

THE PRODUCT OF OPERATORS AND THEIR THE MOORE–PENROSE INVERSES ON HILBERT C^* -MODULES

MARYAM JALAEIAN, MEHDI MOHAMMADZADEH KARIZAKI*
AND MAHMOUD HASSANI

(Communicated by R. Rajić)

Abstract. We assure the existence of the Moore–Penrose inverse of a product UTS , under the assumptions that T has a closed range and that there exist U' and S' such that $U'UT = T = TSS'$, and then we characterize the Moore–Penrose inverse of UTS in terms of the corresponding inverses of T . Also, we obtain the block matrix decomposition of operators, which implies that the reverse order law for operators establishes. Finally we achieve some relations between the product of operators and their the Moore-Penrose inverses.

1. Introduction

Hilbert C^* -modules are generalizations of Hilbert spaces by allowing inner products to take values in a C^* -algebra rather than in the field of real or complex numbers. Some fundamental properties of inner product spaces are no longer valid in inner product C^* -modules in their complete generality. Consequently, when we are studying inner product C^* -modules, it is always of interest under which conditions as well as which more general, situations might appear. The book [4] is used as a standard reference source.

The Moore-Penrose inverse is a topic of considerable research in matrix theory, ring theory, operator algebra with a variety of applications including control theory, signal processing and estimation theory. The existence of the Moore-Penrose inverse is of interest in the study of the structure of a non commutative algebra.

Xu and Sheng [8] showed that a bounded adjointable operator between two Hilbert C^* -modules admits a bounded the Moore–Penrose inverse if and only if that operator has closed range. Ensuring of the existence of the Moore-Penrose inverse of product operators and its computing is not an easy task in general.

Gouveia and Puystjens introduced an equation on finite matrices and applied it for several familiar factorizations of matrices such as the polar, the Schur, and the singular-value decompositions [2]. Patrício in [7] gave necessary and sufficient conditions in order to product of known operators be the Moore–Penrose invertible.

Mathematics subject classification (2010): 15A09, 46L08, 46L05.

Keywords and phrases: Orthogonally complemented, Moore-Penrose inverse, Hilbert C^* -module.

* Corresponding author.

In this paper, the existence of $(TS)^\dagger$, $(UT)^\dagger$ and $(UTS)^\dagger$, under the assumption that T has a closed range and the existence of U' and S' such that $U'UT = T = TSS'$, is guaranteed, and then we characterize the Moore-Penrose inverse UTS in terms of the corresponding inverses of T , and also by focuses on block matrix decomposition of operators reobtain it, in terms of the corresponding the Moore-Penrose inverse T . The same technique enabling us to find that conditions under which the reverse order law for operators hold and it leads to obtain new results of the product of operators and their the Moore-Penrose inverses in the infinite dimensional settings on the Hilbert C^* -module.

Let us fix our notation and terminology. A Hilbert \mathfrak{A} -module \mathcal{X} is a right \mathfrak{A} -module equipped with an \mathfrak{A} -valued inner product $\langle \cdot, \cdot \rangle : \mathcal{X} \times \mathcal{X} \rightarrow \mathfrak{A}$ such that \mathcal{X} is complete with respect to the induced norm $\|x\| = \|\langle x, x \rangle\|^{1/2}$ ($x \in \mathcal{X}$). Throughout the rest of this paper, \mathfrak{A} denotes a C^* -algebra and $\mathcal{X}, \mathcal{Y}, \mathcal{Z}$ and \mathcal{H} denote Hilbert \mathfrak{A} -modules. Let $\mathcal{L}(\mathcal{X}, \mathcal{Y})$ be the set of operators $T : \mathcal{X} \rightarrow \mathcal{Y}$ for which there is an operator $T^* : \mathcal{Y} \rightarrow \mathcal{X}$ such that $\langle Tx, y \rangle = \langle x, T^*y \rangle$ for any $x \in \mathcal{X}$ and $y \in \mathcal{Y}$. It is known that any element $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ must be bounded and \mathfrak{A} -linear. We call $\mathcal{L}(\mathcal{X}, \mathcal{Y})$ the set of adjointable operators from \mathcal{X} to \mathcal{Y} . For any $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$, the range and the null space of T are represented by $\mathcal{R}(T)$ and $\mathcal{N}(T)$, respectively. In case $\mathcal{X} = \mathcal{Y}$, the space $\mathcal{L}(\mathcal{X}, \mathcal{X})$, which is abbreviated to $\mathcal{L}(\mathcal{X})$, is a C^* -algebra.

A closed submodule M of \mathcal{X} is said to be *orthogonally complemented* if $\mathcal{X} = M \oplus M^\perp$, where $M^\perp = \{x \in \mathcal{X} : \langle x, y \rangle = 0 \text{ for any } y \in M\}$. If $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ does not have closed range, then neither $\mathcal{N}(T)$ nor $\overline{\mathcal{R}(T)}$ needs to be orthogonally complemented. In addition, if $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ and $\overline{\mathcal{R}(T^*)}$ is not orthogonally complemented, then it may happen that $\mathcal{N}(T)^\perp \neq \overline{\mathcal{R}(T^*)}$; see [4, 5]. The above facts show that the theory of Hilbert C^* -modules are much different and more complicated than that of Hilbert spaces.

An operator $S \in \mathcal{L}(\mathcal{Y}, \mathcal{X})$ is an inner inverse of T , if $TST = T$ holds. In this case T is inner invertible, or relatively regular. It is well known that T is inner invertible if and only if $\mathcal{R}(T)$ is closed in \mathcal{Y} . The Moore-Penrose inverse of $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ is the operator $X \in \mathcal{L}(\mathcal{Y}, \mathcal{X})$ which satisfies the Penrose equations

$$(1) \ TXT = T, \quad (2) \ XTX = X, \quad (3) \ (TX)^* = TX, \quad (4) \ (XT)^* = XT.$$

The Moore–Penrose inverse of T exists if and only if $\mathcal{R}(T)$ is closed in \mathcal{Y} . If the Moore–Penrose inverse of T exists, then it is unique, and it is denoted by T^\dagger . If $\theta \subseteq \{1, 2, 3, 4\}$ and X satisfies the equations (i) for all $i \in \theta$, then X is a θ -inverse of T . The set of all θ -inverses of T is denoted by $T\{\theta\}$. In particular, $T\{1, 2, 3, 4\} = \{T^\dagger\}$.

The term orthogonal projection will be reserved for T which is self-adjoint and idempotent. From the definition of the Moore–Penrose inverse, it can be proved that the Moore–Penrose inverse of an operator (if it exists) is unique and $T^\dagger T$ and TT^\dagger are orthogonal projections into $\mathcal{R}(T^*)$ and $\mathcal{R}(T)$, respectively. Clearly, T is the Moore–Penrose invertible if and only if T^* is the Moore–Penrose invertible [4, Theorem 3.2], and in this case $(T^*)^\dagger = (T^\dagger)^*$, $(T^*T)^\dagger = T^\dagger(T^*)^\dagger$, $T^* = T^*TT^\dagger$ and $T^\dagger = T^*(TT^*)^\dagger$.

