

THE BIRKHOFF ORTHOGONALITY IN PRE-HILBERT C^* -MODULES

PAWEŁ WÓJCIK

(Communicated by R. Bhatia)

Abstract. In this work we characterize the Birkhoff orthogonality for elements and finite dimensional subspaces of a pre-Hilbert C^* -module in terms of a convex hull of continuous linear functionals. The aim of the paper is to present results concerning the B -orthogonality and its applications. We also present the results concerning smoothness. Moreover, we give a new proof of the Bhatia–Šemrl theorem.

1. Introduction

Let $(X, \|\cdot\|)$ be a normed space over $\mathbb{K} \in \{\mathbb{R}, \mathbb{C}\}$. If the norm comes from an inner product $\langle \cdot | \cdot \rangle$, there is one natural orthogonality relation: $x \perp y \Leftrightarrow \langle x | y \rangle = 0$. In general case, there are several notions of orthogonality and one of the most outstanding is the definition introduced by Birkhoff [4] (cf. also James [6]). For $x, y \in X$ we define:

$$x \perp_B y \Leftrightarrow \forall \lambda \in \mathbb{K} : \|x\| \leq \|x + \lambda y\|.$$

This relation is clearly homogeneous, but neither symmetric nor additive, unless the norm comes from an inner product. Of course, in an inner product space we have $\perp_B = \perp$.

An element x is B -orthogonal to a subspace $M \subset X$ (i.e., $x \perp_B M$) if and only if $x \perp_B m$ for all $m \in M$.

Let us recall some basic facts about C^* -algebras and Hilbert C^* -modules and introduce our notation. A C^* -algebra \mathcal{A} is a Banach $*$ -algebra with the norm satisfying the C^* -condition $\|a^*a\|_{\mathcal{A}} = \|a\|_{\mathcal{A}}^2$ for all $a \in \mathcal{A}$. Let V be a normed space over $\mathbb{K} \in \{\mathbb{R}, \mathbb{C}\}$. Let \mathcal{A} be a C^* -algebra over the same field. A *positive* element a of a C^* -algebra \mathcal{A} is a self-adjoint element such that $\sigma(a) \subset [0, 1]$. If $a \in \mathcal{A}$ is positive, we write $a \geq 0$.

A *right pre-Hilbert C^* -module X over a C^* -algebra \mathcal{A}* is a linear space which is a right \mathcal{A} -module equipped with an \mathcal{A} -valued inner-product $\langle \cdot | \cdot \rangle_V \times V \rightarrow \mathcal{A}$ that is sesquilinear, positive definite and respects the module action, i.e.,

- (C1) $\forall_{\alpha, \beta \in \mathbb{K}} \forall_{x, y, z \in V} \langle x | \alpha y + \beta z \rangle = \alpha \langle x | y \rangle + \beta \langle x | z \rangle$,
- (C2) $\forall_{x, y \in V} \forall_{a \in \mathcal{A}} \langle x | ya \rangle = \langle x | y \rangle a$,
- (C3) $\forall_{x, y \in V} \langle x | y \rangle = \langle y | x \rangle^*$,
- (C4) $\forall_{x \in V} \langle x | x \rangle \geq 0$; if $\langle x | x \rangle = 0$ then $x = 0$,

Mathematics subject classification (2010): 46B20, 46L08, 46L05.

Keywords and phrases: Pre-Hilbert C^* -module, continuous linear functional, smoothness.

For a pre-Hilbert C^* -module V the Cauchy–Schwarz inequality holds: $\|\langle x|y\rangle\|_{\mathcal{A}}^2 \leq \|\langle x|x\rangle\|_{\mathcal{A}} \cdot \|\langle y|y\rangle\|_{\mathcal{A}}$. In particular, $\|x\| := \sqrt{\|\langle x|x\rangle\|_{\mathcal{A}}}$ defines a norm on V . A pre-Hilbert \mathcal{A} -module which is complete with respect to this norm is called a *Hilbert C^* -module over \mathcal{A}* , or a *Hilbert A -module*.

Obviously, every Hilbert space is a Hilbert C^* -module. Also, every C^* -algebra \mathcal{A} can be regarded as a Hilbert C^* -module over itself with the inner product $\langle x|y\rangle := x^*y$, and the corresponding norm is just the norm on \mathcal{A} because of the C^* -condition.

2. Preliminaries

Let X be a normed space over \mathbb{R} or \mathbb{C} . We write B_X for the closed unit ball. Let S_X denote the unit sphere in X . The dual space is denoted by X^* . It is easy to see that for two elements x, y of a normed linear space X , it holds $x \perp_B y$ if and only if there is a norm one linear functional $f \in X^*$ such that $f(x) = \|x\|$ and $f(y) = 0$. If we have additional structures on a normed linear space X , then we get other characterizations of the Birkhoff orthogonality. One of the first results of this form is the result obtained by Bhatia and Šemrl [2] for the C^* -algebra $\mathcal{B}(\mathcal{H})$ of all bounded linear operators on a Hilbert space \mathcal{H} .

THEOREM 1. [2] *Let $A, B \in \mathcal{B}(\mathcal{H})$.*

(a) *If $\dim \mathcal{H} < \infty$, then $A \perp_B B$ if and only if there is a unit vector $x \in \mathcal{H}$ such that $\|Ax\| = \|A\|$ and $\langle Ax|Bx\rangle = 0$.*

(b) *If $\dim \mathcal{H} = \infty$, then $A \perp_B B$ if and only if there is a sequence of unit vectors $(x_n) \subset \mathcal{H}$ such that $\lim_{n \rightarrow \infty} \|Ax_n\| = \|A\|$ and $\lim_{n \rightarrow \infty} \langle Ax_n|Bx_n\rangle = 0$.*

The characterization of the Birkhoff orthogonality for elements of a Hilbert C^* -module by means of the states of the underlying C^* -algebra was obtained by Arambašić and Rajić [1]. Here, a *state* is a positive linear functional with norm 1.

THEOREM 2. [1] *Let V be a Hilbert \mathcal{A} -module, and $x, y \in V$. Then $x \perp_B y$ if and only if there is a positive linear functional $\varphi \in \mathcal{A}^*$ such that $\|\varphi\| = 1$ and $\varphi(\langle x|x\rangle) = \|x\|^2$ and $\varphi(\langle x|y\rangle) = 0$.*

In particular, Theorem 2 implies the following.

THEOREM 3. *Let V be a Hilbert \mathcal{A} -module, and $x \in V$. Assume that $Y \subset V$ is a finite dimensional linear subspace, and let $x \in V \setminus Y$. Then $x \perp_B Y$ if and only if for every $y \in Y$ there is a positive linear functional $\varphi \in \mathcal{A}^*$ such that $\|\varphi\| = 1$ and $\varphi(\langle x|x\rangle) = \|x\|^2$ and $y \in \ker \varphi(\langle x|\cdot\rangle)$.*

In the next section, we will show a result similar to Theorem 3.

Let $\text{Ext}K$ denote the set of all extremal points of a given set K . The dual space is denoted by X^* . The next result is known.

THEOREM 4. [7, p. 170] *Let X be a normed linear space, $Y = \text{span}\{x_1, \dots, x_n\}$ an n -dimensional subspace of X , $x \in X \subset Y$ and $y_o \in Y$. The following statements are equivalent:*

(a) $x \perp_B Y$;

(b) *There exist h extremal points f_1, \dots, f_h of S_{X^*} , where $1 \leq h \leq n + 1$ if the scalars are real and $1 \leq h \leq 2n + 1$ if the scalars are complex and h numbers $\lambda_1, \dots, \lambda_h > 0$ with $\sum_{j=1}^h \lambda_j = 1$, such that*

$$\sum_{j=1}^h \lambda_j f_j(y) = 0 \text{ for all } y \in Y, \quad \text{and} \quad \sum_{j=1}^h \lambda_j f_j(x) = \|x\|,$$

(c) *There exist h extremal points f_1, \dots, f_h of S_{X^*} , where $1 \leq h \leq n + 1$ if the scalars are real and $1 \leq h \leq 2n + 1$ if the scalars are complex and h numbers $\lambda_1, \dots, \lambda_h > 0$ with $\sum_{j=1}^h \lambda_j = 1$, such that*

$$\sum_{j=1}^h \lambda_j f_j(y) = 0 \text{ for all } y \in Y, \quad \text{and} \quad f_j(x) = \|x\| \text{ for } j = 1, \dots, h.$$

3. Main result

The four theorems above motivate the following section. Let X be a normed space over \mathbb{R} or \mathbb{C} . In this paper, the set $D \subset X$ is called *symmetric*, if

$$\text{for all } x \in A, \text{ and for all } \gamma \in \mathbb{K} \text{ with } |\gamma| = 1, \text{ we have } \gamma x \in A.$$

A set $\mathcal{N} \subset S_{X^*}$ is called a **-norming set in X* if

$$\|x\| = \sup\{|x^*(x)| : x^* \in \mathcal{N}\}$$

for all $x \in X$. Let V be a pre-Hilbert \mathcal{A} -module. A set $\mathcal{D} \subset S_V$ is called a *norming set in V* if

$$\|x\| = \sup\{\|\langle b|x \rangle\|_{\mathcal{A}} : b \in \mathcal{D}\}$$

for all $x \in V$. For example, S_{X^*} is a *-norming set in X . Similarly, $\text{Ext}S_{X^*}$ is also *-norming set in X . In general, *-norming set \mathcal{N} need not consist of extreme points and it is even possible to have $\mathcal{N} \cap \text{Ext}S_{X^*} = \emptyset$.

