at zero and $\Gamma \neq \emptyset$, then the sequences $\{x_n\}$ and $\{y_n\}$ both converge weakly to a split common fixed point $x^* \in \Gamma$.

Proof. Taking $q \in \Gamma$, this means that $q \in \cap_{i=1}^N F(S_i) = C$ and $q \in \cap_{i=1}^N F(T_i) = Q$. Using (2.3), we have

$$\begin{aligned} \|x_{n+1} - q\|^2 &\leq \|y_n - q\|^2 - \alpha_n(1 - \beta_n - \alpha_n)\|S_n y_n - y_n\|^2 \\ &\leq \|y_n - q\|^2 - \alpha_n(1 - \beta - \alpha_n)\|S_n y_n - y_n\|^2, \end{aligned} \quad (3.2)$$

where

$$\begin{aligned} \|y_n - q\|^2 &= \|x_n + \gamma A^*(T_n - I)Ax_n - q\|^2 \\ &= \|x_n - q\|^2 + \gamma^2 \|A^*(T_n - I)Ax_n\|^2 + 2\gamma \langle x_n - q, A^*(T_n - I)Ax_n \rangle \\ &= \|x_n - q\|^2 + \gamma^2 \langle (T_n - I)Ax_n, AA^*(T_n - I)Ax_n \rangle \\ &\quad + 2\gamma \langle x_n - q, A^*(T_n - I)Ax_n \rangle. \end{aligned} \quad (3.3)$$

From the definition of λ , we have

$$\begin{aligned} \gamma^2 \langle (T_n - I)Ax_n, AA^*(T_n - I)Ax_n \rangle &\leq \lambda \gamma^2 \langle (T_n - I)Ax_n, (T_n - I)Ax_n \rangle \\ &\leq \lambda \gamma^2 \|(T_n - I)Ax_n\|^2. \end{aligned} \quad (3.4)$$

It follows from (1.5) that

$$\begin{aligned} 2\gamma \langle x_n - q, A^*(T_n - I)Ax_n \rangle &= 2\gamma \langle A(x_n - q), (T_n - I)Ax_n \rangle \\ &= 2\gamma \langle A(x_n - q + (T_n - I)Ax_n - (T_n - I)Ax_n), (T_n - I)Ax_n \rangle \\ &= 2\gamma \langle (T_n - I)Ax_n - Aq, (T_n - I)Ax_n \rangle - \|(T_n - I)Ax_n\|^2 \\ &\leq 2\gamma \left[\frac{1+\mu}{2} \|(T_n - I)Ax_n\|^2 - \|(T_n - I)Ax_n\|^2 \right] \\ &= -\gamma(1 - \mu)\|(T_n - I)Ax_n\|^2. \end{aligned} \quad (3.5)$$

So,

$$\begin{aligned} \|x_{n+1} - q\|^2 &\leq \|x_n - q\|^2 + \lambda \gamma^2 \|(T_n - I)Ax_n\|^2 - \gamma(1 - \mu)\|(T_n - I)Ax_n\|^2 \\ &\quad - \alpha_n(1 - \beta - \alpha_n)\|S_n y_n - y_n\|^2 \\ &\leq \|x_n - q\|^2 - \gamma(1 - \mu - \lambda \gamma)\|(T_n - I)Ax_n\|^2 \\ &\quad - \alpha_n(1 - \beta - \alpha_n)\|S_n y_n - y_n\|^2. \end{aligned} \quad (3.6)$$

By the assumption on γ , β , μ and α_n , we obtain

$$\|x_{n+1} - q\| \leq \|x_n - q\|, \quad n \geq 1. \quad (3.7)$$

This implies $\{x_n\}$ is bounded. From (3.7), we know that the sequence $\{\|x_n - q\|\}$ is monotonically decreasing, therefore, $\lim_{n \rightarrow \infty} \|x_n - q\|$ exists for each $q \in \Gamma$. It follows from (3.6) that

$$\begin{aligned} \gamma(1 - \mu - \lambda \gamma)\|(T_n - I)Ax_n\|^2 + \alpha_n(1 - \beta - \alpha_n)\|S_n y_n - y_n\|^2 \\ \leq \|x_n - q\|^2 - \|x_{n+1} - q\|^2 \rightarrow 0, \text{ as } n \rightarrow \infty. \end{aligned}$$