2. The Moore-Penrose inverse of a product

In the following theorems, the existence of $(TS)^\dagger$, $(UT)^\dagger$ and $(UTS)^\dagger$ satisfying the stated conditions that T has a closed range and the existence of U' and S' such that $U'UT = T = TSS'$, is guaranteed by Theorems 1 and 2. In order to compute their the Moore-Penrose inverses, we determine inverse of two operators in terms of the corresponding the Moore-Penrose inverse of T , that they play fundamental roles in the related results in this section.

THEOREM 1. *Let $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$, $S \in \mathcal{L}(\mathcal{Z}, \mathcal{X})$, $U \in \mathcal{L}(\mathcal{Y}, \mathcal{X})$ and T have closed range. If there exist operators $U' \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ and $S' \in \mathcal{L}(\mathcal{X}, \mathcal{Z})$ such that*

$$U'UT = T = TSS',$$

then

- (i) UT and TS have closed ranges and $T^\dagger U' \in (UT)\{1, 2, 4\}$ and $S'T^\dagger \in (TS)\{1, 2, 3\}$.
(ii) $(UT)^*UT + 1 - T^\dagger T$ and $(TS)(TS)^* + 1 - TT^\dagger$ are invertible operators. In this case,

$$((UT)^*UT + 1 - T^\dagger T)^{-1} = (UT)^\dagger((UT)^*)^\dagger + 1 - T^\dagger T$$

and

$$(TS(TS)^* + 1 - TT^\dagger)^{-1} = ((TS)^*)^\dagger(TS)^\dagger + 1 - TT^\dagger.$$

Proof. (i) Putting $X = T^\dagger U'$ implies that

$$\begin{aligned} UTXUT &= UTT^\dagger U'UT = UTT^\dagger T = UT, \\ XUTX &= T^\dagger U'UTT^\dagger U' = T^\dagger U' = X, \\ (XUT)^* &= (T^\dagger U'UT)^* = (T^\dagger T)^* = T^\dagger T. \end{aligned}$$

Then $T^\dagger U' \in (UT)\{1, 2, 4\}$. It immediately concludes that UT has closed range.

Also, letting $Y = S'T^\dagger$ concludes that

$$\begin{aligned} TSYTS &= TSS'T^\dagger TS = TT^\dagger TS = TS, \\ YTSY &= S'T^\dagger TSS'T^\dagger = S'T^\dagger TT^\dagger = S'T^\dagger = Y, \\ (TSY)^* &= (TSS'T^\dagger)^* = (TT^\dagger)^* = TT^\dagger. \end{aligned}$$

Then TS has closed range and $S'T^\dagger \in (TS)\{1, 2, 3\}$.

(ii) The statement (i) concludes that UT and TS have closed ranges. By [6, Corollary 2.4] $((UT)^*UT)^\dagger$ exists and $((UT)^*UT)^\dagger = (UT)^\dagger((UT)^*)^\dagger$. Taking adjoint of $U'UT = T$ we get $T^*U^*(U')^* = T^*$. This implies that $\mathcal{R}(T^*) = \mathcal{R}((UT)^*)$, therefore $(UT)^\dagger UT = T^\dagger T$. Now, putting $C = (UT)^*UT + 1 - T^\dagger T$ and $D = (UT)^\dagger((UT)^*)^\dagger +$

$1 - T^\dagger T$ implies that

$$\begin{aligned}
 CD &= \left((UT)^* UT + 1 - T^\dagger T \right) \left((UT)^\dagger ((UT)^*)^\dagger + 1 - T^\dagger T \right) \\
 &= (UT)^* UT (UT)^\dagger ((UT)^*)^\dagger + (UT)^* UT - (UT)^* UT T^\dagger T \\
 &\quad + (UT)^\dagger ((UT)^*)^\dagger + 1 - T^\dagger T \\
 &\quad - T^\dagger T (UT)^\dagger ((UT)^*)^\dagger - T^\dagger T + T^\dagger T T^\dagger T \\
 &= (UT)^* ((UT)^*)^\dagger + (UT)^* UT - (UT)^* UT \\
 &\quad + (UT)^\dagger ((UT)^*)^\dagger + 1 - T^\dagger T \\
 &\quad - (UT)^\dagger UT (UT)^\dagger ((UT)^*)^\dagger - T^\dagger T + T^\dagger T \\
 &= (UT)^* ((UT)^*)^\dagger + (UT)^\dagger ((UT)^*)^\dagger + 1 - T^\dagger T - (UT)^\dagger ((UT)^*)^\dagger \\
 &= (UT)^* ((UT)^\dagger)^* + 1 - T^\dagger T \\
 &= \left((UT)^\dagger UT \right)^* + 1 - T^\dagger T \\
 &= (UT)^\dagger UT + 1 - T^\dagger T \\
 &= T^\dagger T + 1 - T^\dagger T \\
 &= 1.
 \end{aligned}$$

Since $(UT)^\dagger UT = T^\dagger T$, therefore

$$\begin{aligned}
 (UT)^\dagger ((UT)^*)^\dagger T^\dagger T &= (UT)^\dagger ((UT)^*)^\dagger (UT)^\dagger (UT) \\
 &= (UT)^\dagger ((UT)^*)^\dagger.
 \end{aligned} \tag{1}$$

Also we obtain

$$\begin{aligned}
 DC &= \left((UT)^\dagger ((UT)^*)^\dagger + 1 - T^\dagger T \right) \left((UT)^* UT + 1 - T^\dagger T \right) \\
 &= (UT)^\dagger ((UT)^*)^\dagger (UT)^* UT + (UT)^\dagger ((UT)^*)^\dagger - (UT)^\dagger ((UT)^*)^\dagger T^\dagger T \\
 &\quad + (UT)^* UT + 1 - T^\dagger T \\
 &\quad - T^\dagger T (UT)^* UT - T^\dagger T + T^\dagger T T^\dagger T \\
 \text{(by 1)} &= (UT)^\dagger UT + (UT)^\dagger ((UT)^*)^\dagger - (UT)^\dagger ((UT)^*)^\dagger \\
 &\quad + (UT)^* UT + 1 - T^\dagger T - (UT)^\dagger UT (UT)^* UT \\
 &= (UT)^\dagger UT + (UT)^* UT + 1 - T^\dagger T - (UT)^* UT \\
 &= (UT)^\dagger UT + 1 - T^\dagger T \\
 &= 1.
 \end{aligned}$$

With similar argument, we prove that $((TS)^*)^\dagger (TS)^\dagger + 1 - TT^\dagger$ is invertible. Since TS has closed range then [6, Corollary 2.4] $(TS(TS)^*)^\dagger$ exists and $(TS(TS)^*)^\dagger = ((TS)^*)^\dagger (TS)^\dagger$. On the other hand, from $T = TSS'$ it follows that $TS(TS)^\dagger = TT^\dagger$ and $\mathcal{R}(T) = \mathcal{R}(TS)$.