If K is dense in S_V , then K is a norming set in V . We say that $E \subset X^*$ is *total over X* , if for all $x \in X \setminus \{0\}$, there exists $\varphi \in E$ such that $\varphi(x) \neq 0$.

LEMMA 1. *Let X be a normed space. Suppose $M \subset X^*$. If M is a *-norming set in X , then M is total over X .*

Proof. Assume, contrary to our claim, that M is not total over X . Then, there exists $x_o \in X \setminus \{0\}$ such that $\varphi(x_o) = 0$ for all $\varphi \in M$. It follows that $0 < \|x_o\| = \sup\{\varphi(x_o) : \varphi \in M\} = \sup\{0 : \varphi \in M\} = 0$, which is a contradiction. \square

LEMMA 2. *Let U be a vector space. Let $M \subset U^*$ be a total set over U . Assume that $\dim U^* = p < \infty$. Then there are functionals x_1^*, \dots, x_p^* in M such that $K := \{x_1^*, \dots, x_p^*\}$ forms a Hamel basis of U^* .*

Proof. It is enough to show that $\dim(\text{span}M) = \dim U^*$. Assume, contrary to our claim, that $\dim(\text{span}M) < \dim U^*$. Then there are functionals y_1^*, \dots, y_k^* in M such that $\text{span}\{y_1^*, \dots, y_k^*\} = \text{span}M$ and $k < p$. It follows that $\bigcap_{j=1}^k \ker y_j^* \neq \{0\}$. Let us fix x_o in $\left(\bigcap_{j=1}^k \ker y_j^*\right) \setminus \{0\}$. Since $M \subset \text{span}\{y_1^*, \dots, y_k^*\}$, we have $z^*(x_o) = 0$ for all $z^* \in M$. Moreover, $x_o \neq 0$. It means that M is not total over U , and we have a contradiction. \square

The following considerations have been inspired by Theorems 1, 2 (in particular Theorem 3) and 4. We will prove a new type of characterization of B -orthogonality in pre-Hilbert C^* -modules. Namely, we will consider a condition $x \perp_B Y$ instead of $x \perp_{B,Y}$ and moreover we will apply the norming sets. Furthermore, we will consider the case over \mathbb{R} and the case over \mathbb{C} simultaneously. What is more, we will consider the Birkhoff orthogonality in pre-Hilbert C^* -modules instead of in Hilbert C^* -modules. We will obtain a characterization of the B -orthogonality in which only the norming sets are involved.

Let $\mathcal{N} \subset S_{\mathcal{A}^*}$ be a fixed $*$ -norming set (in \mathcal{A}) and let $\mathcal{D} \subset S_V$ be a fixed norming set (in V). We define the the following set:

$$\mathcal{F}_h := \left\{ \sum_{k=1}^h \lambda_k a_k^*(\langle u_k | \cdot \rangle) \in V^* : a_k^* \in \mathcal{N}, u_k \in \mathcal{D}, \lambda_k \geq 0, \sum_{k=1}^h \lambda_k = 1 \right\}. \tag{1}$$

It is obvious that

$$\mathcal{F}_h \subset \text{conv}\{a^*(\langle u | \cdot \rangle) \in V^* : a^* \in \mathcal{N}, u \in \mathcal{D}\} \subset B_{V^*}$$

The symbol B_{V^*} denotes the closed unit ball.

Suppose that Y is a n -dimensional subspace of X . We define a new constant:

$$\vartheta(x) := \inf \{ \|x\| - v^*(x) \mid v^* \in \mathcal{F}_{n+1}, Y \subset \ker v^* \}$$

in the real case. In a similar way we define

$$\vartheta(x) := \inf \{ \|x\| - v^*(x) \mid v^* \in \mathcal{F}_{2n+1}, Y \subset \ker v^* \}$$

in the complex case. Clearly $\vartheta(x) \geq 0$ for all $x \in V \setminus Y$. Now we prove the main result of this paper.

THEOREM 5. *Let V be a pre-Hilbert \mathcal{A} -module, where V, \mathcal{A} are over the same field $\mathbb{K} \in \{\mathbb{R}, \mathbb{C}\}$. Assume that $\mathcal{N} \subset S_{\mathcal{A}^*}$ is a $*$ -norming set (in \mathcal{A}). Suppose that $\mathcal{D} \subset S_V$ is a norming set (in V). Moreover, suppose that \mathcal{N} is symmetric. Let $Y \subset V$*

be an n -dimensional subspace. Assume $x \in V \setminus Y$. Then the following conditions are equivalent:

- (A) $x \perp_B Y$,
- (B) $\vartheta(x) = 0$.

Proof. We start with proving (B) \Rightarrow (A). Assume, contrary to our claim, that $x \not\perp_B Y$. Let $W := \text{span}(Y \cup \{x\})$. Since W is finite dimensional, there is $w \in W \setminus Y$ such that $w \perp_B Y$ (by Riesz's Lemma and the compactness of S_W). It follows that $w = \alpha x + y_1$ for some $\alpha \in \mathbb{K}$, $y_1 \in Y$. It is clear that $\frac{1}{\alpha} w \perp_B Y$. We show that $\|x\| > \|\frac{1}{\alpha} w\|$. If we had $\|x\| \leq \|\frac{1}{\alpha} w\|$, then we would obtain

$$\|x\| \leq \|\frac{1}{\alpha} w\| \leq \|\frac{1}{\alpha} w + y\| \text{ for all } y \in Y.$$

In particular, putting $-\frac{1}{\alpha} y_1 + y$ in place of y , we would obtain

$$\|x\| \leq \|\frac{1}{\alpha} w - \frac{1}{\alpha} y_1 + y\| = \|x + y\| \text{ for all } y \in Y.$$

But then $x \perp_B Y$ and we would obtain a contradiction.

Define now $\varepsilon := \frac{1}{2}\|x\| - \frac{1}{2}\|\frac{1}{\alpha} w\| > 0$. Directly from the definition of $\vartheta(x)$, we have

$$\|x\| \leq \varepsilon + \left| \sum_{k=1}^h \lambda_k a_k^* (\langle u_k | x \rangle) \right| \tag{2}$$

for some $\lambda_1, \dots, \lambda_h \geq 0$, $a_1^*, \dots, a_h^* \in \mathcal{N}$, $u_1, \dots, u_h \in \mathcal{D}$ (where $h = n + 1$ in real case or $h = 2n + 1$ in complex case), such that $\sum_{k=1}^h \lambda_k = 1$ and

$$\sum_{k=1}^h \lambda_k a_k^* (\langle u_k | y \rangle) = 0 \text{ for all } y \in Y. \tag{3}$$