Since $\gamma > 0$, $1 - \mu - \lambda \gamma > 0$ and $1 - \beta - \alpha_n > 0$, we can obtain

$$\lim_{n \rightarrow +\infty} \|(T_n - I)Ax_n\| = 0. \quad (3.8)$$

$$\lim_{n \rightarrow +\infty} \|(S_n - I)y_n\| = 0. \tag{3.9}$$

For each fixed $j \in \{1, 2, \dots, N\}$, then $\{\|Ax_{iN+j} - T_j Ax_{iN+j}\|\}$ is a subsequence of $\{\|(T_n - I)Ax_n\|\}$, so, we have

$$\lim_{i \rightarrow \infty} \|Ax_{iN+j} - T_j Ax_{iN+j}\| = 0. \tag{3.10}$$

Similarly,

$$\lim_{i \rightarrow \infty} \|y_{iN+j} - S_j y_{iN+j}\| = 0. \tag{3.11}$$

It follows from (3.3), (3.4) and (3.5) that

$$\|y_n - q\|^2 \leq \|x_n - q\|^2 - \gamma(1 - \mu - \lambda\gamma)\|(T_n - I)Ax_n\|^2.$$

Thus, since $\{x_n\}$ is bounded, we know that $\{y_n\}$ is bounded. Therefore, there exists a subsequence $\{y_{n_i}\}$ of $\{y_n\}$ such that $y_{n_i} \rightharpoonup x^* \in H_1$. Moreover, for any positive integer $j = 1, 2, \dots, N$, there exists a subsequence $\{n_i(l)\}$ of $\{n_i\}$ with $n_i(l) \pmod N = j$ such that $y_{n_i(l)} \rightharpoonup x^*$. It follows from (3.11) that

$$\lim_{n_i(l) \rightarrow \infty} \|y_{n_i(l)} - S_j y_{n_i(l)}\| = 0. \tag{3.12}$$

Since S_j is demi-closed at origin for each $j = 1, 2, \dots, N$, it follows that $x^* \in C = \bigcap_{j=1}^N F(S_j)$. It follows from (3.1) and (3.10) that

$$x_{n_i} = y_{n_i} - \gamma A^*(T_{n_i} - I)Ax_{n_i} \rightharpoonup x^*. \tag{3.13}$$

Since A is a bounded linear operator, we know that $Ax_{n_i} \rightharpoonup Ax^*$. For any positive integer $k = 1, 2, \dots, N$, there exists a subsequence $\{n_i(k)\}$ of $\{n_i\}$ with $n_i(k) \pmod N = k$ such that $Ax_{n_i(k)} \rightharpoonup Ax^*$. Using (3.10), we have

$$\lim_{n_i(k) \rightarrow \infty} \|Ax_{n_i(k)} - S_k Ax_{n_i(k)}\| = 0. \tag{3.14}$$

Since T_k is demi-closed at origin for each $k = 1, 2, \dots, N$, it follows that $Ax^* \in Q = \bigcap_{k=1}^N F(T_k)$. Therefore, $x^* \in \Gamma$, i.e., x^* is a solution of *MSSFP* (1.6).

Finally, we show that $x_n \rightharpoonup x^*$ and $y_n \rightharpoonup x^*$.

Assume that there exists another subsequence $\{y_{n_j}\}$ of $\{y_n\}$ such that $\{y_{n_j}\}$ converges weakly to a point $y^* \in H$ with $y^* \neq x^*$. Using the same argument above, we know that $y^* \in \Gamma$. In addition, from (3.3) and (3.8), we know that $\lim_{n \rightarrow \infty} \|y_n - q\|$ exists for each $q \in \Gamma$. Thus, since each Hilbert space possesses Opial property, we have

$$\begin{aligned} \liminf_{i \rightarrow \infty} \|y_{n_i} - x^*\| &< \liminf_{i \rightarrow \infty} \|y_{n_i} - y^*\| = \lim_{n \rightarrow \infty} \|y_n - y^*\| \\ &= \liminf_{j \rightarrow \infty} \|y_{n_j} - y^*\| < \liminf_{j \rightarrow \infty} \|y_{n_j} - x^*\| \\ &= \lim_{n \rightarrow \infty} \|y_n - x^*\| = \liminf_{i \rightarrow \infty} \|y_{n_i} - x^*\|, \end{aligned}$$

which is a contradiction. This implies that $\{y_n\}$ converges weakly to the point $x^* \in \Gamma$. On the other hand, from (3.1) and (3.8), we can obtain

$$x_n = y_n - \gamma A^*(T_n - I)Ax_n \rightharpoonup x^*, \quad (n \rightarrow \infty).$$

Therefore, the sequences $\{x_n\}$ and $\{y_n\}$ both converge weakly to a split common fixed point $x^* \in \Gamma$. The proof is completed. \square