Now, we put $G = TS(TS)^* + 1 - TT^\dagger$ and $H = ((TS)^*)^\dagger(TS)^\dagger + 1 - TT^\dagger$. Then

$$\begin{aligned}
 GH &= \left(TS(TS)^* + 1 - TT^\dagger \right) \left(((TS)^*)^\dagger(TS)^\dagger + 1 - TT^\dagger \right) \\
 &= TS(TS)^* ((TS)^*)^\dagger(TS)^\dagger + TS(TS)^* - TS(TS)^* TT^\dagger \\
 &\quad + ((TS)^*)^\dagger(TS)^\dagger + 1 - TT^\dagger \\
 &\quad - TT^\dagger ((TS)^*)^\dagger(TS)^\dagger - TT^\dagger + TT^\dagger TT^\dagger \\
 &= TS(TS)^\dagger + TS(TS)^* - TS(TS)^* TS(TS)^\dagger \\
 &\quad + ((TS)^*)^\dagger(TS)^\dagger + 1 - TT^\dagger \\
 &\quad - TS(TS)^\dagger ((TS)^*)^\dagger(TS)^\dagger - TT^\dagger + TT^\dagger \\
 &= TS(TS)^\dagger + TS(TS)^* - TS(TS)^* \\
 &\quad + ((TS)^*)^\dagger(TS)^\dagger + 1 - TS(TS)^\dagger - ((TS)^*)^\dagger(TS)^\dagger \\
 &= 1.
 \end{aligned}$$

Also,

$$\begin{aligned}
 HG &= \left(((TS)^*)^\dagger(TS)^\dagger + 1 - TT^\dagger \right) \left(TS(TS)^* + 1 - TT^\dagger \right) \\
 &= ((TS)^*)^\dagger(TS)^\dagger TS(TS)^* + ((TS)^*)^\dagger(TS)^\dagger - ((TS)^*)^\dagger(TS)^\dagger TT^\dagger \\
 &\quad + TS(TS)^* + 1 - TT^\dagger \\
 &\quad - TT^\dagger TS(TS)^* - TT^\dagger + TT^\dagger TT^\dagger \\
 &= ((TS)^*)^\dagger(TS)^* + ((TS)^*)^\dagger(TS)^\dagger - ((TS)^*)^\dagger(TS)^\dagger TS(TS)^\dagger \\
 &\quad + TS(TS)^* + 1 - TT^\dagger \\
 &\quad - TS(TS)^\dagger TS(TS)^* - TT^\dagger + TT^\dagger \\
 &= ((TS)^*)^\dagger(TS)^* + ((TS)^*)^\dagger(TS)^\dagger - ((TS)^*)^\dagger(TS)^\dagger \\
 &\quad + TS(TS)^* + 1 - TT^\dagger - TS(TS)^* \\
 &= ((TS)(TS)^\dagger)^* + 1 - TT^\dagger \\
 &= (TS)(TS)^\dagger + 1 - TT^\dagger \\
 &= 1.
 \end{aligned}$$

This completes the proof. \square

We notice that $T, S \in \mathcal{L}(\mathcal{X})$, then $[T, S] = TS - ST$ denotes the commutator of T and S .

THEOREM 2. *Let $\mathcal{X}, \mathcal{Y}, \mathcal{Z}, \mathcal{H}$ be Hilbert \mathfrak{A} -modules and $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ has closed range and $S \in \mathcal{L}(\mathcal{Z}, \mathcal{X}), U \in \mathcal{L}(\mathcal{Y}, \mathcal{H})$. If there exist operators $U' \in \mathcal{L}(\mathcal{H}, \mathcal{Y})$ and $S' \in \mathcal{L}(\mathcal{X}, \mathcal{Z})$ such that*

$$U'UT = T = TSS'.$$

Then

- (i) $(TS)^\dagger = (TS)^*G^{-1}$ and $(UT)^\dagger = C^{-1}(UT)^*$,
- (ii) $[G^{-1}, TS(TS)^\dagger] = 0$ and $[C^{-1}, (UT)^\dagger UT] = 0$,
- (iii) UTS has closed range and $(UTS)^\dagger = (TS)^*G^{-1}TC^{-1}(UT)^*$,
- (iv) $S^*C(UT)^\dagger = (TS)^\dagger GU^*$,
- where $C = (UT)^*UT + 1 - T^\dagger T$ and $G = (TS)(TS)^* + 1 - TT^\dagger$.

Proof. (i) From $U'UT = T = TSS'$ we get the following: $\mathcal{R}(T) = \mathcal{R}(TS)$ and $\mathcal{R}(T^*) = \mathcal{R}((UT)^*)$. The first equality implies that $TT^\dagger = TS(TS)^\dagger$. From the second equality it follows that $T^\dagger T = (UT)^\dagger UT$. By details which are shown in the proof of Theorem 2, we conclude that C and G are invertible and their inverses are D and H , respectively. Hence we have

$$\begin{aligned} (TS)^*G^{-1} &= (TS)^* \left(((TS)^*)^\dagger (TS)^\dagger + 1 - TT^\dagger \right) \\ &= (TS)^* ((TS)^*)^\dagger (TS)^\dagger + (TS)^* - (TS)^*(TS)(TS)^\dagger \\ &= (TS)^* ((TS)^*)^\dagger (TS)^\dagger + (TS)^* - (TS)^* \\ &= (TS)^* ((TS)^*)^\dagger (TS)^\dagger \\ &= (TS)^\dagger. \end{aligned}$$

and

$$\begin{aligned} C^{-1}(UT)^* &= \left((UT)^\dagger ((UT)^*)^\dagger + 1 - T^\dagger T \right) (UT)^* \\ &= (UT)^\dagger ((UT)^*)^\dagger (UT)^* + (UT)^* - (UT)^\dagger UT(UT)^* \\ &= (UT)^\dagger ((UT)^*)^\dagger (UT)^* + (UT)^* - (UT)^* \\ &= (UT)^\dagger ((UT)^*)^\dagger (UT)^* \\ &= (UT)^\dagger. \end{aligned}$$

(ii) From statement (i) we have G is invertible and $(TS)^*G^{-1} = (TS)^\dagger$, also G is self adjoint. Taking adjoint, we obtain $G^{-1}(TS) = ((TS)^*)^\dagger$, then $\mathcal{R}(G^{-1}(TS)) = \mathcal{R}((TS)^*)^\dagger = \mathcal{R}(TS)$. Hence by [1, Lemma 2.1] the desired result follows.

Analogously, we can prove that C is invertible and $C^{-1}(UT)^* = (UT)^\dagger$, also C is self adjoint. Then $\mathcal{R}(C^{-1}(UT)^*) = \mathcal{R}((UT)^\dagger) = \mathcal{R}((UT)^*)$. Reuse by [1, Lemma 2.1] concludes that $[C^{-1}, (UT)^\dagger UT] = 0$.