Thus we have

$$\begin{aligned} \varepsilon + \left\| \frac{1}{\alpha} w \right\| &= \frac{1}{2} \|x\| - \frac{1}{2} \left\| \frac{1}{\alpha} w \right\| + \left\| \frac{1}{\alpha} w \right\| = \frac{1}{2} \|x\| + \frac{1}{2} \left\| \frac{1}{\alpha} w \right\| < \frac{1}{2} \|x\| + \frac{1}{2} \|x\| \\ &= \|x\| \stackrel{(2)}{\leq} \varepsilon + \left| \sum_{k=1}^h \lambda_k a_k^* (\langle u_k | x \rangle) \right| \stackrel{(x = \frac{1}{\alpha} w - \frac{1}{\alpha} y_1)}{=} \\ &= \varepsilon + \left| \sum_{k=1}^h \lambda_k a_k^* \left(\left\langle u_k \left| \frac{1}{\alpha} w - \frac{1}{\alpha} y_1 \right\rangle \right) \right| \stackrel{(3)}{=} \\ &= \varepsilon + \left| \sum_{k=1}^h \lambda_k a_k^* \left(\left\langle u_k \left| \frac{1}{\alpha} w \right\rangle \right) \right| \leq \varepsilon + \sum_{k=1}^h \lambda_k \left| a_k^* \left(\left\langle u_k \left| \frac{1}{\alpha} w \right\rangle \right) \right| \\ &\leq \varepsilon + \sum_{k=1}^h \lambda_k \|a_k^*\| \cdot \left\| \left\langle u_k \left| \frac{1}{\alpha} w \right\rangle \right\| \leq \varepsilon + \sum_{k=1}^h \lambda_k \|u_k\| \cdot \left\| \frac{1}{\alpha} w \right\| \\ &\leq \varepsilon + \sum_{k=1}^h \lambda_k \left\| \frac{1}{\alpha} w \right\| = \varepsilon + \left\| \frac{1}{\alpha} w \right\| \sum_{k=1}^h \lambda_k \leq \varepsilon + \left\| \frac{1}{\alpha} w \right\|. \end{aligned}$$

We get $\varepsilon + \|\frac{1}{\alpha}w\| < \varepsilon + \|\frac{1}{\alpha}w\|$, which is a contradiction.

Now we prove (A) \Rightarrow (B). Let us now define $U := \text{span}(Y \cup \{x\})$ and let us consider any $\varepsilon \in (0, 1)$. It is clear that $\dim U = n + 1 < \infty$. Then the compactness of S_U implies that there are $w_1, \dots, w_m \in S_U$ such that

$$S_U \subset \bigcup_{k=1}^m B\left(w_k; \frac{\varepsilon}{4}\right), \quad (4)$$

where $B(w_k; \frac{\varepsilon}{4}) = \{z \in U : \|z - w_k\| < \frac{\varepsilon}{4}\}$. It is easy to check that the set

$$M := \{a^*(\langle u|\cdot \rangle)|_U \in U^* : a^* \in \mathcal{N}, u \in \mathcal{D}\}.$$

is $*$ -norming in U . Indeed, for every $p \in U$, from the assumptions we have

$$\begin{aligned} \|p\| &= \sup \{\|\langle u|p \rangle\| : u \in \mathcal{D}\} \\ &= \sup \{\sup \{|a^*(\langle u|p \rangle)| : a^* \in \mathcal{N}\} : u \in \mathcal{D}\} \\ &= \sup \{|a^*(\langle u|p \rangle)| : a^* \in \mathcal{N}, u \in \mathcal{D}\} \\ &= \sup \{|v^*(p)| : v^* \in M\}, \end{aligned}$$

This means that the set $\{a^*(\langle u|\cdot \rangle)|_U \in U^* : a^* \in \mathcal{N}, u \in \mathcal{D}\}$ is $*$ -norming in U . Therefore there exist $a_1^*, \dots, a_m^* \in \mathcal{N}$, $u_1, \dots, u_m \in \mathcal{D}$ such that

$$|\|w_k\| - |a_k^*(\langle u_k|w_k \rangle)|| < \frac{\varepsilon}{4} \text{ for } k = 1, \dots, m.$$

The set \mathcal{N} is symmetric. Thus, without loss of generality, we may assume that

$$|\|w_k\| - a_k^*(\langle u_k|w_k \rangle)| < \frac{\varepsilon}{4} \text{ for } k = 1, \dots, m. \quad (5)$$

Then we define $L := \{a_1^*(\langle u_1|\cdot \rangle)|_U, \dots, a_m^*(\langle u_m|\cdot \rangle)|_U\}$. We have already defined the set

$$M = \{a^*(\langle u|\cdot \rangle)|_U \in U^* : a^* \in \mathcal{N}, u \in \mathcal{D}\}.$$

We have shown that M is $*$ -norming in U . By Lemma 1, M is total over U . It follows from Lemma 2 that there is $K \subset M$ such that K forms a Hamel basis of U^* .

Without loss of generality, we may assume that

$$K = \{b_1^*(\langle z_1|\cdot \rangle)|_U, \dots, b_n^*(\langle z_n|\cdot \rangle)|_U, b_{n+1}^*(\langle z_{n+1}|\cdot \rangle)|_U\},$$

for some $b_1^*(\langle z_1|\cdot \rangle)|_U, \dots, b_n^*(\langle z_n|\cdot \rangle)|_U, b_{n+1}^*(\langle z_{n+1}|\cdot \rangle)|_U \in M$.

Let us now define the sets

$$E := \{\gamma a_k^*(\langle u_k|\cdot \rangle)|_U \in U^* : k = 1, \dots, m, \gamma \in \mathbb{K} \text{ and } |\gamma| = 1\}$$

and

$$F := \{\gamma b_k^*(\langle z_k|\cdot \rangle)|_U \in U^* : k = 1, \dots, n, n+1, \gamma \in \mathbb{K} \text{ and } |\gamma| = 1\}$$

and let us introduce the set P defined by

$$P := \text{conv}(E \cup F). \tag{6}$$

The set P is convex, absorbing and balanced. Moreover, P is compact. Hence this set introduces a new norm $\|\cdot\|_P$ in U^* by the Minkowski functional.

Now we can define the function $\|\cdot\|_T : U \rightarrow \mathbb{R}$ by $\|x\|_T := \max\{|\varphi(x)| : \varphi \in E \cup F\}$. It is a norm. Indeed, it is easy to show that $\|p+r\|_T \leq \|p\|_T + \|r\|_T$ and $|\alpha| \cdot \|p\|_T = \|\alpha p\|_T$. We prove only an implication $\|p\|_T = 0 \Rightarrow p = 0$. If $p \in U$ and $\|p\|_T = 0$, then $\varphi(p) = 0$ for all $\varphi \in E \cup F$. Moreover $K \subset F$, whence $\varphi(p) = 0$ for all $\varphi \in K$. It is helpful to recall that K forms the Hamel basis in U^* . Therefore we obtain $p = 0$.

It is easy to see that $\|\psi\|_P = \sup\{|\psi(x)| : \|x\|_T \leq 1\}$. Thus we may say that $\|\cdot\|_P$ is the dual norm for $\|\cdot\|_T$, i.e., $(U, \|\cdot\|_T)^* = (U^*, \|\cdot\|_P)$. Directly from the definition of $\|\cdot\|_T$, we have the following inequality

$$\|v\|_T \leq \|v\| \text{ for all } v \in U \setminus \{0\}. \tag{7}$$

Next we will prove that

$$(1 - \varepsilon)\|v\| \leq \|v\|_T \leq (1 + \varepsilon)\|v\| \text{ for all } v \in U \setminus \{0\}. \tag{8}$$

It follows from (6) and $a_k^*(\langle u_k | \cdot \rangle)|_U \in E \subset E \cup F$ that

$$|a_k^*(\langle u_k | v \rangle)| \leq \max\{|\varphi(v)| : \varphi \in E \cup F\} = \|v\|_T \text{ for all } v \in U. \tag{9}$$

It follows that

$$\|w_k\| \stackrel{(5)}{<} \frac{\varepsilon}{4} + |a_k^*(\langle u_k | w_k \rangle)| \stackrel{(9)}{\leq} \frac{\varepsilon}{4} + \|w_k\|_T \tag{10}$$

and by (7) we get $0 \leq \|w_k\| - \|w_k\|_T$. Then, by (10) we have

$$\| \|w_k\| - \|w_k\|_T \| \leq \frac{\varepsilon}{4} \text{ for all } k = 1, \dots, m. \tag{11}$$

Fix $v \in U$ such that $v \neq 0$. It is clear that $\frac{v}{\|v\|} \in S_U$. Applying (4) we have

$$\left\| w_{k_0} - \frac{v}{\|v\|} \right\| < \frac{\varepsilon}{4} \tag{12}$$

for some $w_{k_0} \in \{w_1, \dots, w_m\}$.