THEOREM 2. *Let H_1 and H_2 be two Hilbert spaces and A be a bounded linear operator from H_1 to H_2 , let $S_i : H_1 \rightarrow H_2$ be β_i -demicontractive and $T_i : H_2 \rightarrow H_2$ be μ_i -demicontractive satisfying $\cap_{i=1}^N F(S_i) = C$ and $\cap_{i=1}^N F(T_i) = Q$, $i = 1, 2, \dots, N$. For any $x_0 \in H_1$, $\{x_n\}$ is defined by*

$$\begin{cases} y_n = x_n + \gamma A^*(T_n - I)Ax_n, \\ x_{n+1} = (1 - \alpha_n)y_n + \alpha_n S_n y_n, \end{cases} \quad n \in N, \tag{3.15}$$

where λ is the spectral radius of the operator A^*A , $T_n = T_{n(\text{mod } N)}$, $S_n = S_{n(\text{mod } N)}$, $\forall n \geq 1$, γ and $\{\alpha_n\}$ satisfy the following conditions:

- (1) $C := \cap_{i=1}^N F(S_i) \neq \emptyset$, $Q := \cap_{i=1}^N F(T_i) \neq \emptyset$;
- (2) $\mu = \max_{1 \leq i \leq N} \mu_i < 1$, $\gamma \in (0, \frac{1-\mu}{\lambda})$;
- (3) $\beta = \max_{1 \leq i \leq N} \beta_i < 1$, $\alpha_n \in (\delta, 1 - \beta - \delta)$.

If one of the mappings $\{S_i : i = 1, 2, \dots, N\}$ is semi-compact and $\Gamma \neq \emptyset$, then the sequences $\{x_n\}$ and $\{y_n\}$ both converge strongly to a split common fixed point $x^* \in \Gamma$.

Proof. Without loss of generality, we may assume that S_1 is semi-compact, it follows from (3.12) that

$$\lim_{n_i(1) \rightarrow +\infty} \|y_{n_i(1)} - S_j y_{n_i(1)}\| = 0, \tag{3.16}$$

therefore, there exists a subsequence $\{y_{n_i(1)}\}$ of $\{y_n\}$ converges strongly to a point $p \in H_1$ (some point in H_1). Since $y_{n_1} \rightharpoonup x^* \in \Gamma$. We know that $p = x^*$. This implies that $\{y_{n_1}\}$ converges strongly to $x^* \in \Gamma$. From Theorem 3.1, we know that $\lim_{n \rightarrow \infty} \|y_n - p\|$ exists for each $p \in \Gamma$. Therefore $\{y_n\}$ converges strongly to x^* .

From (3.15) that, $x_n = y_n - \gamma A^*(T_n - I)Ax_n$, by (3.8), we obtain that $\{x_{n_1}\}$ converges strongly to $x^* \in \Gamma$. On the other hand, since $\lim_{n \rightarrow \infty} \|x_n - q\|$ exists, we know that $\{x_n\}$ converges strongly to $x^* \in \Gamma$. The proof is completed. \square

The following corollary can be directly obtained from Theorem 3.2 since the type of demicontractive mappings contains the type of quasi-nonexpansive mappings.

COROLLARY 1. *Let H_1 and H_2 be two Hilbert spaces and A be a bounded linear operator from H_1 to H_2 , let $S_i : H_1 \rightarrow H_2$ and $T_i : H_2 \rightarrow H_2$ be quasi-nonexpansive mappings satisfying $\cap_{i=1}^N F(S_i) = C$ and $\cap_{i=1}^N F(T_i) = Q$, $i = 1, 2, \dots, N$. For any $x_0 \in H_1$, $\{x_n\}$ is defined by*

$$\begin{cases} y_n = x_n + \gamma A^*(T_n - I)Ax_n, \\ x_{n+1} = (1 - \alpha_n)y_n + \alpha_n S_n y_n, \quad n \in N, \end{cases} \tag{3.15}$$

where λ is the spectral radius of the operator A^*A , $T_n = T_{n(\text{mod } N)}$, $S_n = S_{n(\text{mod } N)}$, $\forall n \geq 1$, γ and $\{\alpha_n\}$ satisfy the following conditions:

- (1) $C := \bigcap_{i=1}^N F(S_i) \neq \emptyset$, $Q := \bigcap_{i=1}^N F(T_i) \neq \emptyset$;
- (2) $0 < \gamma\lambda < 1$, $\alpha_n \in (\delta, 1 - \delta)$ for some $\delta \in (0, 1)$.

If one of the mappings $\{S_i : i = 1, 2, \dots, N\}$ is semi-compact and $\Gamma \neq \emptyset$, then the sequences $\{x_n\}$ and $\{y_n\}$ both converge strongly to a split common fixed point $x^* \in \Gamma$.

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Li-Juan Qin
 Department of Mathematics, Kunming University
 Kunming, Yunnan 650214, P. R. China
 e-mail: annyqlj@163.com

Gang Wang
 College of Statistics and Mathematics
 Yunnan University of Finance and Economics
 Kunming, Yunnan 650221, P. R. China
 e-mail: wg631208@sina.com