(iii) The proof of the statement (i) can be used to see that C and G are invertible and $(TS)^*G^{-1} = (TS)^\dagger$ and $C^{-1}(UT)^* = (UT)^\dagger$. Letting $B = UTS$ and $X = (TS)^*G^{-1}TC^{-1}(UT)^*$ conclude that

$$\begin{aligned} BXB &= UTS(TS)^*G^{-1}TC^{-1}(UT)^*UTS \\ &= UTS(TS)^\dagger T(UT)^\dagger UTS \\ &= U \left(TS(TS)^\dagger \right) T \left((UT)^\dagger UT \right) S \\ &= UTT^\dagger TT^\dagger TS \\ &= UTS. \end{aligned}$$

and in the same way we reach

$$\begin{aligned}
 XBX &= (TS)^*G^{-1}TC^{-1}(UT)^*UTS(TS)^*G^{-1}TC^{-1}(UT)^* \\
 &= (TS)^\dagger T(UT)^\dagger UTS(TS)^\dagger T(UT)^\dagger \\
 &= (TS)^\dagger TT^\dagger TS(TS)^\dagger T(UT)^\dagger \\
 &= (TS)^\dagger TS(TS)^\dagger T(UT)^\dagger \\
 &= (TS)^\dagger TT^\dagger T(UT)^\dagger \\
 &= (TS)^\dagger T(UT)^\dagger \\
 &= X.
 \end{aligned}$$

Also BX and XB are orthogonal projections, since

$$\begin{aligned}
 BX &= UTS(TS)^*G^{-1}TC^{-1}(UT)^* \\
 &= UTS(TS)^\dagger T(UT)^\dagger \\
 &= UTT^\dagger T(UT)^\dagger \\
 &= UT(UT)^\dagger,
 \end{aligned}$$

and

$$\begin{aligned}
 XB &= (TS)^*G^{-1}TC^{-1}(UT)^*UTS \\
 &= (TS)^\dagger \left(T(UT)^\dagger UT \right) S \\
 &= (TS)^\dagger \left(TT^\dagger T \right) S \\
 &= (TS)^\dagger TS.
 \end{aligned}$$

Then UTS has closed range and the uniqueness of the Moore-Penrose inverse implies that $(UTS)^\dagger = (TS)^*G^{-1}TC^{-1}(UT)^*$.

(iv) Multiplying the equality $(TS)^\dagger = (TS)^*G^{-1}$ by GU^* on the right side and the equality $(UT)^\dagger = C^{-1}(UT)^*$ by S^*C on the left side, the desired result follows. \square

3. Matrix representation for $U^1UT = T = TSS'$

In this section, we obtain the block matrix decomposition of operators, which implies that the reverse order law for operators establishes. Moreover, we achieve some relations between the product of operators and their the Moore-Penrose inverses.

The following theorem provides some conditions in order to U^1U and SS' are orthogonal projections.

THEOREM 3. *Suppose that $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ has closed range, $S \in \mathcal{L}(\mathcal{Z}, \mathcal{X})$ and $U \in \mathcal{L}(\mathcal{Y}, \mathcal{K})$. If there exist operators $U^1 \in \mathcal{L}(\mathcal{K}, \mathcal{Y})$ and $S' \in \mathcal{L}(\mathcal{X}, \mathcal{Z})$ such that*

$$U^1UT = T = TSS', \quad \mathcal{R}(S) = \mathcal{R}(T^*), \quad \mathcal{R}(U^*) = \mathcal{R}(T),$$

then

(i) U^tU and SS^t are orthogonal projections,

(ii) $S(TS)^\dagger = (UT)^\dagger U$.

Proof. (i) Using [3, Lemma 2.3] and [3, Lemma 2.4], the orthogonal sums $\mathcal{X} = \mathcal{R}(T^*) \oplus \mathcal{N}(T)$, $\mathcal{Y} = \mathcal{R}(T) \oplus \mathcal{N}(T^*)$, $\mathcal{Z} = \mathcal{R}(S^*) \oplus \mathcal{N}(S)$ and $\mathcal{H} = \mathcal{R}(U) \oplus \mathcal{N}(U^*)$ imply that the matrix representation of T has the form $T = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ where T_1 is invertible and $T^\dagger = \begin{bmatrix} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix}$. Also $S = \begin{bmatrix} S_1 & 0 \\ S_3 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(S^*) \\ \mathcal{N}(S) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix}$ and $S^t = \begin{bmatrix} S_1^t & S_2^t \\ S_3^t & S_4^t \end{bmatrix}$, $S^\dagger = \begin{bmatrix} D^{-1}S_1^* & D^{-1}S_3^* \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(S^*) \\ \mathcal{N}(S) \end{bmatrix}$, where $D = S_1^*S_1 + S_3^*S_3$ is invertible. Also, we have $U = \begin{bmatrix} U_1 & U_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(U) \\ \mathcal{N}(U^*) \end{bmatrix}$ and $U^t = \begin{bmatrix} U_1^t & U_2^t \\ U_3^t & U_4^t \end{bmatrix}$, $U^\dagger = \begin{bmatrix} U_1^t E^{-1} & 0 \\ U_2^t E^{-1} & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(U) \\ \mathcal{N}(U^*) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$, where $E = U_1U_1^t + U_2U_2^t$ is invertible. Since $\mathcal{R}(S) = \mathcal{R}(T^*)$ then

$$\begin{aligned} SS^\dagger = T^\dagger T &\Leftrightarrow \begin{bmatrix} S_1 & 0 \\ S_3 & 0 \end{bmatrix} \begin{bmatrix} D^{-1}S_1^* & D^{-1}S_3^* \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix} \\ &\Leftrightarrow \begin{bmatrix} S_1 D^{-1}S_1^* & S_1 D^{-1}S_3^* \\ S_3 D^{-1}S_1^* & S_3 D^{-1}S_3^* \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}. \end{aligned} \tag{1}$$

Equation (1) implies that

$$S_1 D^{-1}S_3^* = 0 \tag{2}$$

$$S_3 D^{-1}S_3^* = 0. \tag{3}$$

By multiplication S_1^* on the left of the equation (2) and multiplication S_3^* on the left of equation (3) we conclude that

$$S_1^*S_1 D^{-1}S_3^* + S_3^*S_3 D^{-1}S_3^* = (S_1^*S_1 + S_3^*S_3)D^{-1}S_3^* = 0,$$

therefore, $S_3 = 0$. Similarly, since $\mathcal{R}(U^*) = \mathcal{R}(T)$ then $U_2 = 0$.

Now consider the following chain of equivalences, which is related to the assumption $U^tUT = T$:

$$\begin{aligned} U^tUT = T &\Leftrightarrow \begin{bmatrix} U_1^t & U_2^t \\ U_3^t & U_4^t \end{bmatrix} \begin{bmatrix} U_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \\ &\Leftrightarrow \begin{bmatrix} U_1^t U_1 T_1 & 0 \\ U_3^t U_1 T_1 & 0 \end{bmatrix} = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \\ &\Leftrightarrow U_1^t U_1 T_1 = T_1, \quad U_3^t U_1 T_1 = 0. \end{aligned}$$

Invertibility of T_1 implies that $U_1^t U_1 = 1$ and $U_3^t U_1 = 0$. So we obtain $U^tU = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$. Similar arguments show that $SS^t = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$. It is clear, U^tU and SS^t are orthogonal projections.

(ii) Using [3, Lemma 2.3], the orthogonal complemented submodules $\mathcal{X} = \mathcal{R}(T^*) \oplus \mathcal{N}(T)$ and $\mathcal{Y} = \mathcal{R}(T) \oplus \mathcal{N}(T^*)$ and $\mathcal{Z} = \mathcal{Z}_1 \oplus \mathcal{Z}_2$ and $\mathcal{K} = \mathcal{K}_1 \oplus \mathcal{K}_2$, conclude that matrix decompositions $T = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ where T_1 is invertible.