Then, we have

$$\begin{aligned} \left| \left\| \frac{v}{\|v\|} \right\| - \left\| \frac{v}{\|v\|} \right\|_T \right| &= \left| 1 - \left\| \frac{v}{\|v\|} \right\|_T \right| = \left| \|w_{k_0}\| - \left\| \frac{v}{\|v\|} \right\|_T \right| \\ &\leq | \|w_{k_0}\| - \|w_{k_0}\|_T | + \left| \|w_{k_0}\|_T - \left\| \frac{v}{\|v\|} \right\|_T \right| \\ &\leq | \|w_{k_0}\| - \|w_{k_0}\|_T | + \left\| w_{k_0} - \frac{v}{\|v\|} \right\|_T \stackrel{(11),(7)}{\leq} \\ &\leq \frac{\varepsilon}{4} + \left\| w_{k_0} - \frac{v}{\|v\|} \right\| \stackrel{(12)}{\leq} \frac{\varepsilon}{4} + \frac{\varepsilon}{4} = \frac{\varepsilon}{2} \leq \varepsilon. \end{aligned}$$

Thus we get $\left| \left\| \frac{v}{\|v\|} \right\| - \left\| \frac{v}{\|v\|} \right\|_T \right| \leq \varepsilon$ for all $v \in U \setminus \{0\}$. From this it is very easy to prove that

$$(1 - \varepsilon)\|v\| \leq \|v\|_T \leq (1 + \varepsilon)\|v\| \text{ for all } v \in U \setminus \{0\}. \tag{13}$$

Let \perp_B^T denote the Birkhoff orthogonality with respect to the norm $\|\cdot\|_T$. The space $(U, \|\cdot\|_T)$ is finite dimensional, whence (applying again Riesz’s Lemma and the compactness of the unit sphere $S_{(U, \|\cdot\|_T)}$) there is $\hat{x} \in U \setminus Y$ such that $\hat{x} \perp_B^T Y$. It follows that $\hat{x} = \beta x + y_1$ for some $\beta \in \mathbb{K}$, $y_1 \in Y$.

Since $\hat{x} \perp_B^T Y$, it follows that $\frac{1}{\beta} \hat{x} \perp_B^T Y$. Now we can apply Theorem 4. There exist h extremal points f_1, \dots, f_h of $S_{(U, \|\cdot\|_T)^*}$, where $1 \leq h \leq n + 1$ if the scalars are real and $1 \leq h \leq 2n + 1$ if the scalars are complex and h numbers $\lambda_1, \dots, \lambda_h > 0$ with $\sum_{j=1}^h \lambda_j = 1$, such that

$$\sum_{j=1}^h \lambda_j f_j(y) = 0 \text{ for all } y \in Y, \text{ and } f_j\left(\frac{1}{\beta} \hat{x}\right) = \left\| \frac{1}{\beta} \hat{x} \right\|_T \text{ for } j = 1, \dots, h. \tag{14}$$

It follows directly from the definition of $\|\cdot\|_T$ that $\text{Ext}S_{(U, \|\cdot\|_T)^*} \subset E \cup F$. In fact, this means that

$$f_1, \dots, f_h \in \bigcup_{|\gamma|=1} \gamma \cdot \{a_t^*(\langle u_t | \cdot \rangle)|_U, b_j^*(\langle z_j | \cdot \rangle)|_U : t = 1, \dots, m, j = 1, \dots, n, n+1\},$$

and hence

$$f_1 = \gamma_1 c_1^*(\langle s_1 | \cdot \rangle)|_U, \dots, f_h = \gamma_h c_h^*(\langle s_h | \cdot \rangle)|_U \tag{15}$$

for some $|\gamma_j| = 1$, and $c_j^* \in \{a_j^*, b_j^*\}$, and $s_j \in \{u_j, z_j\}$. It follows from (14), (15) that

$$0 = \sum_{j=1}^h \lambda_j c_j^*(\langle s_j | y \rangle) \text{ for } y \in Y \text{ and } \gamma_j c_j^*\left(\left\langle s_j \left| \frac{1}{\beta} \hat{x} \right. \right\rangle\right)\Big|_U = \left\| \frac{1}{\beta} \hat{x} \right\|_T \text{ for all } j. \tag{16}$$

It follows from $x \perp_B Y$ that

$$\|x\| \leq \left\| x + \frac{1}{\beta} y \right\| \text{ for all } y \in Y. \tag{17}$$

Since $\hat{x} \perp_B^T Y$, we deduce that $\frac{1}{\beta} \hat{x} \perp_B^T Y$ and

$$\left\| \frac{1}{\beta} \hat{x} \right\|_T \leq \left\| \frac{1}{\beta} \hat{x} - \frac{1}{\beta} y \right\|_T \text{ for all } y \in Y. \tag{18}$$

Thus we have

$$\left\| \frac{1}{\beta} \hat{x} \right\|_T \stackrel{(18)}{\leq} \left\| \frac{1}{\beta} \hat{x} - \frac{1}{\beta} y_1 \right\|_T \stackrel{(\hat{x} = \beta x + y_1)}{=} \|x\|_T \stackrel{(13)}{\leq} (1 + \varepsilon)\|x\| = \|x\| + \varepsilon\|x\| \tag{19}$$

and

$$\|x\| - \varepsilon \|x\| = (1 - \varepsilon) \|x\| \stackrel{(17)}{\leq} (1 - \varepsilon) \left\| x + \frac{1}{\beta} y_1 \right\| = (1 - \varepsilon) \left\| \frac{1}{\beta} \widehat{x} \right\| \stackrel{(13)}{\leq} \left\| \frac{1}{\beta} \widehat{x} \right\|_T. \quad (20)$$

It follows from (19), (20) that

$$\left| \|x\| - \left\| \frac{1}{\beta} \widehat{x} \right\|_T \right| \leq \varepsilon \|x\|. \quad (21)$$

Finally, we will show $\vartheta(x) = 0$. Summarizing, we have $\lambda_j \geq 0$, $\sum_{j=1}^h \lambda_j = 1$.

Moreover $\gamma_j c_j^* \in \mathcal{N}$ and $s_j \in \mathcal{D}$, which yields $\sum_{j=1}^h \lambda_j \gamma_j c_j^* (\langle s_j | \cdot \rangle) \in \mathcal{F}_h$. By (16),

we can conclude that $Y \subset \ker \left(\sum_{j=1}^h \lambda_j \gamma_j c_j^* (\langle s_j | \cdot \rangle) \right)$. Finally, we deduce

$$\begin{aligned} \left| \|x\| - \sum_{j=1}^h \lambda_j \gamma_j c_j^* (\langle s_j | x \rangle) \right| &\stackrel{(\widehat{x} = \beta x + y_1)}{=} \left| \|x\| - \sum_{j=1}^h \lambda_j \gamma_j c_j^* \left(\left\langle s_j \left| \frac{1}{\beta} \widehat{x} - \frac{1}{\beta} y_1 \right\rangle \right) \right| \\ &\stackrel{(16)}{=} \left| \|x\| - \sum_{j=1}^h \lambda_j \gamma_j c_j^* \left(\left\langle s_j \left| \frac{1}{\beta} \widehat{x} \right\rangle \right) \right| \\ &\stackrel{(16)}{=} \left| \|x\| - \sum_{j=1}^h \lambda_j \left\| \frac{1}{\beta} \widehat{x} \right\|_T \right| \\ &= \left| \|x\| - \left\| \frac{1}{\beta} \widehat{x} \right\|_T \right| \stackrel{(21)}{\leq} \varepsilon \|x\|. \end{aligned}$$

Thus we get $\left| \|x\| - \sum_{j=1}^h \lambda_j \gamma_j c_j^* (\langle s_j | x \rangle) \right| \leq \varepsilon \|x\|$. Since ε was arbitrary, this implies that $0 = \inf \{ \|x\| - v^*(x) \mid v^* \in \mathcal{F}_h, Y \subset \ker v^* \} = \vartheta(x)$. \square

4. Approximation

We are interested in the applications of Theorem 5. In approximation theory the condition that x is Birkhoff orthogonal to Y can be interpreted as follows. Suppose $x \in X \setminus Y$. Then the zero vector is the best approximation to x among all vectors in Y .

LEMMA 3. *Let V be a pre-Hilbert \mathcal{A} -module, where V, \mathcal{A} are over the field \mathbb{R} (or \mathbb{C}). Assume that $\mathcal{N} \subset S_{\mathcal{A}^*}$ is a $*$ -norming set (in \mathcal{A}). Suppose that $\mathcal{D} \subset S_V$ is a norming set (in V). Moreover, suppose that \mathcal{N} is symmetric. Let $Y \subset V$ be an n -dimensional subspace. Assume $x \in V \setminus Y$. Then the following condition holds:*

(i) *if $x \perp_B Y$, then $\|x\| = \sup \{ |v^*(x)| : Y \subset \ker v^*, v^* \in \mathcal{F}_{n+1} \}$ (or \mathcal{F}_{2n+1}).*

If V, \mathcal{A} are over the field \mathbb{R} , then the following condition also holds:

(ii) *if $x \perp_B Y$, then $\|x\| = \sup \{ v^*(x) : Y \subset \ker v^*, v^* \in \mathcal{F}_{n+1} \}$.*

Proof. It is obvious that $\|x\| \geq \sup\{|v^*(x)| : v^* \in \mathcal{F}_{n+1}, Y \subset \ker v^*\}$. By Theorem 5 let us choose a sequence $(v_n^*)_{n=1,2,\dots} \subset \mathcal{F}_{n+1}$ (or \mathcal{F}_{2n+1}) such that $Y \subset \ker v_n^*$ and

$$|\|x_n\| - v_n^*(x)| < \frac{1}{n}.$$

It follows from this inequality that

$$\|x\| - |v_n^*(x)| \leq |\|x\| - |v_n^*(x)|| \leq |\|x\| - v_n^*(x)| < \frac{1}{n}.$$

Now, suppose that V, \mathcal{A} are over the field \mathbb{R} . Since \mathcal{N} is symmetric, we may assume that $v_n^*(x) \in [0, +\infty)$. Thus $\|x\| < \frac{1}{n} + v_n^*(x)$, which means that

$$\|x\| = \sup\{v^*(x) : v^* \in \mathcal{F}_{n+1}, Y \subset \ker v^*\}. \quad \square$$

Now we present a different expression for the formula for distance from a given $x \in V$ to a finite dimensional subspace $Y \subset V$.

For $x \in V \setminus Y$ put

$$P_Y(x) := \{y \in Y : \|x - y\| = \text{dist}(x, Y)\}.$$

THEOREM 6. *Let V, \mathcal{N}, D, x, Y be such as in Lemma 3. Then*

$$\text{dist}(x, Y) = \sup\{|v^*(x)| : v^* \in \mathcal{F}_{n+1}, Y \subset \ker v^*\}.$$

In the complex case, we have $\text{dist}(x, Y) = \sup\{|v^(x)| : v^* \in \mathcal{F}_{2n+1}, Y \subset \ker v^*\}$.*

Proof. Since the proofs are similar we present only the real case. Since Y is a finite-dimensional subspace, there exists $y_o \in P_Y(x)$. It is easy to check that

$$y_o \in P_Y(x) \Leftrightarrow (x - y_o) \perp_B Y \tag{22}$$

Now by applying (22) and Lemma 3 we arrive at the desired assertion. Indeed, we obtain

$$\begin{aligned} \text{dist}(x, Y) &= \|x - y_o\| = \sup\{|v^*(x - y_o)| : v^* \in \mathcal{F}_{n+1}, Y \subset \ker v^*\} \\ &= \sup\{|v^*(x)| : v^* \in \mathcal{F}_{n+1}, Y \subset \ker v^*\}. \end{aligned}$$

In the complex case we obtain $\text{dist}(x, Y) = \sup\{|v^*(x)| : v^* \in \mathcal{F}_{2n+1}, Y \subset \ker v^*\}$. \square

5. Smoothness in spaces $\mathcal{C}(\Omega; \mathcal{A})$

Our aim in this section is to consider smoothness and B -orthogonal relation in situations where we use function spaces. Let \mathcal{A} be a real (or complex) C^* -algebra with identity $\mathbf{1}$. For a compact topological space Ω we denote by $\mathcal{C}(\Omega; \mathcal{A})$ the normed space of all \mathcal{A} -valued continuous functions with the usual sup-norm $\|f\|_\infty := \sup\{\|f(t)\|_{\mathcal{A}} : t \in \Omega\}$. It is obvious that $\mathcal{C}(\Omega; \mathcal{A})$ is also a real (or complex) C^* -algebra. In particular, $\mathcal{C}(\Omega; \mathcal{A})$ is also a Hilbert C^* -module over itself with the inner product $\langle f|g \rangle := f^*g$, where $f^*(t) := f(t)^*$, $t \in \Omega$. Now, we obtain another characterization of B -orthogonality. For $f \in \mathcal{C}(\Omega; \mathcal{A})$ put $M(f) := \{t \in \Omega : \|f(t)\|_{\mathcal{A}} = \|f\|_\infty\}$. We consider only the case when $M(f) \neq \emptyset$.

PROPOSITION 1. *Let \mathcal{A} be a real (or complex) C^* -algebra. Let $f, g \in \mathcal{C}(\Omega; \mathcal{A})$. Assume that $M(f) = \{t_o\}$. Then*

$$f \perp_B g \iff f(t_o) \perp_B g(t_o).$$

Proof. We start with proving " \Leftarrow ". Suppose that $f(t_o) \perp_B g(t_o)$. Directly from the definition of \perp_B , we have $\|f(t_o)\|_{\mathcal{A}} \leq \|f(t_o) + \lambda g(t_o)\|_{\mathcal{A}}$ for $\lambda \in \mathbb{K}$. Thus we have

$$\|f\|_{\infty} = \|f(t_o)\|_{\mathcal{A}} \leq \|f(t_o) + \lambda g(t_o)\|_{\mathcal{A}} \leq \|f + \lambda g\|_{\infty}$$

Therefore $\|f\|_{\infty} \leq \|f + \lambda g\|_{\infty}$ for $\lambda \in \mathbb{K}$.

Now we prove the converse. Let us consider $V := \mathcal{C}(\Omega; \mathcal{A})$ and $\widehat{\mathcal{A}} := \mathcal{C}(\Omega; \mathcal{A})$. We define an inner product

$$\langle \cdot | \cdot \rangle : \mathcal{C}(\Omega; \mathcal{A}) \times \mathcal{C}(\Omega; \mathcal{A}) \rightarrow \mathcal{C}(\Omega; \mathcal{A}), \quad \langle h | p \rangle := h^* p.$$

Then, the space $V = \mathcal{C}(\Omega; \mathcal{A})$ can be regarded as a Hilbert C^* -module over itself with $\widehat{\mathcal{A}} = \mathcal{C}(\Omega; \mathcal{A})$. Fix an arbitrary element $t \in \Omega$. Fix an arbitrary functional $x^* \in S_{\mathcal{A}^*}$. Define a linear and continuous functional

$$a_{t,x^*}^* \in \mathcal{C}(\Omega; \mathcal{A}) \rightarrow \mathbb{K} \quad \text{by} \quad a_{t,x^*}^* := x^*(f(t)), \quad f \in \mathcal{C}(\Omega; \mathcal{A}).$$

Now we define a set $\mathcal{N} := S_{\mathcal{A}^*}$. It is easy to check that the set \mathcal{N} is $*$ -norming and symmetric. Let us consider a set $\mathcal{D} := \{e\}$, where $e \in \mathcal{C}(\Omega; \mathcal{A})$, $e(t) = \mathbf{1}$ for $t \in \Omega$. The set D is norming. Next, we define the the following set:

$$\mathcal{F}_2 := \left\{ \lambda a_{t,x^*}^* (\langle e | \cdot \rangle) + (1-\lambda) a_{u,y^*}^* (\langle e | \cdot \rangle) \in \mathcal{C}(\Omega; \mathcal{A})^* : t, u \in \Omega, x^*, y^* \in \mathcal{N}, \lambda \in [0, 1] \right\}$$

Note that $f \perp_B g$ yields $\alpha f \perp_B \beta g$ for all $\alpha, \beta \in \mathbb{K}$ (i.e., \perp_B is full homogeneous). Without loss of generality, we may assume that $\|f\| = 1$.