Also $S = \begin{bmatrix} S_1 & S_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{Z}_1 \\ \mathcal{Z}_2 \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(S) \\ \mathcal{N}(S^*) \end{bmatrix}$ and $U = \begin{bmatrix} U_1 & 0 \\ U_2 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(U^*) \\ \mathcal{N}(U) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{K}_1 \\ \mathcal{K}_2 \end{bmatrix}$. Reuse [3, Lemma 2.3] derives

$$S(TS)^\dagger = \begin{bmatrix} S_1 & S_2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} (T_1S_1)^*E^{-1} & 0 \\ (T_1S_2)^*E^{-1} & 0 \end{bmatrix} = \begin{bmatrix} S_1(T_1S_1)^*E^{-1} + S_2(T_1S_2)^*E^{-1} & 0 \\ 0 & 0 \end{bmatrix}$$

and

$$\begin{aligned} (UT)^\dagger U &= \begin{bmatrix} F^{-1}(U_1T_1)^* & F^{-1}(U_2T_1)^* \\ 0 & 0 \end{bmatrix} \begin{bmatrix} U_1 & 0 \\ U_2 & 0 \end{bmatrix} \\ &= \begin{bmatrix} F^{-1}(U_1T_1)^*U_1 + F^{-1}(U_2T_1)^*U_2 & 0 \\ 0 & 0 \end{bmatrix}, \end{aligned}$$

where $E = T_1S_1(T_1S_1)^* + T_1S_2(T_1S_2)^*$ and $F = (U_1T_1)^*U_1T_1 + (U_2T_1)^*U_2T_1$ are invertible. Since

$$(S_1S_1^* + S_2S_2^*)T_1^*E^{-1} = (S_1S_1^* + S_2S_2^*)T_1^*(T_1^*)^{-1}(S_1S_1^* + S_2S_2^*)^{-1}T_1^{-1} = T_1^{-1}$$

and

$$F^{-1}T_1^*(U_1^*U_1 + U_2^*U_2) = T_1^{-1}(U_1^*U_1 + U_2^*U_2)^{-1}(T_1^*)^{-1}T_1^*(U_1^*U_1 + U_2^*U_2) = T_1^{-1}$$

hold, then $\begin{bmatrix} (S_1S_1^* + S_2S_2^*)T_1^*E^{-1} & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} F^{-1}T_1^*(U_1^*U_1 + U_2^*U_2) & 0 \\ 0 & 0 \end{bmatrix}$ and consequently, $S(TS)^\dagger = (UT)^\dagger U$. \square

In the following theorem, by applying the block matrix decomposition trick, we reobtain $(UTS)^\dagger$, in terms of the corresponding the Moore-Penrose inverse T , and we show that the reverse order law holds for product of operators.

THEOREM 4. *Let $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ have closed range and $S \in \mathcal{L}(\mathcal{X})$, $U \in \mathcal{L}(\mathcal{Y})$. If there exist operators $U' \in \mathcal{L}(\mathcal{K}, \mathcal{Y})$ and $S' \in \mathcal{L}(\mathcal{X}, \mathcal{Z})$ such that $U'UT = T = TSS'$, then*

- (i) UTS has closed range and $(UTS)^\dagger = (TS)^\dagger T(UT)^\dagger$;
- (ii) If S and U have closed ranges then $(UTS)^\dagger = S^\dagger T^\dagger U^\dagger$, under the additional assumption that $(TS)^\dagger = S^\dagger T^\dagger$ and $(UT)^\dagger = T^\dagger U^\dagger$
- (iii) $(UTS(TS)^\dagger)^\dagger = T(UT)^\dagger$;
- (iv) $(UTT^\dagger)^\dagger = T(UT)^\dagger$;
- (v) $((UT)^\dagger UTS)^\dagger = (TS)^\dagger T$;
- (vi) $(T^\dagger TS)^\dagger = (TS)^\dagger T$;

- (vii) $(UTS)^\dagger UT(UT)^\dagger = (UTS)^\dagger$;
- (viii) $(TS)^\dagger TS(UTS)^\dagger = (UTS)^\dagger$;
- (ix) $(UTS)^\dagger = S^\dagger(UT)^\dagger$, under the additional assumption that $\mathcal{R}(T^*) = \mathcal{R}(S)$.

Proof. Since $U^1UT = T = TSS'$, it follows that $\mathcal{R}(T) = \mathcal{R}(TS)$ and $\mathcal{R}(T^*) = \mathcal{R}((UT)^*)$. Using [3, Lemma 2.3], the orthogonal complemented submodules $\mathcal{R}(T^*)$ and $\mathcal{R}(T)$ conclude that matrix decompositions $T = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$

and $T^\dagger = \begin{bmatrix} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix}$. Also $S = \begin{bmatrix} S_1 & S_2 \\ S_3 & S_4 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix}$.

Since $\mathcal{R}(T) = \mathcal{R}(TS)$ by [3, Lemma 2.4] matrix form TS is $TS = \begin{bmatrix} H_1 & H_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ and $(TS)^\dagger = \begin{bmatrix} H_1^*D^{-1} & 0 \\ H_2^*D^{-1} & 0 \end{bmatrix}$, where $D = H_1H_1^* + H_2H_2^*$ is invertible. On the

other hand, product of matrix forms T and S conclude that $TS = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} S_1 & S_2 \\ S_3 & S_4 \end{bmatrix} = \begin{bmatrix} T_1S_1 & T_1S_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$. In the same way, by [3, Lemma 2.4], $UT = \begin{bmatrix} K_1 & 0 \\ K_2 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ and $(UT)^\dagger = \begin{bmatrix} F^{-1}K_1^* & F^{-1}K_2^* \\ 0 & 0 \end{bmatrix}$, where $F = K_1^*K_1 +$

$K_2^*K_2$ is invertible. The product of matrix forms U and T lead to $UT = \begin{bmatrix} U_1 & U_2 \\ U_3 & U_4 \end{bmatrix} \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} U_1T_1 & 0 \\ U_3T_1 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$. With comparing these representations matrix of TS

ensure that $T_1S_1 = H_1$, $T_1S_2 = H_2$ and $T_1(S_1S_1^* + S_2S_2^*)T_1^* = D$. Invertibility D and T_1 imply that $E = S_1S_1^* + S_2S_2^*$ is invertible. Also, we compare the representations matrix of UT and conclude that $U_1T_1 = K_1$, $U_3T_1 = K_2$ and $T_1^*(U_1^*U_1 + U_3^*U_3)T_1 = F$. Invertibility F and T_1 imply that $J = U_1^*U_1 + U_3^*U_3$ is invertible.