Now, suppose that $f \perp_B g$. Applying Lemma 3 we obtain

$$\|f\| = \sup \{ |v^*(f)| : g \in \ker v^*, v^* \in \mathcal{F}_2 \}.$$

There are $v_n^* \in \mathcal{F}_2$ such that $|v_n^*(f)| \rightarrow \|f\|_{\infty}$ and $g \in \ker v_n^*$. By symmetry of \mathcal{N} , we may assume that $v_n^*(f) \in [0, +\infty)$, and then $v_n^*(f) \rightarrow \|f\|_{\infty}$. This means that

$$\begin{aligned} v_n^*(f) &= \lambda_n a_{t_n, x_n^*}^* (\langle e | f \rangle) + (1-\lambda_n) a_{u_n, y_n^*}^* (\langle e | f \rangle) \\ &= \lambda_n a_{t_n, x_n^*}^* (e^* f) + (1-\lambda_n) a_{u_n, y_n^*}^* (e^* f) \\ &= \lambda_n a_{t_n, x_n^*}^* (f) + (1-\lambda_n) a_{u_n, y_n^*}^* (f) \\ &= \lambda_n x_n^*(f(t_n)) + (1-\lambda_n) y_n^*(f(u_n)) \end{aligned}$$

for some $x_1^*, x_2^*, x_3^* \dots \in \mathcal{N}$, $t_1, t_2, t_3, \dots \in \Omega$. Therefore, we obtain

$$\lambda_n x_n^*(f(t_n)) + (1-\lambda_n) y_n^*(f(u_n)) \rightarrow \|f\|_{\infty}. \tag{23}$$

Moreover, $v_n^*(g) = 0$. In a similar way one can prove

$$\lambda_n x_n^*(g(t_n)) + (1-\lambda_n) y_n^*(g(u_n)) = 0. \tag{24}$$

The sets $[0, 1]$ (or $\mathbb{T} := \{z \in \mathbb{C} : |z| \leq 1\}$) and Ω are compact. The closed unit ball $\overline{B}_{\mathcal{A}^*}$ is weak*-compact. Therefore, without loss of generality, we may assume that there are elements t, u in Ω , functionals $x^*, y^* \in \overline{B}_{\mathcal{A}^*}$, a number $\lambda \in [0, 1]$ (or $\lambda \in \mathbb{T}$) and subsequences $\{t_{n_k}\}, \{u_{n_k}\}, \{x_{n_k}^*\}, \{y_{n_k}^*\}, \{\lambda_{n_k}\}$ such that $t_{n_k} \rightarrow t, u_{n_k} \rightarrow u, x_{n_k}^* \xrightarrow{w^*} x^*, y_{n_k}^* \xrightarrow{w^*} y^*, \lambda_{n_k} \rightarrow \lambda$. Clearly $f(t_{n_k}) \rightarrow f(t)$. Now the condition (23) becomes

$$\lambda x^*(f(t)) + (1 - \lambda)y^*(f(u)) = \|f\|_\infty. \tag{25}$$

It is clear that $g(t_{n_k}) \rightarrow g(t)$. We get from (24)

$$\lambda x^*(g(t)) + (1 - \lambda)y^*(g(u)) = 0. \tag{26}$$

We will show that $x^*(f(t)) = 1 = y^*(f(u))$. Now, we obtain the equality

$$1 = \|f\|_\infty \stackrel{(25)}{=} \lambda x^*(f(t)) + (1 - \lambda)y^*(f(u))$$

and $x^*(f(t)), y^*(f(u)) \in [-1, 1]$ (or $x^*(f(t)), y^*(f(u)) \in \mathbb{T}$). It is easy to check that $1 \in \text{Ext}[-1, 1]$ (or in complex case $1 \in \text{Ext}\mathbb{T}$). It yields $x^*(f(t)) = 1$ and $y^*(f(u)) = 1$, whence $\|x^*\| = \|f(t)\| = 1$ and $\|y^*\| = \|f(u)\| = 1$.

Bearing in mind that $M(f) = \{t_o\}$, we have $t_o = t = u$, so $x^*(f(t_o)) = 1$ and $y^*(f(t_o)) = 1$. We can rewrite (25) and (26) in the form

$$\lambda x^*(f(t_o)) + (1 - \lambda)y^*(f(t_o)) = \|f\|_\infty \quad \text{and} \quad \lambda x^*(g(t_o)) + (1 - \lambda)y^*(g(t_o)) = 0. \tag{27}$$

Let us define $w^* := \lambda x^* + (1 - \lambda)y^*$. It follows from (27) that

$$w^*(f(t_o)) = \|f\|_\infty \quad \text{and} \quad \|w^*\| = 1 \quad \text{and} \quad w^*(g(t_o)) = 0. \tag{28}$$

Then for $\lambda \in \mathbb{K}$ we have

$$\begin{aligned} \|f(t_o)\|_{\mathcal{A}} &= \|f\|_\infty \stackrel{(28)}{=} w^*(f(t_o)) = |w^*(f(t_o)) + 0| \\ &\stackrel{(28)}{=} |w^*(f(t_o)) + \lambda w^*(g(t_o))| = |w^*(f(t_o) + \lambda g(t_o))| \\ &\stackrel{(28)}{\leq} \|f(t_o) + \lambda g(t_o)\|_{\mathcal{A}}, \end{aligned}$$

thus finally we get $f(t_o) \perp_{\mathbb{B}} g(t_o)$. \square

A normed space $(X, \|\cdot\|)$ is said to be *smooth at the point* $x_o \in X \setminus \{0\}$, if there is a unique $x^* \in X^*$ such that $x^*(x_o) = \|x_o\|$ and $\|x^*\| = 1$. Now, we consider a set $D_{sm}(X) := \{x \in X : X \text{ is smooth at } x\}$. It is well known that the set $D_{sm}(\mathcal{C}(\Omega))$ is dense in $\mathcal{C}(\Omega)$. Moreover, if X is a separable real Banach space, then $D_{sm}(X)$ is dense. Now we will give a characterization of smoothness at a point in terms of the Birkhoff orthogonality (see [5]).

THEOREM 7. [5] *Let X be a normed space let $x_o \in X \setminus \{0\}$. Then the following statements are equivalent:*

- (i) X is smooth at x_0 , i.e., $x_0 \in D_{sm}(X)$;
- (ii) the Birkhoff orthogonality is x_0 -additive at right, i.e., for every $y, z \in X$ with $x_0 \perp_B y$ $x_0 \perp_B z$, we have also $x_0 \perp_B y + z$.

The next result may be also known, but for the convenience of the readers we present it here.

THEOREM 8. *If $f \in \mathcal{C}(\Omega)$, then $f \in D_{sm}(\mathcal{C}(\Omega))$ if and only if there is a unique $t_1 \in \Omega$ such that $\|f(t_1)\| = \|f\|_\infty$.*

There is a natural question. What happens in a general C^* -algebra $\mathcal{C}(\Omega; \mathcal{A})$ where $\mathcal{A} \neq \mathbb{R}$? Namely, we want to explore the set $D_{sm}(\mathcal{C}(\Omega; \mathcal{A}))$ instead of $D_{sm}(\mathcal{C}(\Omega))$. For $f \in \mathcal{C}(\Omega; \mathcal{A})$ put $M(f) := \{t \in \Omega : \|f(t)\|_{\mathcal{A}} = \|f\|_\infty\}$.

A semi-ideal of $\mathcal{C}(\Omega; \mathcal{A})$ is a linear subspace \mathcal{X} of $\mathcal{C}(\Omega; \mathcal{A})$ such that $\varphi \cdot h \in \mathcal{X}$ whenever $\varphi \in \mathcal{C}(\Omega; \mathbb{R})$, $h \in \mathcal{X}$.