(i) Let $X = (TS)^\dagger T(UT)^\dagger$. We conclude that the operator X has the following matrix form:

$$\begin{aligned} X &= (TS)^\dagger T(UT)^\dagger = \begin{bmatrix} H_1^*D^{-1} & 0 \\ H_2^*D^{-1} & 0 \end{bmatrix} \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} F^{-1}K_1^* & F^{-1}K_2^* \\ 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} S_1^*E^{-1}T_1^{-1}J^{-1}U_1^* & S_1^*E^{-1}T_1^{-1}J^{-1}U_3^* \\ S_2^*E^{-1}T_1^{-1}J^{-1}U_1^* & S_2^*E^{-1}T_1^{-1}J^{-1}U_3^* \end{bmatrix}. \end{aligned}$$

Since

$$\begin{aligned} &UTSXUTS \\ &= \begin{bmatrix} U_1T_1S_1 & U_1T_1S_2 \\ U_3T_1S_1 & U_3T_1S_2 \end{bmatrix} \begin{bmatrix} S_1^*E^{-1}T_1^{-1}J^{-1}U_1^* & S_1^*E^{-1}T_1^{-1}J^{-1}U_3^* \\ S_2^*E^{-1}T_1^{-1}J^{-1}U_1^* & S_2^*E^{-1}T_1^{-1}J^{-1}U_3^* \end{bmatrix} \begin{bmatrix} U_1T_1S_1 & U_1T_1S_2 \\ U_3T_1S_1 & U_3T_1S_2 \end{bmatrix} \\ &= \begin{bmatrix} U_1T_1(S_1S_1^* + S_2S_2^*)E^{-1}T_1^{-1}J^{-1}U_1^* & U_1T_1(S_1S_1^* + S_2S_2^*)E^{-1}T_1^{-1}J^{-1}U_3^* \\ U_3T_1(S_1S_1^* + S_2S_2^*)E^{-1}T_1^{-1}J^{-1}U_1^* & U_3T_1(S_1S_1^* + S_2S_2^*)E^{-1}T_1^{-1}J^{-1}U_3^* \end{bmatrix} \\ &\quad \begin{bmatrix} U_1T_1S_1 & U_1T_1S_2 \\ U_3T_1S_1 & U_3T_1S_2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned}
 &= \begin{bmatrix} U_1 J^{-1} U_1^* & U_1 J^{-1} U_3^* \\ U_3 J^{-1} U_1^* & U_3 J^{-1} U_3^* \end{bmatrix} \begin{bmatrix} U_1 T_1 S_1 & U_1 T_1 S_2 \\ U_3 T_1 S_1 & U_3 T_1 S_2 \end{bmatrix} \\
 &= \begin{bmatrix} U_1 J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_1 & U_1 J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_2 \\ U_3 J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_1 & U_3 J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_2 \end{bmatrix} \\
 &= \begin{bmatrix} U_1 T_1 S_1 & U_1 T_1 S_2 \\ U_3 T_1 S_1 & U_3 T_1 S_2 \end{bmatrix} \\
 &= UTS,
 \end{aligned}$$

and

$$\begin{aligned}
 &XUTSX \\
 &= \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_1^* E^{-1} T_1^{-1} J^{-1} U_3^* \\ S_2^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_2^* E^{-1} T_1^{-1} J^{-1} U_3^* \end{bmatrix} \begin{bmatrix} U_1 T_1 S_1 & U_1 T_1 S_2 \\ U_3 T_1 S_1 & U_3 T_1 S_2 \end{bmatrix} \\
 &\quad \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_1^* E^{-1} T_1^{-1} J^{-1} U_3^* \\ S_2^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_2^* E^{-1} T_1^{-1} J^{-1} U_3^* \end{bmatrix} \\
 &= \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_1^* E^{-1} T_1^{-1} J^{-1} U_3^* \\ S_2^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_2^* E^{-1} T_1^{-1} J^{-1} U_3^* \end{bmatrix} \begin{bmatrix} U_1 J^{-1} U_1^* & U_1 J^{-1} U_3^* \\ U_3 J^{-1} U_1^* & U_3 J^{-1} U_3^* \end{bmatrix} \\
 &= \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) J^{-1} U_1^* & S_1^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) J^{-1} U_3^* \\ S_2^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) J^{-1} U_1^* & S_2^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) J^{-1} U_3^* \end{bmatrix} \\
 &= \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_1^* E^{-1} T_1^{-1} J^{-1} U_3^* \\ S_2^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_2^* E^{-1} T_1^{-1} J^{-1} U_3^* \end{bmatrix} \\
 &= X,
 \end{aligned}$$

also, the operators

$$\begin{aligned}
 XUTS &= \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_1^* E^{-1} T_1^{-1} J^{-1} U_3^* \\ S_2^* E^{-1} T_1^{-1} J^{-1} U_1^* & S_2^* E^{-1} T_1^{-1} J^{-1} U_3^* \end{bmatrix} \begin{bmatrix} U_1 T_1 S_1 & U_1 T_1 S_2 \\ U_3 T_1 S_1 & U_3 T_1 S_2 \end{bmatrix} \\
 &= \begin{bmatrix} S_1^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_1 & S_1^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_2 \\ S_2^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_1 & S_2^* E^{-1} T_1^{-1} J^{-1} (U_1^* U_1 + U_3^* U_3) T_1 S_2 \end{bmatrix} \\
 &= \begin{bmatrix} S_1^* E^{-1} S_1 & S_1^* E^{-1} S_2 \\ S_2^* E^{-1} S_1 & S_2^* E^{-1} S_2 \end{bmatrix}
 \end{aligned}$$

and $UTSX = \begin{bmatrix} U_1 J^{-1} U_1^* & U_1 J^{-1} U_3^* \\ U_3 J^{-1} U_1^* & U_3 J^{-1} U_3^* \end{bmatrix}$ are self adjoint, then uniqueness of the Moore–Penrose inverse implies that, $(UTS)^\dagger = (TS)^\dagger T(UT)^\dagger$.

(ii) By previous statement is obvious.

(iii) We compute

$$\begin{aligned}
 (UTS(TS)^\dagger)^\dagger &= \left(\begin{bmatrix} U_1 T_1 S_1 & U_1 T_1 S_2 \\ U_3 T_1 S_1 & U_3 T_1 S_2 \end{bmatrix} \begin{bmatrix} H_1^* D^{-1} & 0 \\ H_2^* D^{-1} & 0 \end{bmatrix} \right)^\dagger \\
 &= \left(\begin{bmatrix} U_1 T_1 E T_1^* (T_1^*)^{-1} E^{-1} T_1^{-1} & 0 \\ U_3 T_1 E T_1^* (T_1^*)^{-1} E^{-1} T_1^{-1} & 0 \end{bmatrix} \right)^\dagger \\
 &= \left(\begin{bmatrix} U_1 & 0 \\ U_3 & 0 \end{bmatrix} \right)^\dagger \\
 &= \begin{bmatrix} J^{-1} U_1^* & J^{-1} U_3^* \\ 0 & 0 \end{bmatrix}.
 \end{aligned} \tag{4}$$

On the other hand, we obtain

$$\begin{aligned}
 T(UT)^\dagger &= \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} F^{-1}K_1^* & F^{-1}K_2^* \\ 0 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} T_1 T_1^{-1} J^{-1} (T_1^*)^{-1} T_1^* U_1^* & T_1 T_1^{-1} J^{-1} (T_1^*)^{-1} T_1^* U_3^* \\ 0 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} J^{-1} U_1^* & J^{-1} U_3^* \\ 0 & 0 \end{bmatrix}.
 \end{aligned} \tag{5}$$

Hence, equations (4) and (5) imply that $(UTS(TS)^\dagger)^\dagger = T(UT)^\dagger$.

(iv) By applying the equality $\mathcal{R}(T) = \mathcal{R}(TS)$ we obtain $TT^\dagger = TS(TS)^\dagger$. According to the previous statement, it is obvious.

(v) This implication can be proved in the same way as the statement (iii).

(vi) The equality $\mathcal{R}(T^*) = \mathcal{R}((UT)^*)$ implies that $T^\dagger T = (UT)^\dagger UT$. By previous statement is trivial.

(vii) We obtain $(UTS)^\dagger UT(UT)^\dagger = (TS)^\dagger T(UT)^\dagger UT(UT)^\dagger = (TS)^\dagger T(UT)^\dagger = (UTS)^\dagger$ by according to the statement (i).

(viii) Similarly before, it is obvious.

(ix) Since $\mathcal{R}(T^*) = \mathcal{R}(S)$, then S closed range. Also, we have $\mathcal{R}((UT)^*) = \mathcal{R}(T^*)$. Therefore, $\mathcal{R}((UT)^*) = \mathcal{R}(S)$. Now, by [3, Lemma 2.4] matrix forms S, S^\dagger, UT and $(UT)^\dagger$ are $S = \begin{bmatrix} S_1 & S_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(S) \\ \mathcal{N}(S^*) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(S) \\ \mathcal{N}(S^*) \end{bmatrix}$, $S^\dagger = \begin{bmatrix} S_1^* E^{-1} & 0 \\ S_2^* E^{-1} & 0 \end{bmatrix}$, $UT = \begin{bmatrix} K_1 & 0 \\ K_2 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ and $(UT)^\dagger = \begin{bmatrix} F^{-1}K_1^* & F^{-1}K_2^* \\ 0 & 0 \end{bmatrix}$ where $E = S_1 S_1^* + S_2 S_2^*$ and $F = K_1^* K_1 + K_2^* K_2$ are invertible. Let

$$X = S^\dagger (UT)^\dagger = \begin{bmatrix} S_1^* E^{-1} & 0 \\ S_2^* E^{-1} & 0 \end{bmatrix} \begin{bmatrix} F^{-1}K_1^* & F^{-1}K_2^* \\ 0 & 0 \end{bmatrix},$$

then straightforward computations show that X is Moore-Penrose inverse of UTS . \square

THEOREM 5. *Suppose that $T \in \mathcal{L}(\mathcal{X}, \mathcal{Y})$ has closed range and $S \in \mathcal{L}(\mathcal{X})$. If there exist operator $S' \in \mathcal{L}(\mathcal{X})$ such that $T = TSS'$, then*

(i) $T^\dagger TSS^* T^\dagger T$ and $TSS^* T^\dagger$ have closed ranges and

$$(T^\dagger TSS^* T^\dagger T)^\dagger = T^* ((TS)^*)^\dagger (TS)^\dagger T$$

and

$$(TSS^* T^\dagger)^\dagger = TT^* ((TS)^*)^\dagger (TS)^\dagger;$$

(ii) There is an invertible operator $F \in \mathcal{L}(\mathcal{X})$ such that

$$(T^\dagger TSS^* T^\dagger T)^\dagger = F(T^\dagger TSS^* T^\dagger T) = (T^\dagger TSS^* T^\dagger T)F;$$

(iii) $((T^* T)^m SS^* (T^* T)^n)^\dagger = (T^\dagger (T^*)^\dagger)^n T^* ((TS)^*)^\dagger (TS)^\dagger T (T^\dagger (T^*)^\dagger)^m$ ($m, n \in \mathbb{N}$);

(iv) $(1 - TT^\dagger + (TSS^* T^\dagger)^\dagger)^{-1} = 1 - TT^\dagger + TT^* ((TS)^*)^\dagger (TS)^\dagger$;

- (v) If S has a closed range and SS' is self adjoint, then $TSS^*S(S' - S^\dagger)T^* = 0$;
- (vi) If $SS^*T^\dagger T = T^\dagger TSS^*T^\dagger T$, then $S(TS)^\dagger = T^\dagger$;
- (vii) $(T^\dagger TSS^*T^*)^\dagger = (TS(TS)^*)^\dagger T$.

Proof. Since $T = TSS'$, it follows that $\mathcal{R}(T) = \mathcal{R}(TS)$. Using [3, Lemma 2.3], the orthogonal complemented submodules $\mathcal{R}(T^*)$ and $\mathcal{R}(T)$ conclude that matrix decompositions $T = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ and $T^\dagger = \begin{bmatrix} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix}$. Also $S = \begin{bmatrix} S_1 & S_2 \\ S_3 & S_4 \end{bmatrix}, S' = \begin{bmatrix} S'_1 & S'_2 \\ S'_3 & S'_4 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix}$. By [3, Lemma 2.4] matrix form TS is $TS = \begin{bmatrix} H_1 & H_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$ and $(TS)^\dagger = \begin{bmatrix} H_1^* D^{-1} & 0 \\ H_2^* D^{-1} & 0 \end{bmatrix}$, where $D = H_1 H_1^* + H_2 H_2^*$ is invertible. On the other hand, product of matrix forms T and S conclude that $TS = \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} S_1 & S_2 \\ S_3 & S_4 \end{bmatrix} = \begin{bmatrix} T_1 S_1 & T_1 S_2 \\ 0 & 0 \end{bmatrix} : \begin{bmatrix} \mathcal{R}(T^*) \\ \mathcal{N}(T) \end{bmatrix} \rightarrow \begin{bmatrix} \mathcal{R}(T) \\ \mathcal{N}(T^*) \end{bmatrix}$. With comparing these representations matrix of TS ensure that

$$T_1 S_1 = H_1, \quad T_1 S_2 = H_2 \tag{6}$$

and

$$T_1 (S_1 S_1^* + S_2 S_2^*) T_1^* = D. \tag{7}$$

Invertibility of D and T_1 imply that $E = S_1 S_1^* + S_2 S_2^*$ is invertible.

Also,

$$T = TSS' \\ \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} T_1 (S_1 S'_1 + S_2 S'_3) & T_1 (S_1 S'_2 + S_2 S'_4) \\ 0 & 0 \end{bmatrix}.$$

Invertibility of T_1 implies that

$$S_1 S'_1 + S_2 S'_3 = 1, \quad S_1 S'_2 + S_2 S'_4 = 0. \tag{8}$$

(i) By (7) we have $E = T_1^{-1} D (T_1^*)^{-1}$ that is $E^{-1} = T_1^* D^{-1} T_1$. Considering block matrices of these operators conclude that

$$\begin{aligned} (T^\dagger TSS^* T^\dagger T)^\dagger &= \begin{bmatrix} E^{-1} & 0 \\ 0 & 0 \end{bmatrix} = T^* (TSS^* T^*)^\dagger T = T^* (TS(TS)^*)^\dagger T \\ &= T^* ((TS)^*)^\dagger (TS)^\dagger T. \end{aligned}$$

Since $\mathcal{R}(T) = \mathcal{R}(TS)$, then $TT^\dagger = TS(TS)^\dagger$. Hence we have

$$\begin{aligned} (TSS^* T^\dagger)^\dagger &= \begin{bmatrix} (T_1 (S_1 S_1^* + S_2 S_2^*) T_1^{-1})^{-1} & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} T_1 (S_1 S_1^* + S_2 S_2^*)^{-1} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix} \\ &= T (T^\dagger TSS^* T^\dagger T)^\dagger T^\dagger = TT^* ((TS)^*)^\dagger (TS)^\dagger TT^\dagger \\ &= TT^* ((TS)^*)^\dagger (TS)^\dagger. \end{aligned}$$

(ii) From the proof of the previous implication and [3, Theorem 3.6] is straightforward.