PROPOSITION 2. *Let $\mathcal{X} \subset \mathcal{C}(\Omega; \mathcal{A})$ be a semi-ideal (not necessarily closed). If $f \in \mathcal{X}$, $f \neq 0$ and $\overline{M(f)} > 1$, then $f \notin D_{sm}(\mathcal{X})$.*

Proof. Fix arbitrarily $t_1, t_2 \in M(f)$ such that $t_1 \neq t_2$. By Urysohn’s Lemma there is a continuous function $\rho : \Omega \rightarrow [0, 1]$ such that $\rho(t_1) = 0$ and $\rho(t_2) = 1$. It is obvious that $\rho \cdot f, (1 - \rho) \cdot f \in \mathcal{C}(\Omega; \mathcal{A})$. Then for $\lambda \in \mathbb{K}$ we have

$$\begin{aligned} \|f\|_\infty &= \|f(t_1)\|_{\mathcal{A}} = \|f(t_1) + \lambda \rho(t_1) \cdot f(t_1)\|_{\mathcal{A}} \leq \|f + \lambda \rho \cdot f\|_\infty, \\ \|f\|_\infty &= \|f(t_2)\|_{\mathcal{A}} = \|f(t_2) + \lambda(1 - \rho(t_2)) \cdot f(t_2)\|_{\mathcal{A}} \leq \|f + \lambda(1 - \rho) \cdot f\|_\infty, \end{aligned}$$

which means that $f \perp_B \rho \cdot f$ and $f \perp_B (1 - \rho) \cdot f$. Since \mathcal{X} is a semi-ideal,

$$\rho f, (1 - \rho)f \in \mathcal{X}.$$

On the other hand it is easy to verify that f is not B -orthogonal to f . Thus, f is not B -orthogonal to $\rho \cdot f + (1 - \rho) \cdot f$, and Theorem 7 yields $f \notin D_{sm}(\mathcal{X})$. \square

COROLLARY 1. *If $f \in \mathcal{C}(\Omega; \mathcal{A})$ and $\overline{M(f)} > 1$, then $f \notin D_{sm}(\mathcal{C}(\Omega; \mathcal{A}))$.*

So, the case of $\overline{M(f)} > 1$ is clear. Now we will investigate the case where $\overline{M(f)} = 1$. Fix $t_0 \in \Omega$. We say that subspace $U \subset \mathcal{C}(\Omega; \mathcal{A})$ is t_0 -surjective, if for all $a \in \mathcal{A}$, there exists $g \in U$ such that

$$g(t_0) = a, \quad \text{or, equivalently,} \quad \mathcal{A} = \bigcup_{g \in U} \{g(t_0)\}.$$

It is clear that $\mathcal{C}(\Omega; \mathcal{A})$ is t_0 -surjective. On the other hand, t_0 -surjective subspace may be small.

EXAMPLE 1. Let us consider $\mathcal{C}([0, 1]; \mathbb{R}^2)$ (with some normed space \mathbb{R}^2). Fix $t_0 \in (0, 1]$. We define $f, g \in \mathcal{C}([0, 1]; \mathbb{R}^2)$ by $f(t) := (t, 0)$, $g(t) := (0, t)$. It is easy to check that the space $U := \text{span}\{f, g\}$ is t_0 -surjective and $\dim U = 2 < \dim \mathcal{C}([0, 1]; \mathbb{R}^2)$.

The next result establishes the connection between $D_{sm}(\mathcal{C}(\Omega; \mathcal{A}))$ and $D_{sm}(\mathcal{A})$ and $D_{sm}(U)$.

THEOREM 9. *Let \mathcal{A} be a real (or complex) C^* -algebra. Suppose that Ω is a compact topological space. Assume that $f \in \mathcal{C}(\Omega; \mathcal{A})$ and $M(f) = \{t_1\}$. The following conditions are equivalent:*

- (a) $f \in D_{sm}(\mathcal{C}(\Omega; \mathcal{A}))$;
- (b) $f(t_1) \in D_{sm}(\mathcal{A})$;
- (c) there is a t_1 -surjective subspace $U \subset \mathcal{C}(\Omega; \mathcal{A})$ such that $f \in D_{sm}(U)$.

Proof. We start with proving (b) \Rightarrow (a). Fix arbitrarily $g, h \in \mathcal{C}(\Omega; \mathcal{A})$ such that $f \perp_B g$ and $f \perp_B h$. By Proposition 1 we have $f(t_1) \perp_B g(t_1)$ and $f(t_1) \perp_B h(t_1)$. It follows from (b) and Theorem 7 that $f(t_1) \perp_B g(t_1) + h(t_1)$. Using again Proposition 1 we get $f \perp_B g + h$ and Theorem 7 yields $f \in D_{sm}(\mathcal{C}(\Omega; \mathcal{A}))$.

The implications (a) \Rightarrow (c) is obvious. Finally, we prove (c) \Rightarrow (b). Fix arbitrarily $x, y \in \mathcal{A}$ such that $f(t_1) \perp_B x$ and $f(t_1) \perp_B y$. Since U is t_1 -surjective, there are $g, h \in U$ such that $g(t_1) = x$, $h(t_1) = y$. It follows from (c) and Theorem 7 that $f \perp_B g + h$. Using again Proposition 1 we get $f(t_1) \perp_B g(t_1) + h(t_1)$, which means $f(t_1) \perp_B x + y$. Theorem 7 yields $f(t_1) \in D_{sm}(\mathcal{A})$. \square

6. Bhatia–Šemrl theorem

Now, we will show a new proof of the Bhatia–Šemrl theorem using Lemma 3. We will use again the new method to obtain the following characterization of B -orthogonality.

THEOREM 10. [2] *Let \mathcal{H} be a real Hilbert space. Suppose that $\dim \mathcal{H} < \infty$. Let $A, B \in \mathcal{B}(\mathcal{H})$. Then*

$$A \perp_B B \quad \Leftrightarrow \quad \exists_{x \in \mathcal{S}_{\mathcal{H}}} \|Ax\| = \|A\|, Ax \perp_B Bx.$$

We are now ready to prove a real version of the Bhatia–Šemrl theorem using these concepts. Our approach will revolve around Lemma 3 (in particular (ii)).

Proof. We start with proving " \Leftarrow ". Suppose that there is a vector x such that $\|Ax\| = \|A\|$, $Ax \perp_B Bx$. Thus we have $\langle Ax|Bx \rangle = 0$ hence

$$\begin{aligned} \|A\|^2 &= \|Ax\|^2 = \langle Ax|Ax \rangle = \langle Ax|Ax \rangle + 0 \\ &= \langle Ax|Ax \rangle + \lambda \langle Ax|Bx \rangle = \langle Ax|Ax + \lambda Bx \rangle \\ &\leq \|Ax\| \cdot \|Ax + \lambda Bx\| \leq \|A\| \cdot \|A + \lambda B\|. \end{aligned}$$

Therefore $\|A\| \leq \|A + \lambda B\|$ for $\lambda \in \mathbb{R}$.

Now we prove the converse. Let us consider $V := \mathcal{B}(\mathcal{H})$ and $\mathcal{A} := \mathcal{B}(\mathcal{H})$. We define an inner product

$$\langle \cdot | \cdot \rangle_{\mathcal{B}(\mathcal{H})} : \mathcal{B}(\mathcal{H}) \times \mathcal{B}(\mathcal{H}) \rightarrow \mathcal{B}(\mathcal{H}), \quad \langle M|N \rangle_{\mathcal{B}(\mathcal{H})} := M^*N.$$

Then, the space $V = \mathcal{B}(\mathcal{H})$ can be regarded as a Hilbert C^* -module over itself with $\mathcal{A} = \mathcal{B}(\mathcal{H})$. Fix arbitrarily two vectors $x, y \in \mathcal{H}$. Define a linear and continuous functional

$$a_{x,y}^* \in \mathcal{B}(\mathcal{H}) \rightarrow \mathbb{R} \quad \text{by} \quad a_{x,y}^*(T) := \langle Tx|y \rangle_{\mathcal{H}}, \quad T \in \mathcal{B}(\mathcal{H}).$$

Now we define a set $\mathcal{N} := \{a_{x,y}^* \in \mathcal{B}(\mathcal{H})^* : \|x\| = \|y\| = 1\}$. It is easy to check that the set \mathcal{N} is $*$ -norming. Let us consider a set $\mathcal{D} := \{I\}$, where $I \in \mathcal{B}(\mathcal{H})$, $I(x) = x$. The set D is norming.

We will consider only inner products $\langle \cdot | \cdot \rangle_{\mathcal{B}(\mathcal{H})} : \mathcal{B}(\mathcal{H}) \times \mathcal{B}(\mathcal{H}) \rightarrow \mathcal{B}(\mathcal{H})$, $\langle \cdot | \cdot \rangle_{\mathcal{H}} : \mathcal{H} \times \mathcal{H} \rightarrow \mathbb{R}$, and to shorten the notation we will write $\langle \cdot | \cdot \rangle_{\mathcal{B}} := \langle \cdot | \cdot \rangle_{\mathcal{B}(\mathcal{H})}$ and $\langle \cdot | \cdot \rangle := \langle \cdot | \cdot \rangle_{\mathcal{H}}$.

We define the the following set:

$$\mathcal{F}_2 := \{ \lambda a_{x,y}^* (\langle I | \cdot \rangle_{\mathcal{B}}) + (1 - \lambda) a_{u,w}^* (\langle I | \cdot \rangle_{\mathcal{B}}) \in \mathcal{B}(\mathcal{H})^* : x, y, u, w \in S_{\mathcal{H}}, \lambda \in [0, 1] \};$$

compare (1).

Note that $A \perp_B B$ yields $\alpha A \perp_B \beta B$ for all $\alpha, \beta \in \mathbb{R}$ (i.e., \perp_B is full homogeneous). Without loss of generality, we may assume that $\|A\| = 1$.

Now, suppose that $A \perp_B B$. Applying Lemma 3 (in particular (ii)) we obtain

$$\|A\| = \sup \{ v^*(A) : B \in \ker v^*, v^* \in \mathcal{F}_2 \}.$$

There are $v_n^* \in \mathcal{F}_2$ such that $v_n^*(A) \rightarrow \|A\|$ and $B \in \ker v_n^*$. This means that

$$\begin{aligned} v_n^*(A) &= \lambda_n a_{x_n, y_n}^* (\langle I|A \rangle_{\mathcal{B}}) + (1 - \lambda_n) a_{u_n, w_n}^* (\langle I|A \rangle_{\mathcal{B}}) \\ &= \lambda_n a_{x_n, y_n}^* (I^*A) + (1 - \lambda_n) a_{u_n, w_n}^* (I^*A) \\ &= \lambda_n a_{x_n, y_n}^* (A) + (1 - \lambda_n) a_{u_n, w_n}^* (A) \\ &= \lambda_n \langle Ax_n | y_n \rangle + (1 - \lambda_n) \langle Au_n | w_n \rangle. \end{aligned}$$

Therefore, we obtain

$$\lambda_n \langle Ax_n | y_n \rangle + (1 - \lambda_n) \langle Au_n | w_n \rangle \rightarrow \|A\|. \tag{29}$$

Moreover, $v_n^*(B) = 0$. In a similar way one can prove

$$\lambda_n \langle Bx_n | y_n \rangle + (1 - \lambda_n) \langle Bu_n | w_n \rangle = 0. \tag{30}$$

The set $[0, 1]$ is compact. Since \mathcal{H} is finite dimensional, $S_{\mathcal{H}}$ is a compact set. Therefore, without loss of generality, we may assume that there are vectors x, y, u, w in $S_{\mathcal{H}}$, a number $\lambda \in [0, 1]$ and subsequences $\{x_{n_k}\}$, $\{y_{n_k}\}$, $\{u_{n_k}\}$, $\{w_{n_k}\}$, $\{\lambda_{n_k}\}$ such that $x_{n_k} \rightarrow x$, $y_{n_k} \rightarrow y$, $u_{n_k} \rightarrow u$, $w_{n_k} \rightarrow w$, $\lambda_{n_k} \rightarrow \lambda$. Now the condition (29) becomes

$$\lambda \langle Ax|y \rangle + (1 - \lambda) \langle Au|w \rangle = \|A\|. \tag{31}$$

We get from (30)

$$\lambda \langle Bx|y \rangle + (1 - \lambda) \langle Bu|w \rangle = 0. \tag{32}$$

We will show that $\langle Ax|y \rangle = 1 = \langle Au|w \rangle$. We have

$$1 = \|A\| = \lambda \langle Ax|y \rangle + (1-\lambda) \langle Au|w \rangle$$

and $\langle Ax|y \rangle, \langle Au|w \rangle \in [-1, 1]$. It is easy to check that $1 \in \text{Ext}[-1, 1]$. So, $\langle Ax|y \rangle = 1$ and $\langle Au|w \rangle = 1$.

We have $\langle Ax|y \rangle = 1$ and $\langle Ax|y \rangle \leq \|Ax\| \cdot \|y\| \leq 1 \cdot 1 = 1$. This implies $\langle Ax|y \rangle = \|Ax\| \cdot \|y\|$ and $\|Ax\| = 1 = \|y\|$. So, $Ax = y$, and hence $\|Ax\| = \|A\|$.

In a similar way, one checks that $Au = w$ and $\|Au\| = \|A\|$. Putting $Ax = y$, $Au = w$ into (32), we get

$$\lambda \langle Bx|Ax \rangle + (1-\lambda) \langle Bu|Au \rangle = 0. \quad (33)$$

It follows from (33) that $\langle Bx|Ax \rangle \leq 0 \leq \langle Bu|Au \rangle$ or $\langle Bu|Au \rangle \leq 0 \leq \langle Bx|Ax \rangle$. Without loss of generality, we may assume that

$$\langle Bx|Ax \rangle \leq 0 \leq \langle Bu|Au \rangle. \quad (34)$$

We define a set $\mathcal{M}(A) := \{x \in S_{\mathcal{H}} : \|Ax\| = \|A\|\}$. It is obvious that $\overline{\overline{\mathcal{M}(A)}} \geq 2$. We have two possibilities:

Possibility 1: If $\mathcal{M}(A) = 2$, then $x = u$ or $x = -u$. By (34) we obtain

$$\langle Bx|Ax \rangle \leq 0 \leq \langle Bu|Au \rangle = \langle B(\pm x)|A(\pm x) \rangle = \langle Bx|Ax \rangle,$$

hence $\langle Bx|Ax \rangle = 0$.

Possibility 2: If $\overline{\overline{\mathcal{M}(A)}} > 2$, then $\mathcal{M}(A)$ is connected. Indeed, fix arbitrarily two linearly independent vectors $a, b \in \mathcal{M}(A)$, i.e., $a \neq b \neq -a$. Define $\eta : [0, 1] \rightarrow S_{\mathcal{H}}$ by $\eta(t) := \frac{(1-t)a+tb}{\|(1-t)a+tb\|}$. It is easy to check that η is a path and $\|A(\eta(t))\| = \|A\|$ for all $t \in [0, 1]$. This means that $\eta([0, 1]) \subset \mathcal{M}(A)$, and therefore $\mathcal{M}(A)$ is connected.

Now, we define a mapping $\varphi : \mathcal{M}(A) \rightarrow \mathbb{R}$ by $\varphi(v) := \langle Bv|Av \rangle$, $v \in \mathcal{M}(A)$. Inequalities (34) yield $\varphi(x) \leq 0 \leq \varphi(u)$. The mapping φ is continuous. Moreover, the set $\mathcal{M}(A)$ is connected. Using the Darboux property we get $\varphi(x_o) = 0$ for some $x_o \in \mathcal{M}(A)$. Thus for the vector $x_o \in \mathcal{M}(A)$ we have $\langle Bx_o|Ax_o \rangle = 0$ and $\|Ax_o\| = \|A\|$, i.e., $\|Ax_o\| = \|A\|$ and $Ax_o \perp Bx_o$. Whence, in any case $\exists_{x \in S_{\mathcal{H}}} \|Ax\| = \|A\|, Ax \perp Bx$. \square

REFERENCES

- [1] L.J. ARAMBAŠIĆ AND R. RAJIĆ, *The Birkhoff–James orthogonality in Hilbert C^* -modules*, Linear Algebra Appl. **437** (2012), no. 7, 1913–1929.
- [2] R. BHATIA, P. ŠEMRL, *Orthogonality of matrices and some distance problems*, Linear Algebra Appl. **287** (1999), no. 1–3, 77–85.
- [3] T. BHATTACHARYYA, P. GROVER, *Characterization of Birkhoff–James orthogonality*, J. Math. Anal. Appl. **407** (2013), 350–358.
- [4] G. BIRKHOFF, *Orthogonality in linear metric spaces*, Duke Math. J. **1** (1935), 169–172.
- [5] S. S. DRAGOMIR, *Semi-Inner Products and Applications*, Nova Science Publishers, Inc., Hauppauge, NY, 2004.

- [6] R. C. JAMES, *Orthogonality and linear functionals in normed linear spaces*, Trans. Amer. Math. Soc., **61** (1947), 265–292.
- [7] I. SINGER, *Best Approximation in Normed Linear Spaces by Elements of Linear Subspaces*, Springer-Verlag, Berlin, Heidelberg, New York, 1970.

(Received November 27, 2015)

Paweł Wójcik
Institute of Mathematics
Pedagogical University of Cracow
Podchorążych 2, 30-084 Kraków, Poland
e-mail: pwojcik@up.krakow.pl