(iii) By (7) and matrix forms, we have

$$\begin{aligned} ((T^*T)^m SS^*(T^*T)^n)^\dagger &= \begin{bmatrix} (T_1^*T_1)^m(S_1S_1^* + S_2S_2^*)(T_1^*T_1)^n & 0 \\ 0 & 0 \end{bmatrix}^\dagger \\ &= \begin{bmatrix} ((T_1^*T_1)^m(S_1S_1^* + S_2S_2^*)(T_1^*T_1)^n)^{-1} & 0 \\ 0 & 0 \end{bmatrix} \\ &= (T^\dagger(T^*)^\dagger)^n (T^\dagger TSS^*T^\dagger T)^\dagger (T^\dagger(T^*)^\dagger)^m \\ \text{(By statement (i))} &= (T^\dagger(T^*)^\dagger)^n T^*((TS)^*)^\dagger (TS)^\dagger T (T^\dagger(T^*)^\dagger)^m. \end{aligned}$$

(iv) Matrix operator $1 - TT^\dagger = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$ and equality (7) ensure that $1 - TT^\dagger + (TSS^*T^\dagger)^\dagger = \begin{bmatrix} T_1ET_1^{-1} & 0 \\ 0 & 1 \end{bmatrix}$ is an invertible operator. Statement (i) leads to compute of inverse and its inverse is $1 - TT^\dagger + TT^*((TS)^*)^\dagger (TS)^\dagger$.

(v) Being self adjoint of SS' and equality (8) imply that $SS' = \begin{bmatrix} 1 & 0 \\ 0 & S_3S_2' + S_4S_4' \end{bmatrix}$. Hence matrix operators yield

$$\begin{aligned} TSS^*SS'T^* &= \begin{bmatrix} T_1(S_1S_1^* + S_2S_2^*) & T_1(S_1S_3^* + S_2S_4^*) \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & S_3S_2' + S_4S_4' \end{bmatrix} \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \\ &= TSS^*T^*. \end{aligned}$$

Since S has a closed range, then $TSS^*S(S' - S^\dagger)T^* = 0$.

(vi) Condition $SS^*T^\dagger T = T^\dagger TSS^*T^\dagger T$ leads to

$$\begin{aligned} (1 - T^\dagger T)SS^*T^\dagger T &= \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} S_1S_1^* + S_2S_2^* & S_1S_3^* + S_2S_4^* \\ S_3S_1^* + S_4S_2^* & S_3S_3^* + S_4S_4^* \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ S_3S_1^* + S_4S_2^* & 0 \end{bmatrix} = 0. \end{aligned}$$

On the other hand, (6) implies that $(TS)^\dagger = \begin{bmatrix} S_1^*T_1^*D^{-1} & 0 \\ S_2^*T_1^*D^{-1} & 0 \end{bmatrix}$. Therefore $S(TS)^\dagger = \begin{bmatrix} (S_1S_1^* + S_2S_2^*)T_1^*D^{-1} & 0 \\ (S_3S_1^* + S_4S_2^*)T_1^*D^{-1} & 0 \end{bmatrix}$. Then $S(TS)^\dagger = \begin{bmatrix} ET_1^*D^{-1} & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix}$. That is $S(TS)^\dagger = T^\dagger$.

(vii) A straightforward computation shows that

$$\begin{aligned} T^\dagger TSS^*T^* &= \begin{bmatrix} T_1^{-1} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} T_1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} S_1 & S_2 \\ S_3 & S_4 \end{bmatrix} \begin{bmatrix} S_1^* & S_3^* \\ S_2^* & S_4^* \end{bmatrix} \begin{bmatrix} T_1^* & 0 \\ 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} (S_1S_1^* + S_2S_2^*)T_1^* & 0 \\ 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} ET_1^* & 0 \\ 0 & 0 \end{bmatrix}, \end{aligned}$$

where $(S_1S_1^* + S_2S_2^*)T_1^*$ is invertible. On the other

$$\begin{aligned} (T^\dagger TSS^*T^*)^\dagger &= \begin{bmatrix} (T_1^*)^{-1}E^{-1} & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} (T_1^*)^{-1}(T_1^{-1}D(T_1^*)^{-1})^{-1} & 0 \\ 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} D^{-1}T_1 & 0 \\ 0 & 0 \end{bmatrix} \\ &= (TS(TS)^*)^\dagger T. \end{aligned}$$

Thus $(T^\dagger TSS^*T^*)^\dagger = (TS(TS)^*)^\dagger T$. \square

Acknowledgement. The authors would like to sincerely thank the anonymous referee for carefully reading the paper and for useful comments.

REFERENCES

- [1] D. S. DJORDJEVIĆ, AND N. Č. DINČIĆ, *Reverse order law for the Moore-Penrose inverse*, Journal of Mathematical Analysis and Applications **361** (1) (2010) 252–261.
- [2] M. GOUVEIA, R. PUYSTIENS, *About the group inverse and Moore-Penrose inverse of a product*, Linear Algebra and its Applications **150** (1991) 361–369.
- [3] M. JALAEIAN, M. MOHAMMADZADEH KARIZAKI, M. HASSANI, *Conditions that the product of operators is an EP operator in Hilbert C^* -module*, Linear and Multilinear Algebra **68** (10) (2020) 1990–2004.
- [4] E. C. LANCE, *Hilbert C^* -modules*, A toolkit for operator algebraists, Vol. 210, Cambridge University Press, 1995.
- [5] V. MANUILOV, E. TROITSKY, *Hilbert C^* -modules*, translated from the 2001 russian original by the authors, Translations of Mathematical Monographs 226.
- [6] M. S. MOSLEHIAN, K. SHARIFI, M. FOROUGH, M. CHAKOSHI, *Moore-Penrose inverse of gram operator on Hilbert C^* -modules*, Studia Math. **210** (2012) 189–196.
- [7] P. PATRICIO, *The Moore-Penrose inverse of a factorization*, Linear algebra and its applications **370** (2003) 227–235.
- [8] Q. XU, L. SHENG, *Positive semi-definite matrices of adjointable operators on Hilbert C^* -modules*, Linear Algebra and its Applications **428** (4) (2008) 992–1000.

(Received March 9, 2020)

Maryam Jalaeian
Department of Mathematics
Mashhad Branch, Islamic Azad University
Mashhad, Iran
e-mail: jalaeianmaryam7@gmail.com

Mehdi Mohammadzadeh Karizaki
Department of Computer Engineering
University of Torbat Heydarieh
Torbat Heydarieh, Iran
e-mail: m.mohammadzadeh@torbath.ac.ir

Mahmoud Hassani
Department of Mathematics
Mashhad Branch, Islamic Azad University
Mashhad, Iran
e-mail: mhassanimath@gmail.com